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System Programmer's Guide **AT&T** Personal Computer 6300

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System Programming Concepts

- Purpose of this Manual
- Notation
- Programming Steps

This guide provides you with in-depth information on the AT&T Personal Computer program development tools. The guide focuses on what you need to know to make use of the existing AT&T Personal Computer 6300 hardware and hardware interfaces.

The final chapter on programming devices assumes that you have a working knowledge of the principles of designing device drivers and need the technical details on how to program the AT&T Personal Computer. The following syntax is used throughout this manual in descriptions of command and statement syntax:

- [] Square brackets indicate that the enclosed entry is optional.
- {} Braces indicate a choice between two or more entries. At least one of the entries enclosed in braces must be chosen.
- ... Ellipses indicate that an entry may be repeated as many times as needed.

This guide contains examples of prompts and messages displayed on the screen. These systemdisplayed items are indented from the main body of the text so that you can easily distinguish them. For example, MS-LINK prompts:

OBJECT MODULES[.OBJ]

Descriptions or examples that show a required response are indented and presented in boldface type:

LINK OBJ1+OBJ2+OBJ3,MAP

	This section shows where to go for information on the task you are performing.
Running High-Level Language	If you are running a program via the BASIC interpreter, the section on "System Calls" is applicable, since you can call these functions via a BASIC program.
	If you are running a compiled program, read the section on MS-LINK as well as the section on System Calls.
Writing Assembler Programs	The first eight chapters are aimed at pro- grammers writing assembler programs. If you have not used the 8088 or 8086 assembly lan- guage, the section "8086 Addressing Scheme" gives you a good start. The sections on the linker and debugger are fundamental to writing and debugging assembler programs. Also read the sections on "System Calls" and "ROM BIOS Service Calls."
Writing Utilities	If you are writing a supplementary utility pro- gram, read the sections on assembly programs, the sections on "Memory Maps, Control Blocks, and Diskette Allocation," and "Program File Structure and Loading."
Programming Devices Directly	Every section applies to writing device drivers, especially the chapter on "MS-DOS Device Drivers."

MS-LINK

2

- Overview
- MS-LINK File Usage
- Segments, Groups, and Classes
- Invoking MS-LINK
- Sample MS-LINK Session
- MS-LINK Error Messages

MS-LINK is an executable program on your DOS Supplemental Programs diskette. MS-LINK combines object modules that are the output of the MACRO-86 assembler or a compatible compiler. It produces a relocatable run file (load module) and a list file of external references and error messages.

To run MS-LINK, you provide object, run, list, and library file parameters. You may optionally enter switches that modify the operation of MS-LINK.

"Invoking the Linker" describes the three ways to run MS-LINK: interactive entry, command line entry, and automatic response file entry. Interactive entry is used most frequently, so its section contains information common to all three methods.

If you are linking a high-level language program, the compiler determines the arrangement of your object modules in memory. If you are using assembler, however, you have more control over your program's organization. The section "Segments, Groups, and Classes" shows you how to specify the order of your object modules at run time.

MS-LINK File Usage

The link process involves the use of several files. MS-LINK:

- Works with one or more input files
- Produces two output files
- Creates a temporary disk file if necessary
- Searches up to eight library files

	The format for MS-LINK file specifications is the same as that of any disk file:
Syntax	[d:][path]filename[.ext]
d:	the drive designation. Permissible drive designa- tions for MS-LINK are A: through O:.
path	a path of directory names.
filename	any legal filename of one to eight characters.
ext	a one- to three-character extension to the filename.
	If no filename extensions are given in the input (object) file specifications, MS-LINK recognizes the following extensions by default:
	.OBJ Object .LIB Library
	MS-LINK appends the following default extensions to the output (Run and List) files:
	.EXE Run (may not be overridden) .MAP List (may be overridden)

VM.TMP File MS-LINK uses available memory for the link session. If an output file exceeds available memory, MS-LINK creates a temporary file, names it VM.TMP, and puts it on the disk in the default drive. If MS-LINK creates VM.TMP, it will display the message:

> VM.TMP has been created. Do not change diskette in drive, <d:>

Once this message is displayed, do not remove the diskette from the default drive until the link session ends. If the diskette is removed, the operation of MS-LINK is unpredictable and MS-LINK usually displays the error message:

Unexpected end of file on VM.TMP

MS-LINK writes the contents of VM.TMP to the file named following the Run File: prompt. VM.TMP is a working file only and is deleted at the end of the linking session.

Do not use VM.TMP as a filename for any file. If MS-LINK requires the VM.TMP file, MS-LINK deletes the VM.TMP already on disk and creates a new VM.TMP. Thus, the contents of the previous VM.TMP file are lost.

Changing diskettes You may want to change diskettes during the link operation. If MS-LINK cannot find an object file on the specified diskette, it prompts you to change diskettes rather than aborting the session. If you enter the /PAUSE switch, MS-LINK pauses and prompts you to change diskettes before it creates the run file. You may change diskettes when prompted except in the following cases:

- the diskette you want to change has a VM.TMP file on it.
- you have requested a list file on the diskette you want to change.

Segments, Groups, and Classes

	Below terms are explained to help you under- stand how MS-LINK works. Generally, if you are linking object modules from a high-level language compiler, you do not need to know these terms. If you are linking assembly lan- guage modules, read this section carefully.
Segment	The segment is one of the most basic units of program memory organization. A segment is a contiguous area of memory up to 64K bytes long, and may be located anywhere in RAM. The con- tents of a segment are addressed by a seg- ment:offset address pair, where "segment" is the segment's base or lowest address (see "The 20- Bit Address" in chapter 4).
	Each segment has a class name in addition to its segment name. All segments with the same class name are loaded into memory contiguously by the linker from the first segment of that class to the last.
Class	A class is a collection of related segments. By naming the segments of your assembly lan- guage program to classes, you control the order in which they are loaded into memory (for high level languages, the compiler does this for you).
	MS-LINK loads segments into memory on a class-by-class basis. Starting with the first class encountered in the first object file, all of the segments of each class are loaded. Within each class, the linker loads the segments in the order in which it finds them in the object files. There- fore, you can control the order in which classes are loaded by the order in which segments from different classes appear in the object files.

To ensure that classes are loaded in the order you desire, you can create a dummy module to feed to the linker as the first object file. This module declares empty-segment classes in the order you want the classes loaded. For example, one such file might look like this:

- A SEGMENT 'CODE'
- A ENDS
- **B** SEGMENT 'CONST'
- B ENDS
- C SEGMENT 'DATA'
- C ENDS
- D SEGMENT STACK 'STACK'
- D ENDS

If this method is used, be sure to declare all the classes used in your program in the dummy module; otherwise, you lose absolute control over the ordering of classes. Also, this method should only be used when linking assembly language programs. Do not create a dummy module if linking object files for a compiler, or unpredictable results may occur. Classes may be any length.

Group

Just as classes allow you to combine segments in a way that is logical, groups combine segments in 64K byte chunks to make them easily addressable. The segments in a group need not be contiguous, but when loaded they must fit within 64K bytes. This way each segment in the group can be fully addressed by an offset to one segment address, which is the start address of the lowest segment in the group. Segments are named to groups by the assembler or compiler or, as is possible in assembly language programs, by the programmer. Note that a segment can be large enough to be an entire group by itself.

Invoking MS-LINK

MS-LINK is invoked in one of three ways. The first method, interactive entry, requires you to respond to individual prompts. For the second method, command line entry, type all commands on the same line used to start MS-LINK.		
To use the third method, automatic response file entry, create a response file that contains all the necessary commands and tell MS-LINK where that file is when you run MS-LINK.		
Interactive Entry	LINK	
Command Line Entry	LINK filenames[/switches]	
Automatic Response File Entry	LINK @filespec	
To invoke MS-LINK interactively, type:		
		MS-LINK loads into memory, then displays four prompts, one at a time. At the end of each line, after typing your response to the prompt, you may type one or more switches preceded by a forward slash.
The command prompts are summarized below. Defaults appear in square brackets ([]) after the prompt. Object Modules is the only prompt that requires a response.		
	first method, interactive respond to individual p For the second method type all commands on MS-LINK. To use the third method entry, create a response necessary commands a that file is when you re Interactive Entry Command Line Entry Automatic Response File Entry To invoke MS-LINK in LINK MS-LINK loads into m prompts, one at a time after typing your responding may type one or more forward slash. The command prompt Defaults appear in squiprompt. Object Moduli	

MS-LINK Prompts Ob	Prompt	Responses
	Object Modules[.OBJ]:	[d:][path]filename[.ext] [+[[d:][path]filename[.ext]]]
	Run File[filename.EXT]:	[d:][path][filename[.ext]]
	List File[NUL.MAP]:	[d:][path][filename[.ext]]
	Libraries[.LIB]:	[d:][path][filename[.ext]] [+[d:][[path]filename[.ext]]]

Notes:

- If you enter a filename without specifying the drive, the default drive is assumed. If you enter a filename without specifying the path, the default path is assumed. The libraries prompt is an exception if the linker looks for the libraries on the default drive and doesn't find them, it looks on the drive specified by the compiler.
- To select default responses to all remaining prompts, use a single semicolon (;) followed immediately by <return> at any time after the second prompt (Run File:).

Once you enter the semicolon, you can no longer respond to any of the prompts for that link session. Use the <RETURN> key to skip prompts.

• Use <CONTROL-C> to abort the link session at any time.

Object Modules to be Included	Object Modules [.OBJ]: List .OBJ files to be linked. They must be separ- ated by blank spaces or plus signs (+). If the plus sign is the last character typed, this prompt will reappear so that you can enter more object modules. MS-LINK assumes that object modules have the extension .OBJ unless you explicitly specify some other extension. Object filenames may not begin with the @ symbol (@ is used for specify- ing an automatic response file). The order in which you key in the the object files
	is significant. See section on segments, groups, and classes for more information.
Load Module	Run File [Obj-file.EXE]: Give filename for executable object code. The default is: <first-object-filename>.EXE. (You cannot change the output extension.)You can specify just the drive designation or just a path for this prompt.</first-object-filename>
Listing	List File [NUL.MAP]: Give filename for listing (also known as a linker map). The listing is not created if you select the default. You can request a listing by entering a drive designator, path, or filename[.ext]. If you do not specify an extension, the default .MAP is used.

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You can have the listing printed by specifying a print device instead of a filename or have the listing displayed on the screen by specifying CON. If you display the linker map, you can also print it by pressing Ctrl-PrtSc.
Libraries [.LIB]:
List filenames to be searched separated by blank spaces or plus signs (+). If a plus sign is the last character typed, the prompt will reappear.
MS-LINK searches library files in the order listed to resolve external references. When it finds the module that defines the external sym- bol, MS-LINK processes that module as another object module.
There is no default library search for MACRO assembler object modules. For compiled modules, if you select the default for this prompt, MS-LINK looks for the compiler package's library on the default drive. If not found there, MS-LINK looks on the drive specified by the compiler.
If MS-LINK cannot find a library file, it displays:
Cannot find library <library-name> Type new drive letter:</library-name>
Press the letter for the drive designation (for example, B).
If two libraries have the same filename, only the first in the list is searched.

MS-LINK Switches

The seven MS-LINK switches control various MS-LINK functions. Type switches at the end of a prompt response regardless of which method you use to start MS-LINK. Switches may be grouped at the end of any response, or may be scattered at the end of several. Even if you type more than one switch at the end of one response, each switch must be preceded by a forward slash (/).

All switches may be abbreviated. The only restriction is that an abbreviation must be sequential from the first letter through the last typed; no gaps or transpositions are allowed. For example:

Legal	Illegal
/D /DS /DSA /DSALLOCA	/DSL /DAL /DLC /DSALLOCT

/DSALLOCATE

/DSALLOCATE tells MS-LINK to load all data at the high end of the Data Segment. Otherwise, MS-LINK loads all data at the low end of the Data Segment. At runtime, the DS pointer is set to the lowest possible address to allow the entire DS segment to be used. Use of /DSALLOCATE in combination with the default load low (that is, the /HIGH switch is not used) permits the user application to dynamically allocate any available memory below the area specifically allocated within DGroup yet to remain addressable by the same DS pointer. This dynamic allocation is needed for Pascal and FORTRAN programs.

Your application program may dynamically allocate up to 64K bytes (or the actual amount of memory available) less the amount allocated within DGroup.

/HIGH

/HIGH causes MS-LINK to place the Run file as high as possible in memory. Otherwise, MS-LINK places the Run file as low as possible.

Note:

Do not use /HIGH with Pascal or FORTRAN programs.

/LINENUMBERS

/LINENUMBERS tells MS-LINK to include in the List file the line numbers and addresses of the source statements in the input modules. Otherwise, line numbers are not included in the List file.

Not all compilers produce object modules that contain line number information. In these cases, of course, MS-LINK cannot include line numbers.

/MAP/MAP directs MS-LINK to list all public (global)
symbols defined in the input modules. If /MAP
is not given, MS-LINK will list only errors
(including undefined globals).

The symbols are listed alphabetically. For each symbol, MS-LINK lists its value and its segment:offset location in the Run file. The symbols are listed at the end of the List file.

/PAUSE /PAUSE causes MS-LINK to pause in the link session when the switch is encountered. Normally, MS-LINK performs the linking session from beginning to end without stopping. This switch enables you to swap the diskettes before MS-LINK outputs the Run (.EXE) file. When MS-LINK encounters /PAUSE, it displays the message:

About to generate .EXE file Change disks <hit any key>

MS-LINK resumes processing when you press any key.

Note

Do not remove the disk which will receive the List file, or the disk used for the VM.TMP file, if one has been created.

/STACK: <number>

Stack number represents any positive numeric value (in hexadecimal radix) up to 65536 bytes. If a value from 1 to 511 is typed, MS-LINK will use 512. If /STACK is not used for a link session, MS-LINK calculates the necessary stack size automatically.

All compilers and assemblers should provide information in the object modules that allow the linker to compute the required stack size.

At least one object (input) module must contain a stack allocation statement. If not, MS-LINK will display the following error message:

WARNING: NO STACK STATEMENT

/N0

/NO is short for NODEFAULTLIBRARY-SEARCH. This switch applies only to higher level language modules. This switch tells MS-LINK not to search the default libraries in the object modules. For example, if you are linking object modules in Pascal, specifying /NO tells MS-LINK not to automatically search the library named PASCAL.LIB to resolve external references.

Command Line Entry

Purpose You may invoke MS-LINK by typing all commands on one line. The entries following LINK are responses to the command prompts. The entry fields for the different prompts must be separated by commas. Use the following syntax:

- Syntax LINK <obj-list>,<runfile>,<listfile>, <lib-list>[/switch...]
- **obj-list** a list of object modules, separated by plus signs or spaces.
- runfile name of the file to receive the executable output.
- listfile name of the file to receive the listing.
- **lib-list** list of library modules to be searched, separated by spaces or plus signs.

/switch refers to optional switches which may be placed following any of the response entries (just before any of the commas or after the <lib-list>, as shown).

To select the default for a field, simply type a second comma with no spaces between the two commas.

Example:

LINK FUN+TEXT+TABLE+CARE, FUNLIST, COBLIB.LIB

This command causes MS-LINK to load. Then the object modules FUN.OBJ, TEXT.OBJ, TABLE.OBJ and CARE.OBJ are loaded. MS-LINK links the object modules and writes the output to FUN.EXE (by default), creates a List file named FUNLIST.MAP, and searches the library file COBLIB.LIB.

Automatic Response File Entry

It is often convenient to save responses to the linker for re-use at a later time. This is especially useful when a long list of object modules needs to be specified. The use of an automatic response file allows you to do this.

Before using this option, you must create the response file. Each line of text corresponds to one MS-LINK prompt. The responses must be typed in the same order as they are when entered interactively. To continue a line, type a plus sign (+) at the end of the line.

You can enter the name of more than one automatic response file on the command line and combine response file names with additional parameters. The combined series of resulting parameters must be a valid sequence of MS-LINK prompts.

Use switches and special characters (+ and ;) in the response file the same way they are used when entered interactively. To invoke the linker using a response file, type

LINK @ <filespec>

Filespec is the name of a response file.

When the session begins, MS-LINK displays each prompt with the corresponding response from the response file. If the response file does not contain answers for all the prompts, MS-LINK displays the prompt which does not have a response and waits for a response. When you type a legal response, MS-LINK continues the link session.

Example:

FUN TEXT TABLE CARE /PAUSE /MAP FUNLIST COBLIB.LIB

This response file tells MS-LINK to load the four object modules named FUN.OBJ, TEXT.OBJ, TABLE.OBJ, and CARE.OBJ. MS-LINK pauses before producing a public symbol map to permit you to swap disks. When you press any key, the output files will be named FUN.EXE and FUNLIST.MAP. MS-LINK will search the library file COBLIB.LIB.

Sample MS-LINK Session

This sample shows you the type of information displayed during an MS-LINK session.

In response to the MS-DOS prompt, type:

LINK

The system displays the following messages and prompts:

Microsoft Object Linker V2.01 (Large) (C) Copyright 1982,1983 by Microsoft Inc.

Object Modules [.OBJ]: IO SYSINIT Run File [IO.EXE]: List File [NUL.MAP]: PRN /MAP /LINE Libraries [.LIB]: ;

Notes:

- By specifying /MAP, you get both an alphabetic listing and a chronological listing of public symbols.
- By responding PRN to the List File: prompt, you can redirect your output to the printer.
- By specifying the /LINE switch, MS-LINK gives you a listing of all line numbers for all modules. (Note that /LINE can generate a large volume of output.)

Once MS-LINK locates all libraries, the linker map displays a list of segments in the order of their appearance within the load module. The list might look like this:

Start	Stop	Length	Name
00000H	009ECH	09EDH	CODE
009F0H -	01166H	0777H	SYSINITSEG

The information in the Start and Stop columns shows the 20-bit hex address of each segment relative to location zero. Location zero is the beginning of the load module.

The addresses displayed are not the absolute addresses where these segments are loaded. See the following section on the MS-LINK DEBUG program for information on how to determine the absolute address of a segment. Because the /MAP switch was used, MS-LINK displays the public symbols by name and value. For example:

ADDRESS	PUBLICS BY NAME
009F:0012	BUFFERS
009F:0005	CURRENT DOS LOCATION
009F:0011	DEFAULT DRIVE
009F:000B	DEVICE LIST
009F:0013	FILES
009F:0009	FINAL DOS LOCATION
009F:000F	MEMORY SIZE
009F:000F	SYSINIT
ADDRESS	PUBLICS BY VALUE
009F:0000	SYSINIT
009F:0005	CURRENT DOS LOCATION
009F:0009	FINAL DOS LOCATION
009F:000B	DEVICE LIST
009F:000F	MEMORY SIZE
009F:0011	DEFAULT DRIVE
009F:0012	BUFFERS
009F:0013	FILES

The final line in the listing file describes the program's entry point:

Program entry point at 0009F:0000

MS-LINK Error Messages

All errors, except for the two warning messages, cause the link session to abort. After the cause has been found and corrected, MS-LINK must be rerun. The following error messages are displayed by MS-LINK:

Attempt to access data outside of segment bounds, possibly bad object module

There is probably a bad object file.

Bad numeric parameter

Numeric value is not in digits.

Cannot open temporary file

MS-LINK is unable to create the file VM.TMP because the disk directory is full. Insert a new disk. Do not remove the disk that will receive the List. MAP file.

Error: dup record too complex

DUP record in assembly language module is too complex. Simplify DUP record in assembly language program.

Error: fixup offset exceeds field width

An assembly language instruction references an address with a short or near instruction instead of a long or far instruction. Edit assembly language source and reassemble.

Input file read error

There is probably a bad object file.

Invalid object module

An object module(s) is incorrectly formed or incomplete (as when assembly is stopped in the middle).

Symbol defined more than once

MS-LINK found two or more modules that define a single symbol name.

Program size or number of segments exceeds capacity of linker

The total size may not exceed 384K bytes and the number of segments may not exceed 255.

Requested stack size exceeds 64K

Specify a size less than or equal to 64K bytes with the /STACK switch.

Segment size exceeds 64K

64K bytes is the addressing system limit.

Symbol table capacity exceeded

Very many and/or very long names were typed exceeding the limit of approximately 50K bytes.

Too many external symbols in one module

The limit is 256 external symbols per module.

Too many groups

The limit is ten groups.

Too many libraries specified

The limit is 8 libraries.

Too many public symbols

The limit is 1024 public symbols.

Too many segments or classes

The limit is 256 (segments and classes together must total 256 or less).

Unresolved externals: <list>

The external symbols listed have no defining module among the modules or library files specified.

VM read error

This is a disk error; it is not caused by MS-LINK.

Warning: no stack segment

None of the object modules specified contains a statement allocating stack space.

Warning: segment of absolute or unknown type

There is a bad object module or an attempt has been made to link modules that MS-LINK cannot handle (e.g., an absolute object module).

Write error in TMP file

No more disk space remains to expand the VM.TMP file.

Write error on run file

Usually, this means there is not enough disk space for the Run file.

DEBUG

3

- Overview
- How to Invoke DEBUG
- Debugging Commands
- Command Parameters
 - A Assemble
 - C Compare
 - D Display
 - **E** Enter
 - F Fill
 - G Go
 - **H** Hexarithmetic
 - I Input
 - L Load
 - M Move
 - N Name
 - **O** Output
 - Q Quit
 - **R** Register
 - S Search
 - **T** Trace
 - U Unassemble
 - W Write
- DEBUG Error Messages

The DEBUG utility is an executable object program that resides on your MS-DOS diskette. DEBUG performs the following functions:

- Allows you to single step through a program, instruction by instruction, for testing purposes.
- Changes register and file contents during the DEBUG session so that you can test a code change without reassembling your program.
- Makes permanent changes to diskette files so you can use DEBUG to recover files that may otherwise be lost.
- Supports a disassemble command so you can translate machine code instructions into their assembly language equivalents for testing purposes.

How to Invoke DEBUG

	The DEBUG program is invoked as follows:
	DEBUG [filespec [,arglist]]
filespec	the name of the program file to be debugged.
arglist	An optional list of file name parameters and switches. These will be passed to the program specified by the filespec parameter. When the program is loaded into memory, it is loaded as if it had been invoked with the command
	filespec arglist
	That is, filespec indicates the file to be debugged, and arglist is the rest of the command line that is used when the file is invoked and loaded in memory via COMMAND.COM.
	If you enter DEBUG without parameters, since no file name has been specified, current memory, disk blocks, or disk files can be manipulated.

DEBUG

On entering the DEBUG environment DEBUG Comments responds with the hyphen (-) prompt and underline (_) cursor. You now may enter any DEBUG command. If you include the filespec in the command line, the specified file is loaded into memory starting at location 100 (hexadecimal). However, if you specify a file with a .EXE extension, the program is relocated to the address specified in the header of the file. See the chapter on "Program Structure and Loading" for information on the format of the file header. If the file has the HEX extension, the file is loaded beginning at the address specified in the HEX file. HEX files are in INTEL hex format and are converted to memory image format by DEBUG. All DEBUG commands may be aborted at any time by pressing <CTRL-C>. Pressing <CTRL-S> suspends the display, so that you can read it before the output scrolls away. After suspending the display, press any key (except <CTRL-S> or <CTRL-C>) to continue scrolling. Examples DEBUG <CR>. The DEBUG session begins, but without loading a file. DEBUG b:myprog <CR>.

The DEBUG environment is entered and the file named "myprog" is loaded into memory from drive B. When you invoke DEBUG, it sets up a program segment prefix at offset 0 in the program work area. You can overwrite this area if you enter DEBUG without parameters. Moreover, if you are debugging a file with a COM or EXE extension, do not tamper with the program header below location 5CH, or DEBUG will terminate.

Do not restart a program after a "Program terminated normally" message is displayed. You must reload the program with the N and L commands for it to run properly. This section describes the DEBUG commands in alphabetical order for ease of reference.

- Commands can be entered in either upper or lower case.
- Command keywords and command parameters can be separated from each other by spaces or commas for readability but need not be, except where two hexadecimal numbers are entered as parameters, in which case they must be separated by a comma or space. For brevity, the syntax of this chapter will always indicate a comma where separation is obligatory, but note that a space can alternatively be used.
- Commands only become effective after entering <CR>.
- If you make a syntax error when entering a command, the message "Error" will be displayed. You must re-enter the command using the correct syntax.

Command Parameters

The following DEBUG command parameters require definition.

address a hex value in one of the following formats:

• a segment register designation and a hex offset separated from each other by a colon. For example:

DS:0300

• a hexadecimal segment and offset separated from each other by a colon. For example:

9D0:0100

• a hexadecimal offset value. The DEBUG command will use a default segment value from either the DS or CS registers, depending on the command. For example:

200

- byte a one or two character hexadecimal value.
- **drive** 0, 1, or 2 depending on whether you wish to select drive A, drive B or drive C, respectively.

range	a range of addresses. The range can be specified as
	address L value
	where address specifies the start of the range and value specifies the length of the range. For example:
	DS:300L30
	indicates a range of 48 locations starting at address 300 in the segment indicated by the DS register.
	The specified range cannot be greater than 10000 (hexadecimal). To specify this value enter 0000 (or 0) as the value parameter.
	A range can also be specified as:
	address, address
	where the two addresses indicate the limits of the range. A space may be used instead of a comma.
value	a 1 to 4 character hexadecimal value.

A (ASSEMBLE)

Assembles 8086 mnemonics directly into memory.

Syntax A [address]

Address is the start address into which the subsequently entered line of mnemonics is to be assembled. If this parameter is omitted, offset 100 from the segment in the CS register is assumed, if you did not enter an Assemble command previously. If you did enter Assemble previously, the code assembles into the address following the last instruction loaded by the previous Assemble command.

- **Comments** After you enter the Assemble command, DEBUG displays the specified address followed by the cursor. You may then enter a line of 8086 assembler mnemonics. On terminating the line with <CR>, the line will be assembled into memory starting at the specified location. The address of the byte subsequent to the assembled code will be displayed on the next line along with the cursor to enable you to enter the next line of code. If, instead of a line of 8086 mnemonics, you simply enter <CR>, the Assemble command terminates and the DEBUG prompt reappears.
 - All numeric values are hexadecimal and must be entered as 1 to 4 characters without a trailing H. Prefix mnemonics must be specified in front of the opcode to which they refer. You may also enter them on a separate line.
 - The segment override mnemonics are CS:, DS:, ES: and SS:. The mnemonic for the far return is RETF. String manipulation mnemonics must explicitly state the string size. For example, use MOVSB to move byte strings.

• The Assemble command will automatically assemble short, near, or far jumps and calls, depending on byte displacement with respect to the destination address. These may be overridden with the NEAR or FAR prefix. For example:

0100:0500 JMP 502	;a two-byte
0100:0502 JMP NEAR 505	;short jump ;a three-byte
0100:505 JMP FAR 50A	;near jump
0100:505 JMF I AR 50A	;a five-byte far ;jump

The NEAR prefix may be abbreviated to NE, but the FAR prefix cannot be abbreviated.

• DEBUG cannot tell whether some operands refer to a word memory location or to a byte memory location. In this case the data type must be explicitly stated with the prefix "WORD PTR" or "BYTE PTR". Acceptable abbreviations are "WO" and "BY". For example:

NEG	BYTE PTR [128]
DEC	WO [SI]

• DEBUG cannot distinguish whether an operand refers to a memory location or to an immediate operand. Enclose operands that refer to memory locations in square brackets. For example:

MOV AX,21	;Load AX with 21H
MOV AX,[21]	;Load AX with the contents of
	;location 21H

• Two pseudo-instructions are available with the Assemble command. The DB opcode will assemble byte values directly into memory. The DW opcode assembles word values into memory. For example:

DB 1,2,3,4, "THIS IS AN EXAMPLE" DB "THIS IS A QUOTE:" ' DB "THIS IS A QUOTE'" DW 1000,2000,3000, "BACH"

• The Assemble command supports all forms of register indirect addressing. For example:

ADD BX,34[BP+2]. [SI-1] POP [BP+DI] PUSH [SI]

All opcode synonyms are supported. For example:

LOOPZ	100
LOOPE	100
JA	200
JNBE	200

Example 1 Enter A200 <CR>.

- 2 DEBUG displays 09AC:0200_.
- **3** Enter MOV AX,[21] <CR>.
- 4 The 8086 mnemonics are assembled starting at location 200. The byte location subsequent to the assembled code is then displayed:

09AC:0203_

- 5 Enter < CR >.
- 6 The Assemble command terminates and the DEBUG prompt reappears.

C (COMPARE)

Compares the contents of two areas of memory.

Syntax C range, address

range the range of addresses defining the first area to be compared. If no segment is specified, then the segment specified in the DS register is assumed.

address the start of the area to be compared with the area specified by the range parameter.

- **Comments** The Compare command compares the area of memory specified by the range parameter with an area of the same size starting at the location specified by the address parameter.
 - If the contents of the two areas are identical, nothing is displayed. If there are differences, then the differences are displayed in the form

<address1><contents1><contents2><address2>

<address1> indicates the address in the first area and <contents1> its contents. <address2> indicates the corresponding address in the second area and <contents2> its contents.

Example 1 Enter C100,1FF,300 <CR> or

C100L100, 300 <CR>.

2 The area of memory from 100 to 1FF is compared with the area of memory from 300 to 3FF.

D (DISPLAY)

Displays an area of memory.

Syntax D [range] or D [address]

range the range of addresses whose contents are to be displayed. If you enter only offsets, then the segment specified in the DS register is assumed.

address the address from which the display is to start. The contents of this address and the subsequent 127 locations are displayed. If only an offset is entered, then the segment specified in the DS register is assumed.

- **Comments** If D is specified without parameters, then the 128 bytes following the last address to be displayed are displayed. If no location has yet been accessed, the display will start from location DS:100.
 - If D and the range parameter are specified, the contents of that range of addresses are displayed. If this takes more than 24 screen lines, the display is scrolled until the contents of the final address in the range are displayed on line 24.
 - The display is displayed in two portions:

A hexadecimal display, where each byte is represented by its hexadecimal value, and an ASCII display, where the equivalent ASCII character for the byte is displayed. If there is no corresponding printable ASCII character, a period (.) is displayed. • Each line of the display begins with an address followed by the hexadecimal contents of the 16 bytes starting from the addressed location. The eighth and ninth bytes are separated by a hyphen (-). The right-hand columns display the equivalent ASCII values. Each line of the display, except possibly the first, begins on a 16 byte boundary.

Example 1 Enter D 100,110 < CR>.

- 2 Lines 100H to 110H (inclusive) are displayed.
- **3** Enter D < CR >.
- 4 The 128 bytes starting from location 111H are displayed.
- 5 Enter D200 < CR>.
- 6 The 128 bytes starting from location 200H are displayed.

E (ENTER)

	Replaces the contents of memory locations at the byte address(es) specified.
Syntax	E address[,bytevalue[,bytevalue]]
address	the address of the location whose value is to be replaced; or the address of the first of a succes- sion of locations whose contents are to be replaced. If only an offset is specified, then the segment indicated by the DS register is assumed.
bytevalue	the value that is to replace the contents of the specified address. The first bytevalue parameter will replace the contents of the location specified by the address parameter. A second bytevalue will replace the contents of the location follow- ing that specified by the address parameter, and so on.
Comments •	If the command is entered without the byte value list, then DEBUG displays the specified address and its contents. The Enter command then waits for you to perform one of the following:
1	Replace the displayed bytevalue by entering another value. Enter the new value after the cur- rent value. If you enter an illegal value, or if you type more than two digits, 's, the illegal or extra character is not echoed.
2	Advance to the next byte by pressing <space>. To change the value of this byte simply enter the value as described above. If you</space>

advance beyond an eight-byte boundary, DEBUG starts a new display line with the address displayed at the start of the line. To advance to the next byte without changing the current byte, press <SPACE> again.

- **3** To return to the previous byte enter hyphen (-). DEBUG then starts a new display line with the address of the byte you have returned to and its contents. You can then change the contents of this location as described above. To move back one byte further without changing this value, enter hyphen again, and another new display line will be generated.
- 4 Terminate the Enter command by pressing <CR>. This key may be pressed in any byte position.
- If you specify byte values in the command line, then the first of these byte values will replace the contents of the location specified by the address parameter. Subsequent entries in the list of byte values will replace subsequent bytes in memory.
- Example 1 Enter E100 < CR>.
 - 2 DEBUG displays something like 058D:0100 CD._
 - **3** Enter 26.
 - 4 the value of location 100 is changed to 26 and DEBUG displays:

058D:0100 CD.26_

- 5 Enter < SPACE>.
- 6 The next byte (location 101) is displayed 058D:0100 CD.26 20._
- 7 Enter <SPACE>.
- 8 The next byte (location 102) is displayed

058D:100 CD.26 20. 00._

- **9** Enter <->.
- 10 The previous byte (location 101) is displayed on the next line

058D:0100 CD.26 20. 00. 058D:0101 20._

- 11 Enter 30 <CR>.
- **12** The contents of location 101 are changed to 30 and the Enter command is terminated.

```
058D:0100 CD.26. 20. 00.
058D:0101 20.30
```

- 13 Enter E 200,26,0A, 19,23 <CR>.
- 14 The contents of byte locations 200, 201, 202 and 203 are changed to 26, 0A, 19 and 23, respectively.

F (FILL)

	Fills an area of memory with specified byte values.
Syntax	F range,bytevalue[,bytevalue]
range	the range of addresses whose contents are to be overwritten with the specified bytevalues. If only the offset is specified, then the segment indi- cated by the DS register is assumed.
bytevalue	a two digit hexadecimal value that is to over- write the contents of the specified address(es).
Comments •	If the specified range contains more bytes than the list of byte values, then the list of byte values is repeated until the specified range is filled.
•	If the list of byte values is longer than the speci- fied range, the extra byte values are ignored.
Example 1	Enter F04BA:100L100,42,45,48,37,20 <cr>.</cr>
2	DEBUG fills memory locations 04BA :100 to 04BA :1 FF with the byte values specified. The five values are repeated until all 256 locations are filled.

G (**GO**)

	Executes the program currently in memory, optionally halting at specified breakpoint(s) and displaying information about the system and program environment.
Syntax	G [=address][,address]
=address	the address in memory at which program execu- tion is to start. "=" must be entered to distin- guish a start address from a breakpoint address.
address	the breakpoint address. You can specify up to ten breakpoints, in any order.
Comments	If you enter G without parameters, the program currently in memory is executed starting from the address specified by the CS and IP registers.
	If you specify the =address parameter, the con- tents of the CS and IP registers are changed to those specified by the =address parameter and the program in memory is executed, starting from the address you specified.
	If you specify one or more breakpoint addresses, program execution stops at the first such address encountered and displays the contents of the registers, the state of the flags and the next instruction to be executed (see the Register command for a description of the display).
•	If only an offset is entered for an address, the GO command assumes the segment in the CS register.

• If you enter more than ten breakpoints, DEBUG will display

BP Error

• Before executing the program, the GO command replaces the contents of the breakpoint locations with an interrupt instruction (hexadecimal CC). Therefore, each breakpoint address that you specify must point to the first byte of an 8086 instruction, or unpredictable results occur.

When program execution halts at a breakpoint DEBUG restores the original values of all the specified breakpoint locations. However, if the program terminates normally (that is, not at a specified breakpoint), the original values are not restored.

Note: Once a program has reached completion (DEBUG has displayed "Program terminated normally") you must reload the program before you can re-execute it.

The stack segment must have six bytes available at the stack pointer for this command, otherwise unpredictable results occur. This is because the GO command jumps into the user program with the IRET instruction. The flag, CS, and IP registers have to be pushed onto the stack in preparation for the IRET, taking up six bytes.

Example 1 Enter G=200, 1AF, 141 < CR >.

- 2 The program currently in memory is executed starting from location 200. Assuming location 141 is encountered before 1AF, then the program halts at location 141 and the register and flag values are displayed along with the next instruction to be executed. If neither breakpoint location is encountered, then the program terminates normally.
- 3 Enter G < CR>.
- **4** If, in step two, the program had halted at location 141, then program execution continues from that address.

H (HEXARITHMETIC)

1

	Calculates and displays the sum and the differ- ence of two hexadecimal values.
Syntax	H value_a,value_b
value_a	The first of two hexadecimal values.
value_b	The hexadecimal value that is to be added to or subtracted from value_a.
Comments	The hexadecimal values may be up to four digits long.
	The Hex command displays two four-digit values:
	 the first is the result of adding value_b to value_a
	 the second is the result of subtracting value_b from value_a
Example 1	Enter H19F,10A <cr>.</cr>
2	DEBUG displays
	02A9 0095
3	Enter HFFFF,2 <cr>.</cr>
4	DEBUG displays
	0001 FFFD

I (INPUT)

	Inputs and displays (in hexadecimal) one byte from the specified port.
Syntax	I value
value	the address of the port that the byte is to be input from.
Comments	The port address can be up to 16 bits.
Example 1	Enter I2F8.
2	the byte at the addressed port is input and displayed.

L (LOAD)

	Loads a file or absolute disk blocks into memory.
Syntax	L [address[,drive,block,count]]
address	the address in memory at which the file or range of blocks is to be loaded. If only an offset is entered, then the segment indicated by the CS register is assumed.
drive	the drive from which disk blocks are to be loaded. For drive A you must enter 0, for drive B you must enter 1, etc.
block	the first of a range of blocks to be loaded from the disk specified by the drive parameter.
count	the number of blocks to be loaded.
Comments •	If all parameters are specified, then DEBUG loads blocks of information from disk into memory.
•	If you enter L without parameters, or with just the address parameter, the file whose file control block is correctly formatted at location CS:5C is loaded into memory. The file control block at CS:5C is set either to the filespec specified when the DEBUG command was invoked, or to the filespec specified by the most recent "Name" command.
•	The default location for programs to load is at CS:100. If you specify L and the address parameter, the file is loaded at the specified

address unless it is a .EXE or .HEX file. In any case DEBUG sets the BX:CX registers to the number of bytes loaded.

- If the file has an EXE extension, then it is relocated to the load address specified in the header of the .EXE file. That is, the address parameter to the Load command is ignored. The header itself is stripped off the .EXE file before the file is loaded into memory. Thus the size of the .EXE file on disk will differ from its size in memory.
- If the file is a .HEX file, entering the Load command with no parameters causes the file to be loaded starting at the address specified within the .HEX file. If the address parameter, however, is specified, then loading starts at the address which is the sum of the address specified and the address in the .HEX file.
- **Examples** The following examples assume the system to be initially in MS-DOS.
 - 1 Enter debug <CR> Nb:file.com <CR> L <CR>.

Debug is entered and the subsequent Name command sets the file control block at CS:5C to identify file "file.com" on the diskette inserted in drive B. The Load command then loads this file into memory starting at CS:100 (the default address).

2 Enter debug b:file.com <CR> L300 <CR>.

> file.com is loaded into memory at location CS:100 by the DEBUG command. It is then relocated to CS:300 by the Load command.

M (MOVE)

		Moves the contents of a specified range of memory addresses to the locations starting at a specified address.
Syntax		M range,address
range		The area of memory whose contents are to be moved. If you only enter an offset, the segment indicated in the DS register is assumed.
address		The start of the destination area. If you only enter an offset, then the segment indicated by the DS register is assumed.
Comments		If the source and destination areas overlap, the move is performed without loss of data.
		The contents of the source area are not changed by the move, unless the destination area over- laps it.
		If you specify an address as the end of the range, you must only enter the offset. The seg- ment specified, or defaulted to, in the start address of the range is assumed.
Example	1	Enter MCS:100,110,CS:500 <cr> or MCS:100L11,CS:500 <cr>.</cr></cr>
	2	The 17 bytes starting at location CS:100 are copied to the 17 bytes starting at location CS:500.

N (NAME)

Provides file names for the Load and Write commands or file name parameters for the program to be debugged.

Syntax N filespec[,filespec...]

filespec the file specifier of a file to be loaded into memory, written to diskette, or used as a file name parameter to the file currently in memory.

Comments The Name command can be used to provide:

the name of the disk file to be loaded into memory by a subsequent Load command

the name to be assigned to the file currently in memory when the file is subsequently written to disk

file name parameters to the file in memory to be debugged.

The first case enables you to specify the file you wish to debug after entering the DEBUG environment. That is, you can enter DEBUG without specifying parameters, then use the Name command to name the disk file you wish to debug, then load the file into memory using the Load command. This has the same effect as entering the file name as the first parameter to the DEBUG command upon invocation. In either case the file control block for the file to be debugged is set up at location CS:5C and the file is loaded. In the second case, the file is already in memory and the Name command sets up the file control block for the specified file name at location CS:5C. When a Write command is subsequently entered the file in memory is written to disk with the file name whose file control block is set up at location CS:5C.

In the third case, the Name command provides file name parameters for the program currently in memory. Whatever file control block was set at CS:5C is replaced by that of the first such parameter. If a second file parameter is specified, its file control block is set up at location CS:6C. Only two file control blocks are set up, although additional file name parameters may be included if required. All the specified including any delimiters and switches that may have been typed — are placed in a save area at CS:81, with CS:80 containing a character count. Parameters specified in this way are analogous to file names specified in the argument list to the DEBUG command.

Examples 1

Enter DEBUG <CR> Nb:file.com <CR> L <CR>.

The system enters the DEBUG environment and FILE.COM resident on drive B has its file control block set up at location CS:5C. The Load command subsequently loads this file into memory.

This sequence has the same effect as entering

"DEBUG b:file.com"

$\begin{array}{cc} 2 & \text{Enter Nb:newfile.com} <\!\! \text{CR}\!\! > \\ & \mathbb{W} <\!\! \text{CR}\!\! > \end{array}$

The file control block is set up at location CS:5C for the file specifier "b:newfile.com". The subsequent Write command writes the file currently in memory to drive B and names the file "newfile.com".

3 Enter DEBUG b:file 1.com <CR> Nfile2.dat,file3.dat <CR> G <CR>

The DEBUG command loads the file named "file1. com" from drive B to be debugged. The Name command sets up two file control blocks at locations CS:5C and CS:6C for the file specifiers b:file2.dat and b:file3.dat, respectively. These files then become parameters to file1.COM when the subsequent GO command executes file1-.COM. Therefore, the file is executed as if the following command line had been typed:

b:file1 file2.dat file3.dat

O (OUTPUT)

i.

Sends a specified byte to an output port.

Syntax		O value,byte
value		the address of the output port. It must be speci- fied in hexadecimal and can be up to 16 bits.
byte		a two-digit hexadecimal value to be sent to the specified port.
Example	1	01 E , 27 < C R>
	2	the byte value 27H is output to the port 1EH.

Q (QUIT)

Terminates the DEBUG program.

SyntaxQCommentsThe Quit command terminates the debugger
without saving the file you are working on. Con-
trol is returned to MS-DOS command mode.

DEBUG

R (REGISTER)

	Displays the contents of the registers and flag settings, or displays the contents of a specified register with the option to change that value, or displays the flag settings with the option of reversing any number of those settings.
Syntax	R [register-name pipe: F]
register- name	any valid register name whose contents are to be examined and optionally changed. This may be one of:
	AX DX SI ES IP BX SP DI SS PC CX BP DS CS
	Note: IP and PC both refer to the Instruction Pointer.
F	the flag settings are to be displayed and option- ally changed.
Comments	If you enter R without parameters, then the con- tents of all registers are displayed along with the flag settings and the next instruction to be exe- cuted. For Example:
	AX=058D BX=0000 CS=0000 DX=0000 SP=FFF0 BP=0000 SI=0000 DI=0000 DS=058D ES=058D CS=058D IP=013B NV UP EI PL NZ NA PO NC 058D:013B 83D8 MOV DS,AX
	If you enter R with a register name, then DEBUG displays the contents of that register. The command then waits for you to do one of the following:

- press <CR> to terminate the Register command without changing the value of the displayed register.
- change the value of the register by entering the four-digit hexadecimal value, then terminate the Register command by entering <CR>.

The valid flag values are shown in the following table:

Flag Name	Set	Clear
Overflow	OV (yes)	NV (no)
Direction	DN (decrement)	UP (increment)
Interrupt Sign	EI (enabled) NG (negative)	DI (disabled) PL (plus)
Zero	ZR (yes)	NZ (no)
Auxiliary	AC (yes)	NA (no)
Carry		
Parity	PE (even)	PO (odd)
Carry	CY (yes)	NC (no)

If you enter RF, then the current flag settings are displayed. You can then either

- press <CR> to terminate the Register command without changing the flag values, or
- change the setting of one or more flags by entering the alternate value of the appropriate flags. The new values may be entered in any order, with or without delimiters.

Example 1 Enter R < CR >.

- **2** DEBUG displays the contents of all registers, flag settings and the next instruction to be executed.
- **3** Enter RIP < CR>.
- **4** DEBUG displays the contents of the Instruction Pointer. For example:

IP 0139

:---

- **5** Enter 0138 < CR>.
- 6 the contents of the Instruction Pointer are changed to 0138.
- **7** Enter RF < CR >.
- 8 DEBUG displays the flag settings. For example:

NV UP EI PL NZ NA PO NC -

- 9 Enter PE ZR DI NG < CR>.
- 10 The Parity flag is set to even (PE), the Zero flag is set (ZR), the Interrupt flag is cleared (DI), and the Sign flag is set (NG).
- **11** Enter $\mathbf{RF} < \mathbf{CR} >$.
- **12** DEBUG displays the new state of the flags

NV UP DI NG ZR NA PE NC-

S (SEARCH)

Searches a specified range for a list of bytes.

Syntax	S range,list
range	the range of addresses within which the search is to be made. If you only enter the offset, the segment indicated by the DS register is assumed.
list	the list of one or more bytes to be searched for. Bytes in the list must be separated by a space or a comma.
Comments	For each occurrence of the list of bytes within the specified range, DEBUG returns the address of the first byte. If no address is returned, no match was found.
Example 1	Enter S100L100,20 <cr> or S100,1FF,20 <cr>.</cr></cr>
2	DEBUG displays the address of every occur- rence of byte value 20 in the address range 100 to 1FF, inclusive, for example:
•	058D: 010C 058D: 0110 058D: 0115 058D: 0118 058D: 0120 058D: 0128 058D: 01CE

T (TRACE)

		Executes one or more instructions and displays the register contents, flag settings and the next instruction to be executed.
Syntax		T [=address][,value]
= address		DEBUG is to commence execution at this address.
value		the number of instructions to be executed.
Comments		If the =address parameter is not specified, execu- tion begins at CS:IP.
		If the value parameter is not specified, only one instruction is executed.
		The display generated is of the same format as that of the Register command (without parameters).
Example	1	Enter T = 200,5 < CR >.
	2	Five instructions, starting with the one at loca- tion CS:200, are executed, and the register and flag values following each instruction are displayed along with the next instruction to be executed.
	3	Enter T < CR >.
	4	The instruction pointed to by CS:IP is executed and the register and flag contents are displayed along with the next instruction to be executed.

U (UNASSEMBLE)

	Disassembles strings of bytes in memory and displays them as assembler-like statements along with their corresponding addresses.
Syntax	U [range] or U [address]
range	the range of addresses whose byte values are to be disassembled. If you do not specify the seg- ment, then the segment indicated by the CS reg- ister is assumed.
address	the start of a 32 byte area of memory to be dis- assembled. If you only enter an offset, then the segment indicated by the CS register is assumed.
Comments •	If neither the range nor address parameter is specified, then 32 bytes are disassembled start- ing at location CS:IP. If the Unassemble command is given more than once, each subsequent invocation starts at the address following the last disassembled location.
•	The number of bytes disassembled may be slightly more than the number you specified. This is because instructions are not always the same length and the final address in a range will not always contain the last byte of an instruction.
•	The first address of a range, or the address parameter, must always refer to the first byte of an 8086 instruction, otherwise results are unpredictable.

Example

- $1 \quad \text{Enter U058D:204L8} < \text{CR} >.$
- 2 Eight bytes starting at location 058D:204 are disassembled and the result displayed:

058D:0204	8D16DFOD	LEA	DX,[ODDF]
058D:0208	42	INC	DX
058D:0209	03DO	ADD	DX,AX
058D:020B	8916E50B	MOV	[OBE5],DX

W (WRITE)

	Writes the file being debugged to disk.	
Syntax	W [address[,drive,block,count]	
address	the start address of the code in memory that is to be written to disk. If you enter only an offset, then the segment indicated in the CS register is assumed.	
drive	the drive containing the specified blocks to which code in memory is to be written. For drive A you must enter 0, for drive B you must enter 1, etc.	
block	the block number on disk that is the first of a contiguous range of blocks to be overwritten with code from memory.	
count	the number of disk blocks to be overwritten with code from memory.	
Comments •	If you enter the WRITE command without parameters, then the file is written to disk start- ing from memory address CS:100. If you specify the address parameter, then the file in memory, starting from the specified address, is written to disk.	
•	In either case, before executing the WRITE command, BX:CX must be set to the number of bytes to be written if the count parameter is not included. This value was set up correctly when the file was loaded (either by the Load command or the DEBUG command itself). However, if, since loading the file, you have executed a GO or	

TRACE command, then the value of BX:CX will have been changed. Be sure this value is set up correctly.

- When the WRITE command writes a file to disk, it obtains the drive specifier and file name via the file control block set up at CS:5C. If no drive specifier is set up, then the default is assumed. This file control block is set up either by the DEBUG command (for the file you specify as a parameter to DEBUG) or by a subsequent NAME command. If it does not indicate the file specifier you require, you must set up this file control block using the NAME command. Refer to "Memory Maps, Control Blocks, and Diskette Allocation" for further details.
- When the file is written to disk it overwrites the version currently on disk unless the specified file name does not exist, in which case a new file is created.
- If all parameters are specified, then the code in memory is written to the drive specified by the parameter. The data to be written starts at the memory location specified by the address parameter, and is written to the blocks on the disk specified by the block and count parameters. Be extremely careful to correctly specify the blocks, since information stored there previously will be destroyed by this operation.

Examples 1 Enter W < CR >.

The file in memory, starting from location CS:100, is written to disk with the file specifier defined by the file control block set up at location CS:5C. The number of bytes written is given by BX:CX.

2 Enter W200 < CR>.

The file in memory, starting from location CS:200, is written to disk with the file specifier defined by the file control block set up at location CS:5C. The number of bytes written is given by BX:CX.

3 Enter W200,1,1F,20 <CR>.

Blocks 1F through 3F on drive B are overwritten with the data starting at memory location CS:200.

DEBUG ERROR MESSAGES

BF	Bad Flag You attempted to alter a flag, but entered some characters that are not acceptable pairs of flag values. See R (Register) command for the list of acceptable flag entries.
BP	Too many Breakpoints You specified more than ten breakpoints as parameters to the GO command. Reenter the command with ten or fewer breakpoints.
BR	Bad Register You entered the R command with an invalid reg- ister name.
DF	Double Flag You entered two values for one flag.

4

8086 Addressing Scheme

- Overview
- The 20-Bit Address
- Aligned and Non-Aligned Words
- Registers and Flags
- Code, Data, and Stack Segments
- Addressing Modes

The 8086 microprocessor has an extremely flexible addressing scheme. The 8086 uses a 16-bit word, but can address a megabyte of memory. The 8086 supports seven different addressing modes.

To take advantage of the flexibility of the 8086, so that you can write assembly language code and navigate through programs while debugging, study the addressing scheme by carefully reading this chapter.

The 20-Bit Address

The AT&T Personal Computer 6300 utilizes the full address space that is available due to the design of the 8086 microprocessor. The addresses are 20 bits long, so the address space is two to the twentieth power, 1024K, or one megabyte.

The 8086 has a 16-bit word. To convert 16-bit words to a 20-bit address, the 8086 uses "segmented addressing." A 20-bit address is created by using values from two separate registers. Two 16-bit numbers are used.

The binary representation of the first number is considered to have four binary zeroes tacked on to its end. This effectively multiplies the number by 16. This value is known as the segment portion of the address. The segment portion can point to any 16-byte segment of memory in the megabyte address space. However, with four zeroes as its least significant bits, it cannot "zero in" on individual bytes. The segment register's function is just to point to a 16-byte boundary (also known as a paragraph boundary).

Once a segment is located, the other register comes into play. This "offset register" points to the relative part of the address. The 16 bits that comprise the offset register point to an individual byte which is relative to the start of the segment.

8086 Addressing Scheme

		The 8086 locates a par	rticular address by:	
	1	Shifting the segment register to the left by four bits		
	2	Adding the contents of the offset register		
		The 20-bit address is o in special notation:	conventionally expressed	
Syntax		<segment register=""></segment>	offset register>	
Example		009F:0012		
		Segment address + Relative address	009F0 0012	
		= Actual Address	00A02	

Aligned and Non-Aligned Words

The instructions for the 8086 are made up of from one to six bytes. Instructions can start at either an even or odd address. The 8086 is capable of accessing two bytes of data in memory in a single memory cycle. When the CPU accesses a word (16 bits) located at an even address, it is accessing an "aligned" word. The word is aligned because both bytes are located at the same word address and can be accessed in a single memory cycle.

When the CPU accesses a word starting at an odd address, it is accessing a "non-aligned" word. Since the two bytes comprising the word do not occupy the same word address, two memory cycles are required to read the entire word.

The importance of aligned or non-aligned words is determined by the importance of execution speed in your application. It is good programming practice to store data starting at an even address. If your program accesses or manipulates many word quantities, this will help speed program execution. If you are writing a device driver and instruction cycle times affect the execution of your program, the impact of aligned and non-aligned words should be taken into consideration.

General Registers

There are two main groups of general registers used by the 8086: the data group and the pointer and index group. Each register is 16 bits wide.

- The data registers are AX, BX, CX, and DX. Each can be used as a single 16-bit register or as two 8-bit registers. When they are used as two 8-bit registers, they are divided into an upper(H) and lower(L) half and called AH, AL, BH, BL, CH, CL, DH, and DL.
- The pointer and index registers are 16-bit registers. They are named according to their functions: SP (stack pointer), BP (base pointer), SI (source index), and DI (destination index).

Segment Registers	There are four segment registers in the 8086. Each register is 16 bits and their names reflect their use:
•	CS — Code Segment Always defines the current code segment.
•	DS — Data Segment Usually defines the current data segment.
•	SS — Stack Segment Always defines the current stack segment.
•	ES — Extra Segment Can define an auxiliary data segment.
	These registers are used in combination with other registers to form the 20-bit address. Each segment begins on a paragraph (16 byte) bound- ary. There are four "current" segments at any one time. The contents of each segment register is called the "segment base value". The sections on "Code, Data, and Stack Segments" and "Addressing Modes" give details on how these registers are utilized.
Instruction Pointer	The instruction pointer (IP) is used in conjunc- tion with the Code Segment register to point to the address of the next executable instruction. The IP is also a 16-bit register.
Flags	The 8086 has nine 1-bit status or condition flags that are used to indicate the condition of the result of an arithmetic or logical operation that has just occurred. Some of the assembly lan- guage instructions use these flags to condition- ally change the execution path of a program.

8086 Addressing Scheme

Flag Definitions	ÁF	Auxiliary Carry Flag This flag is set (i.e., equal to 1) under two conditions:
		During addition there is a carry of the low nybble to the high nybble. (nybble = 4 bits)
		During subtraction there is a borrow from the low nybble to the high.
	CF	Carry Flag This flag is set when there has been a carry or a borrow to the high-order bit of the (8- or 16-bit) result of an operation.
	OF	Overflow Flag When this flag is set, an arithmetic over- flow has occurred and a significant digit has been lost.
	SF	Sign Flag This flag is set when the high-order bit of the result of an operation is a logical 1. Since negative binary numbers are represented using two's complement notation, SF reflects the sign of the result: 0 indicates a positive number and 1 indicates a negative number.
	\mathbf{PF}	Parity Flag If this flag is set, the result of the operation has an even number of ones in it. Use this flag to check for data transmission errors.
	ZF	Zero Flag This flag is set when the result of an opera- tion is zero.

Flag Definitions (Cont'd)	TF	Trap Flag When set, the trap flag puts the system into single-step mode for the purposes of debug- ging. An internal interrupt is generated after each instruction so that you can inspect your program one instruction at a time.		
	IF	Interrupt-enable Flag If this flag is set, external (maskable) inter- rupts are recognized by the 8086.		
	DF	Direction Flag This flag is set and cleared by the STD (Set Direction Flag) and CLD (Clear Direction Flag) instructions. If it has the value 1, SI and DI are decremented during string move operations. If it has the value of 0, SI and DI are incremented during string move operations. This flag is used for the follow- ing instructions: MOVS, MOVSB, MOVSW, CMPS, CMPSB, and CMPSW. The flag register looks like this:		
Bit 15 14 13	19 1	1 10 9 8 7 6 5 4 3 2 1 0		
		$\overrightarrow{\text{DF}} \overrightarrow{\text{DF}} \overrightarrow{\text{IF}} \overrightarrow{\text{TF}} \overrightarrow{\text{SF}} \overrightarrow{\text{ZF}} - \overrightarrow{\text{AF}} - \overrightarrow{\text{PF}} - \overrightarrow{\text{CF}}$		
FLA	GSh	FLAGS1		

8086 Addressing Scheme

Registers

AX	АН	AL	accumulator
BX	BH	BL	base
сх	СН	CL	count
DX	DH	DL	data
			-

SP ΒP SI DI

stack pointer base pointer source index destination index

IP		instruction pointer
FLGSh	FLGS1	flags

CS	
DS	
ES	
SS	

code segment

data seg

extra seg

stack seg

Code, Data, and Stack Segments

	When you invoke a program, MS-DOS loads all of its segments into memory on paragraph boundaries. The segment registers are set to point to these locations. The data, code, and stack segments aren't necessarily far apart in memory; they may, in fact, overlap. Each seg- ment may be up to 64 KB in length.
Code Segment	Programs are limited to 64K of code, unless they change the value in the CS register. If a pro- gram changes the CS register, it may address up to 1024K of code.
	The CS register is modified by the FAR CALL and FAR RETurn instructions. Use these instructions to execute code that is located out- side the bounds of the current segment.
Data Segment	Most programs use a maximum of 64 KB of memory for data. This includes Pascal and compiled BASIC. Assembly language programs, however, can use additional memory for data by employing the Extra Segment.
Extra Segment	The extra segment may be used in any manner you wish but is often used for transferring large blocks of data quickly in memory or as a storage area for a second stack.
Stack Segment	Stacks are used for temporarily storing register contents and other important values under these conditions:
• • •	Interrupts Inter-segment calls One program calls another

8086 Addressing Scheme

General Comments	The flexible architecture of the 8086 supports many different memory-addressing modes. These can be broken down into six main types of addressing: immediate, register, direct, register indirect, and two kinds of calculated addressing. The following section discusses these modes and concerns the nature of the operand.
Immediate Addressing	In the immediate addressing mode, the operand appears in the instruction. For example, MOV AX,333 moves the constant value 333 into the AX register.
Register Addressing	The register addressing mode uses the contents of one of the registers as the operand for the instruction. The instruction can specify that either 8 bits or 16 bits are to be manipulated. For example: MOV AX,BX ;moves 16 bits from BX to AX MOV AL,BL ;moves 8 bits from BL to AL

Direct Addressing	The direct addressing mode specifies a location in memory whose contents are used as the ope- rand for the instruction. Example: MOV CX,COUNT
	This instruction uses the value found in the memory location designated by the symbol COUNT. Unless otherwise specified, COUNT is expected to be somewhere in the Data Segment. To specify that the operand is located in a seg- ment other than the data segment, use the "segment override prefix:"
	MOV CX, ES:COUNT
	This syntax specifies that COUNT is located in the Extra Segment.
Register Indirect Addressing	With the register indirect addressing mode, the 16-bit offset address is contained in a base or index register. That is, the offset address resides in the BX, BP, SI, or DI register. Example:
	MOV AX,[SI]
	The 16-bit offset contained in the SI register is combined with the data segment register to compute the 20-bit address of the operand to move into register AX. Which segment register is used to compute the address depends on which instruction you are using (i.e., data segment or segment override for MOV, code segment for JMP or CALL, etc.).

8086 Addressing Scheme

Calculated Addressing Modes

The calculated addressing modes are like a combination of register indirect mode and direct addressing mode. There are two calculated addressing modes: single index and double index. In single index addressing, a 16-bit offset from the BX, BP, SI or DI register is added to an offset location in memory specified in the instruction. The combined value of these two items provides the offset into memory from which the operand is fetched. If the BP register is used the offset is from within the stack segment; otherwise the offset is from within the data segment. As always, use of a segment override prefix can change this. Examples:

MOV AX, COUNT[DI] MOV AX, RECORD[BP]

In double index calculated addressing mode, values from two 16-bit registers are added to an optionally specified location in memory to produce the final offset. Either the BX or BP register is used for one of the register values, and the SI or DI register is used for the other one. If only two registers are given with no memory location, the memory location defaults to 0000 (start of segment). Once again, the default calculation is from the stack segment if the BP register is used; if BX is used the default is from the data segment. Examples:

MOV AX, COUNT[BX+SI] MOV AX, RECORD[BP] [DI] MOV AX, [BX] [DI]

5 Memory Maps Control Blocks Diskette Allocation

- Overview
- The Address Space
- Low Memory Map
- ROM BIOS Data Area
- File Control Blocks
- ASCIIZ Strings
- Handles
- Diskette Layout
- Diskette Directory
- File Allocation Table
- Diskette Formats

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The purpose of this chapter is to enable you to locate items in memory or on diskette for the purposes of programming and debugging.

The first portion of the chapter contains detailed memory maps of the RAM and ROM memory areas. The sections on control blocks deal with program file formats and I/O data structures. The last part of this chapter describes how data is organized on the diskette.

The Address Space

Hex	Decimal	Contents
00000	0K	Interrupt vectors (see detail in low memory map)
04000	16K	DOS software
08000	32K	Language, applications programs and data
		Note: There is at least 98,000 hex or 608K of address space reserved for user pro- grams and data. To take advantage of the full amount, you must have purchased and installed the physical memory.
		•
		•
A0000	640K	Reserved for extended graphics
B0000	704K	Monochrome display buffer — Not used
B8000	736K	Color/graphics display buffer(s)
C8000	800K	Fixed disk adapter's ROM (Optional)
F0000	960K	Reserved for ROM expansion
FC000	1008K	ROM BIOS

Low Memory Map

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Hexadecimal addresses are in segment:offset format.

Hex	Decimal	Contents
0:0000	0	Interrupt vectors 0 - 7 8259 interrupt controller vectors (8-F)
0:0040	64	
0:0080	128	BIOS interrupt vectors 10-1F
0:0100	256	MS-DOS interrupt vectors 20-3F
0.0100	200	Assignable interrupt vectors (40-FF)
0:0400	1024	Note: These vectors may be assigned to non-Intel hardware and software products.
0:0500	1024	ROM BIOS data area (also called BIOS communications area) See map on next page.
0.0000	1200	DOS data area (also called DOS com- munications area)
0:0600	1536	

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ROM BIOS Data Area

Hex addresses are in segment:offset format.

Hex	Decimal	Contents
0:0400	1024	Hardware environment parameters (printer and RS232C device addresses, memory size, etc.)
0:0417	1047	
0:043E	1086	Keyboard buffer and status bytes
0:0449	1097	Floppy and hard disk status bytes
0:0467	1127	Video display area (current mode, color pallette, cursor position, active page numbers, etc.)
0:0471	1137	Data area for option ROM and 8253 timer chip
0:0488	1160	Fixed disk, I/O timeouts, and more key- board status information
		RESERVED
0:0500	1280	Inter-applications communications area

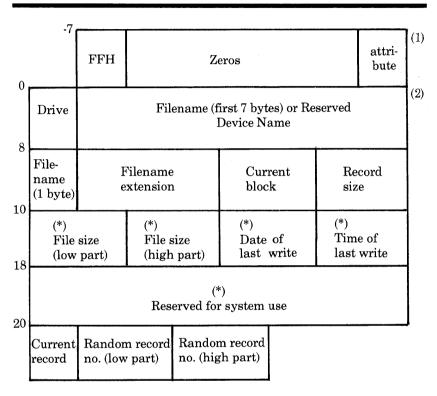
FCB Format

The standard File Control Block (FCB) contains 37 bytes of file control information. The extended File Control Block is used to create or search for files in the disk directory that have special attributes. If the extended FCB is used, it adds a 7-byte prefix to the standard FCB.

Any of the DOS functions which employ FCBs may use either an FCB or an extended FCB. (See chapter 7 for a description of each DOS function call.)

If you are using an extended FCB, set the appropriate register to the first byte of the prefix, not to the first byte of the standard FCB, before executing the function call.

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(1) FCB extension

(2) Standard FCB

(*) Areas with an asterisk are filled by DOS and must not be modified. Other areas must be filled by the using program. Offsets are in decimal.

Byte	Function		
0	Drive number		
	Before open: 0 — default drive 1 — drive A 2 — drive B etc.		
	After open: $1 - \text{drive A}$ 2 - drive B etc.		
	A 0 is replaced by the actual drive number when the file is opened.		
1-8	Filename, left-justified, padded with trailing blanks. If a reserved device name is placed here (e.g., LPT1,) do not include the optional colon.		
9-OB	Filename extension, left-justified, with trailing blanks (may be all blanks).		
OC-OD	Current block number relative to the beginning of the file (starting at zero). A block is defined as a group of 128 records. This field is set to 0 when the file is opened. This field and the Cur- rent Record field (offset 20H) make up the record pointer that is used for sequential reads and writes.		
OE-OF	Logical record size in bytes. Automati- cally set to 80H during open. If this is not correct, set it to the correct value.		
10-13	File size in bytes. The first word of the		

Byte	Function
14-15	Date the file was created or last up- dated. The bits correspond to the date as follows:
	< 15 >< 14 > 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0 y y y y y y ymmmddddd
	yy = 0 - 119 (1980 to 2099) mm = 1 - 12 dd = 1 - 31
16-17	Time the file was created or last up- dated. The bits correspond to the time as follows:
	$< 17 > < 16 > \\ 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0 \\ h h h h h mmmmms s s s s $
	hh = 0 - 23 mm = 0 - 59 ss = 0 - 30 (number of 2-second increments)
18-1F	Reserved for use by DOS.
20	Current relative record number (0-127) within the current block. Set this field before doing sequential read/write operations; it is not initialized by the Open File function call.
21-24	Relative record number; relative to the beginning of the file, starting with zero.

Byte	Function
	This field is not initialized by the Open File function call and must be set before doing a random read or write. If the record size is less than 64 bytes, both words of the field are used; otherwise, only the first three bytes are used.
	Note: If you use the FCB at offset 5CH of the Program Segment Prefix, the last byte of the Relative Record field is the first byte of the unformatted parameter area that starts at offset 80H. This is the default Disk Transfer Address.

Extended Control Block	Byte	Function
	FCB-7	Contains hex FF to indicate this is extended FCB.
	FCB-6 to FCB-2	Reserved
	FCB-1	Attribute byte. 02 = Hidden file 04 = System file

ASCIIZ Strings

MS-DOS version 2.11 provides a set of new function calls for file I/O that are easier to use than the "traditional" calls that were used in past versions. These new calls do not utilize file control blocks. To open a diskette file, you simply provide information to identify the file in the form of an ASCIIZ string. DOS returns a numeric value, a "handle", that you use to refer to the file once you have opened it.

The older function calls that require the use of file control blocks and do not utilize ASCIIZ strings and handles are supported in MS-DOS 2.11 to provide upward compatibility. Use the newer function calls whenever possible. See Chapter 7 for details of function calls.

ASCIIZ String Format An ASCIIZ string, also known as a pathname string, has the following format: an optional drive specifier, followed by a directory path, and where applicable, a filename. The last byte must be binary zeroes. For example:

A:\LEVELA\LEVELB\FILEA

(followed by a byte of zeroes)

Either back slash (\setminus) or forward slash (/) are valid path-separator characters.

Several of the new function calls that support files or devices use an identifier known as a "handle" (also known as a "token"). When you create or open a file or device with these function calls, a 16-bit value is returned in register AX. Use this handle to refer to the file after it has been opened.

The following handles are pre-defined by DOS for your use. You need not open them before using them:

- 0000 Standard input device
- 0001 Standard output device
- 0002 Standard error output device
- 0003 Standard auxiliary device
- 0004 Standard printer device

Note:

See your MS-DOS User's Guide for information on redirecting I/O for the first two handles.

The DOS area of the diskette is formatted as follows:

Reserved Area — variable size

First copy of file allocation table — variable size

Second copy of file allocation table — variable size

Root directory — variable size

File data area

Clusters

Space for a file in the data area is not preallocated. The space is allocated one "cluster" at a time. A cluster consists of one or more consecutive sectors; all of the clusters for a file are "chained" together in the File Allocation Table (FAT). On diskettes formatted by MS-DOS 2.11, there are two copies of the FAT kept, for consistency. Should the disk develop a bad sector in the middle of the first FAT, the second is used as a backup.

	tory max the r Since are r limit All c are i	e FORMAT command builds the root direc- y for all disks. Its location on disk and the ximum number of entries are dependent on media. the directories other than the root directory regarded as files by MS-DOS, there is no it to the number of files they may contain. directory entries are 32 bytes in length, and in the following format (byte offsets are in cadecimal):	
Directory Format	an th: tho sta 00	and p this is the fir	ame. Eight characters, left aligned added, if necessary, with blanks. If s not currently a file directory entry, rst byte of this field indicates the s as follows: The directory entry has never been used. This is used to mark the end of the allocated directory and limit the length of directory searches, for per- formance reasons. The entry is for a directory (2EH is the ASCII code for the dot '.' char- acter used to represent a directory). If the second byte is also 2EH (i.e., the entry is ''), then the cluster field con-
		•	tains the cluster number of this direc- tory's parent directory (0000H if the parent directory is the root directory). Otherwise, bytes 01H through 0AH are all spaces (i.e., the entry is '.') and the cluster field contains the cluster number of this directory.

8-0A	Filename extension.			
0B	File attribute. The attribute byte is mapped as follows (values are in hex):			
	 61 File is marked read-only. An attempt to open the file for writing using the Open a File system call (Function Request 3DH) results in an error code being returned. This value can be used along with other values below. Attempts to delete the file with the Delete File system call (13H) or Delete a Directory Entry (41H) will also fail. 62 Hidden file. The file is excluded from normal directory searches. 64 System file. The file is excluded from normal directory searches. 68 The entry contains the volume label in the first 11 bytes. The entry contains no other usable information 			
	(except date and time of creation), and may exist only in the root			
	directory. 10 The entry defines a sub-directory, and is excluded from normal direc-			
	 tory searches. 20 Archive bit. The bit is set to "on" whenever the file has been written to and closed. It is used by BACKUP and RESTORE commands for determining whether or not a file has changed since its last backup. The BACKUP command clears this attribute on all files backed up. 			

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Memory Maps Control Blocks Diskette Allocation

Directory Format (cont'd)		The system files (IO.SYS and MSDOS.SYS) are marked as read-only, hidden, and system files. Files can be marked hidden when they are created. Also, the read-only, hidden, system, and archive attributes may be changed through the Change Attributes system call (Function Request 43H).	
	0C-15	Reserved.	
	16-17	Time the file was created or last updated The hour, minutes, and seconds are mapped into two bytes as follows:	
		Offset 17H $ H H H H H M M M M $ 7 6 5 4 3 2 1 0 Offset 16H $ M M M S S S S S S $ 5 $ S S S S $ $ S $ 7 6 5 4 3 2 1 0 Offset 16H $ M M M S S S S S S S $	
		 H is the number of hours (0-23) M is the number of minutes (0-59) S is the number of two-second increments 	
		The time is stored with the least signifi- cant bit first.	

Memory Maps Control Blocks Diskette Allocation

Directory Format (cont'd)	18-19	Date the file was created or last updated. The year, month, and day are mapped into two bytes as follows:		
		$\begin{array}{c c c} \text{Offset 19H} \\ & Y & Y & Y & Y & Y & Y & Y \\ \hline 7 & 6 & 5 & 4 & 3 & 2 & 1 & 0 \end{array}$		
		$\begin{array}{c c c c c c c c c c c c c c c c c c c $		
		 Y is the number of years since 1980, 0-119 (1980-2099) M is the month number 1-12 D is the day of the month 1-31 		
cant byte first. 1A-1B The cluster number of the fithe file. The first cluster for on all disks is cluster 002.		The date is stored with its least signifi- cant byte first.		
	The cluster number of the first cluster in the file. The first cluster for data space on all disks is cluster 002.			
		The cluster number is stored with the least significant byte first.		
	Note:			
	for det	to "How to Use the File Allocation Table" ails on converting cluster numbers to logi- tor numbers.		

1C-1F File size in bytes. The first word of this four-byte field is the low-order part of the size.

Memory Maps Control Blocks Diskette Allocations

File Allocation Table (FAT)

	The following information is included primarily for system programmers who are writing install- able device drivers. This section explains how MS-DOS uses the File Allocation Table to con- vert the clusters of a file to logical sector num- bers. The driver program is then responsible for locating the logical sector on disk. If you are writing a system utility, use the MS-DOS file management function calls for accessing files; programs that access the FAT directly are not guaranteed to be upwardly-compatible with future releases of MS-DOS.
FAT Entries	The File Allocation Table is an array of 12-bit entries (1.5 bytes) for each cluster on the disk.
•	The first two FAT entries map a portion of the directory; these FAT entries indicate the size and format of the disk.
•	The second and third bytes currently always contain FFH.
•	The third FAT entry, which starts at byte offset 4, begins the mapping of the data area (cluster 002). Files in the data area are not always writ- ten sequentially on the disk. The data area is allocated one cluster at a time, skipping over clusters already allocated. The first free cluster found will be the next cluster allocated, regard- less of its physical location on the disk. This permits the most efficient utilization of disk space because clusters made available by eras- ing files can be allocated for new files.

Each FAT entry contains three hexadecimal characters:

- 000 If the cluster is unused and available.
- FF7 The cluster has a bad sector in it. MS-DOS will not allocate such a cluster. CHKDSK counts the number of bad clusters for its report. These bad clusters are not part of any allocation chain.
- FF8-FFF Indicates the last cluster of a file.
- XXX The cluster number of the next cluster in the file. The cluster number of the first cluster in the file is kept in the file's directory entry.

The File Allocation Table always begins on the first sector after the reserved sectors. If the FAT is larger than one sector, the sectors are contiguous. Two copies of the FAT are usually written for data integrity. The FAT is read into one of the MS-DOS buffers as needed (open, read, write, etc.). For performance reasons, this buffer is given a high priority so that it stays in memory as long as possible.

How to Use the File Allocation Table	Use the directory entry to find the starting clus- ter of the file. Next, to locate each subsequent cluster of the file:
1	Multiply the cluster number just used by 1.5 (each FAT entry is 1.5 bytes long).
2	The whole part of the product is an offset into the FAT, pointing to the entry that maps the cluster just used. That entry contains the cluster number of the next cluster of the file.
3	Use a MOV instruction to move the word at the calculated FAT offset into a register.
4	If the last cluster used was an even number, keep the low-order 12 bits of the register by ANDing it with FFF; otherwise, keep the high- order 12 bits by shifting the register right 4 bits with a SHR instruction.
5	If the resultant 12 bits are FF8H-FFFH, the file contains no more clusters. Otherwise, the 12 bits contain the cluster number of the next cluster in the file.

To convert the cluster to a logical sector number (relative sector, such as that used by Interrupts 25H and 26H and by DEBUG):

- **1** Subtract 2 from the cluster number.
- **2** Multiply the result by the number of sectors per cluster.
- **3** Add to this result the logical sector number of the beginning of the data area.

On an MS-DOS disk, the clusters are arranged on diskette to minimize head movement for multi-sided media. All of the space on a track (or cylinder) is allocated before moving on to the next track. This is accomplished by using the sequential sectors on the lowest-numbered head, then all the sectors on the next head, and so on until all sectors on all heads of the track are used. The next sector to be used will be sector 1 on head 0 of the next track.

The first byte of the FAT, called the Media Descriptor Byte, can sometimes be used to determine the format of the disk. The following formats have been defined for the AT&T Personal Computer 6300, based on values of the first byte of the FAT.

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MS-DOS	No. sides	1	1	2	2
Standard Diskette	Tracks/side	40	40	40	40
Formats	Bytes/sector	512	512	512	512
	Sectors/track	8	9	8	9
	Sectors/cluster	1	1	2	2
	Reserved sectors	1	1	1	1
	No. FATs	2	2	2	2
	Root directory entries	64	64	112	112
	No. sectors	320	360	640	720
	Media Descriptor Byte	FE	FC	FF	FD
	Sectors for 1 FAT	1	2	1	2

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Program Structure and Loading

- Overview
- Pros and Cons for Selecting a Program File Format
- EXE2BIN
- File Header Format
- Relocation Process for .EXE Files
- Program Segment Prefix
- Program Loading Process

This chapter describes the MS-DOS program file formats and procedures for loading them into memory. MS-DOS supports two main program file formats: .EXE and .COM.

The .EXE format is the more flexible program type. An .EXE file is limited in size only by the amount of user memory installed in your system.

Programs linked by MS-LINK are output in .EXE format. .EXE files can be executed either by COMMAND.COM or by an EXEC system call (Function Request 4BH) in your program.

A .COM program file cannot exceed 64K bytes in length. However, because it does not have the same lengthy header that an .EXE file does, a .COM file takes up less diskette storage space and loads into memory more quickly than an .EXE file.

After assembling and linking your program, it must be converted to .COM format. The easiest way to do this is with the EXE2BIN utility provided on your MS-DOS Supplemental Programs diskette.

Pros and Cons for Selecting a Program File Format

This section is concerned with the pros and cons of selecting between a .EXE program format and the .COM program type.

PROS for .EXE

- Can be larger than 64 K
- Can cross segment boundaries
- Can run .EXE immediately after linking, i.e., you need not take the extra step of running EXE2BIN
- Can declare a stack segment in the assembly program

CONS for .EXE

• Disk file has large "header" containing relocation information. .EXE therefore takes more space on disk and takes longer to load into memory at execution time.

PRO for .COM

• .COM files are smaller and faster loading because .COM does not have a file header containing relocation information.

CONS for .COM

- .COM files can be no larger than one 64K segment.
- .COM is segment-relocatable; the segment can be relocated at run time. However, all of the addresses in the program must be relative to the same segment address.

EXE2BIN

EXE2BIN EXE2BIN is an executable program available on your MS-DOS system diskette. It converts programs that are in .EXE format (as they are after having been linked) into the .COM format.

EXE2BIN can generate two types of .COM files: relocatable and non-relocatable.

Syntax	EXE2BIN <input filename=""/> <output file<br="">name> Both file names are in the form: [d:][path][filename[.ext]]</output>
Example	EXE2BIN B:PROG.EXE B:PROG.COM
Discussion	In specifying the input file, everything except the file name is optional. If you do not specify a drive, the default is used. If you do not specify a path, the default path is used. If you do not spec- ify an extension, the default is .EXE. The input file is converted to .COM file format (memory image of the program) and placed in the output file.
	You are not required to enter any part of the output file specification. If you do not specify a drive, the drive of the input file will be used. If you do not specify an output path or filename, the input path or filename will be used. If you do not specify a filename extension in the output filename, the new file will be given an extension of .BIN.
	The input file must be in valid .EXE format pro- duced by the linker. The resident, or actual code and data part of the file must be less than 64K. There must be no STACK segment.

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Two kinds of conversions are possible, depending on the initial CS:IP (Code Segment: Instruction Pointer) specified in the .EXE file:

- 1 If CS:IP is specified as 0000:100H, it is assumed that the file is to be run as a .COM file with the location pointer set at 100H by the assembler statement ORG; the first 100H bytes of the file are deleted. No segment address fixups (that is, instructions that contain a reference to an absolute segment address) are allowed, as .COM files must be segment relocatable. Once the conversion is complete, rename the resulting file with a .COM extension. The command processor can load and execute the program in the same way as the .COM programs supplied on your MS-DOS diskettes.
- 2 If CS:IP is not specified in the .EXE file, a pure binary conversion is assumed. If segment fixups are necessary (i.e., the program contains instructions requiring a segment address), you are prompted for the fixup value. This value is the absolute segment at which the program is to be loaded. The resulting program is usable only when loaded at the absolute memory address specified by your application. The command processor is not capable of properly loading the program. This is the case when writing a .BIN program to use in an application such as a device driver that is always loaded at the same absolute address.

EXE2BIN Messages

Amount read less than size in header

The program portion of the file was smaller than indicated in the file's header. You should reassemble and relink your program.

File cannot be converted

CS:IP does not meet either of the criteria specified above, or it meets the .COM file criterion but has segment fixups. This message is also displayed if the file is not a valid executable file.

File creation error

EXE2BIN cannot create the output file. Run CHKDSK to determine if the directory is full or if some other condition caused the error.

File not found

The file is not on the diskette specified.

Fixups needed - base segment (hex):

The source (.EXE) file contained information indicating that a load segment is required for the file. Specify the absolute segment address at which the finished module is to be located.

Insufficient disk space

There is not enough disk space to create a new file.

Insufficient memory

There is not enough memory to run EXE2BIN.

WARNING - Read error in EXE file

Amount read less than size in header. This is a warning message only. However, it is usually a good idea to reassemble and relink your source program when this message appears.

File Header Format

The .EXE files produced by MS-LINK consist of two parts:

- Control and relocation information
- The load module

The control and relocation information is at the beginning of the file in an area called the header. The load module immediately follows the header.

Note: .COM files do not have file headers. The header is formatted as follows (offsets are in hexadecimal):

0)ffset	Contents
Ç	00-01	Must contain 4DH, 5AH.
C)2-03	Number of bytes contained in last page; used for reading overlays.
C)4-05	Size of the file in 512-byte pages, including the header.
C)6-07	Number of relocation entries in table.
C)8-09	Size of the header in 16-byte para- graphs. This is used to locate the beginning of the load module in the file.
0.	A-0B	Minimum number of 16-byte para- graphs required above the end of the loaded program (minalloc).
0	C-0D	Maximum number of 16-byte para- graphs required above the end of the loaded program (maxalloc). If both minalloc and maxalloc are 0, then the program will be loaded as high as possible.

0E-0F	Initial value to be loaded into stack segment before starting program execution. This must be adjusted by relocation.
10-11	Value to be loaded into the SP reg- ister before starting program exe- cution.
12-13	Negative sum of all the words in the file.
14-15	Initial value to be loaded into the IP register before starting program execution.
16-17	Initial value to be loaded into the CS register before starting pro- gram execution. This must be adjusted by relocation.
18-19	Relative byte offset from beginning of run file to relocation table.
1A-1B	The number of the overlays gener- ated by MS-LINK.

This is followed by the relocation table. The table consists of a variable number of relocation items. Each relocation item contains two fields: a two-byte offset value, followed by a two-byte segment value. These two fields contain the offset into the load module of a word which requires modification before the module is given control.

Relocation Process for .EXE Files

The following steps describe the relocation process:

- **1** The formatted part of the header is read into memory. Its size is 1BH.
- 2 A portion of memory is allocated depending on the size of the load module and the allocation numbers (0A-0B and 0C-0D). MS-DOS attempts to allocate FFFFH paragraphs. This will always fail, returning the size of the largest free block. If this block is smaller than minalloc and loadsize, then there will be a no memory error. If this block is larger than maxalloc and loadsize, MS-DOS will allocate (maxalloc + loadsize). Otherwise, MS-DOS will allocate the largest free block of memory.
- **3** A Program Segment Prefix is built in the lowest part of the allocated memory.
- 4 The load module size is calculated by subtracting the header size from the file size. Offsets 04-05 and 08-09 can be used for this calculation. The actual size is downward-adjusted based on the contents of offsets 02-03. Based on the setting of the high/low loader switch, an appropriate segment is determined at which to load the load module. This segment is called the start segment.

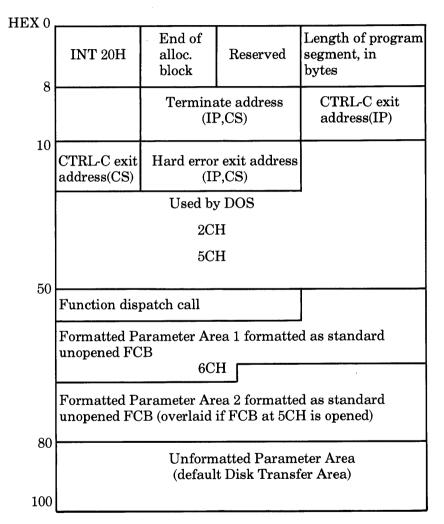
- 5 The load module is read into memory beginning with the start segment.
- 6 The relocation table items are read into a work area.
- 7 Each relocation table item segment value is added to the start segment value. This calculated segment, plus the relocation item offset value, points to a word in the load module to which is added the start segment value. The result is placed back into the word in the load module.
- 8 Once all relocation items have been processed, the SS and SP registers are set from the values in the header. Then, the start segment value is added to SS. The ES and DS registers are set to the segment address of the Program Segment Prefix. The start segment value is added to the header CS register value. The result, along with the header IP value, is the initial CS:IP to transfer to before starting execution of the program.

Program Segment Prefix

Unless you specify otherwise when linking your program, DOS loads your program in the lowest memory address available, immediately following the DOS code. This occurs whether the program loads as a result of your entering its name at the DOS prompt or through your use of the EXEC (4BH) function call. The area into which your program is loaded is called the Program Segment.

DOS requires control information for each running program: it builds a Program Segment Prefix and places it at offset 0 within the program segment. The Program Segment Prefix is hex 100 bytes long, so your program is loaded at relative address 100H.

PSP Format



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HEX OFFSET	CONTENTS			
0	Return address used by interrupt hex 20			
2	Segment address of allocatable memory following this program (If this program calls a memory management function to get more memory, this is its starting address.)			
4	Reserved			
6	Number of bytes in this program segm	ent (2 byte value)		
8	Not used			
A	Terminate address : IP	•		
C	Terminate address : CS			
E	Ctrl break exit : IP	· · ·		
10	Ctrl break exit : CS			
12	Critical error exit : IP			
14	Critical error exit : CS			
2C	Segment address of the environment	USED by DOS		
50	Code to call function dispatcher for DOS (INT 21H) interrupts			
$5\mathrm{C}$	Formatted parameter area 1: formatted as standard, unopened FCB			
6C	Formatted parameter area 2: formatted as standard, unopened FCB			
80	Count of argument characters that follow the command name.	These comprise the default DTA: Disk Transfer		
81	The argument characters themselves.	Area(80H - FFH)		

Program Loading Process

PSP Conditions	When a program receives control, the following conditions are in effect:
upon Program Initiation	• The segment address of the passed environment is contained at offset 2CH in the Program Seg- ment Prefix. The environment is a series of ASCII strings (totaling less than 32K) in the form:

NAME = parameter

Each string is terminated by a byte of zeros, and the set of strings is terminated by another byte of zeros. The environment built by the command processor contains at least a COMSPEC= string (the parameters on COMSPEC define the path used by MS-DOS to locate COMMAND.COM on disk). The last PATH and PROMPT commands issued will also be in the environment, along with any environment strings defined with the MS-DOS SET command.

The environment that is passed is a copy of the invoking process environment. If your application uses a "keep process" concept, be aware that the copy of the environment passed to you is static. That is, it will not change even if subsequent SET, PATH, or PROMPT commands are issued.

- Offset 50H in the Program Segment Prefix contains code to call the MS-DOS function dispatcher. After correctly loading the registers, a program can issue a far call to offset 50H to invoke an MS-DOS function, rather than issuing an Interrupt 21H. Since this is a call and not an interrupt, MS-DOS may place any code appropriate to making a system call at this position. This makes the process of calling the system portable.
- The Disk Transfer Address (DTA) is set to 80H (default DTA in the Program Segment Prefix).
- File control blocks at 5CH and 6CH are formatted from the first two parameters typed when the command was entered. If either parameter contains a pathname, then the corresponding FCB contains only the valid drive number. The filename field will not be valid.
- An unformatted parameter area at 81H contains all the characters typed after the command (including leading and imbedded delimiters), with the byte at 80H set to the number of characters. If the < or > parameters were typed on the command line, they (and the filenames associated with them) do not appear in this area or in the character count; redirection of standard input and output is transparent to applications.
- Offset 6 (one word) contains the number of bytes available in the segment.

• Register AX indicates whether or not the drive specifiers (entered with the first two parameters) are valid, as follows:

AL=FF if the first parameter contained an invalid drive specifier (otherwise AL=OO)

AH=FF if the second parameter contained an invalid drive specifier (otherwise AH=OO)

• Offset 2 (one word) contains the segment address of the first byte of unavailable memory. Programs must not modify addresses beyond this point unless they were obtained by allocating memory via the Allocate Memory system call (Function Request 48H).

Initial Conditions for .EXE	•	DS and ES registers are set to point to the Pro- gram Segment Prefix.
Programs	•	CS, IP, SS, and SP registers are set to the values passed by MS-LINK.

Initial Conditions for .COM Programs

- All four segment registers contain the segment address of the initial allocation block that starts with the Program Segment Prefix control block.
- The Instruction Pointer (IP) is set to 100H.
- The Stack Pointer register is set to the end of the program's segment. The segment size at offset 6 is reduced by 100H to allow for a stack of that size.
- A word of zeros is placed on top of the stack. This allows your program to exit to COM-MAND.COM by doing a RET instruction last. Make sure, however, to maintain your stack and code segments.

Other Uses of the Program Segment Prefix	In MS-DOS versions prior to 2.0, the PSP con- tained the mechanism for program termination. One of these four techniques had to be used to terminate your programs:		
1	A long jump to offset 0 in the Program Segment Prefix.		
2	By issuing an INT 20H with CS:0 pointing at the PSP.		
3	By issuing an INT 21H with register $AH = 0$ and $CS:0$ pointing at the PSP.		
4	By a long call to location 50H in the Program Segment Prefix with AH = 0 and CS:0 pointing at the PSP.		
	It is the responsibility of all programs to ensure that the CS register contains the segment address of the Program Segment Prefix when terminating via any of these methods.		
	However, with the 2.0 Terminate a Process sys- tem call (Function Request 4CH), the CS register need not point to the Program Segment Prefix. For this reason, Function Request 4CH is the preferred method. It may be invoked by loading the AH register with 4CH and issuing an INT 21H (or a long call to offset 50H in the Program Segment Prefix).		

System Calls

- Quick Reference: Functions and Interrupts
- Overview
- Programming Considerations
- Interrupts
- Functions
- System Call Descriptions

Functions

Number	Function Name	Number	Function Name
OOH	Terminate Program	30H	Get DOS Version
01H	Read Keyboard and		Number
	Echo	31H	Keep Process
02H	Display Character	33H	<CTRL C $>$ Check
03H	Auxiliary Input	35H	Get Interrupt Vector
04H	Auxiliary Output	36H	Get Disk Free Space
05H	Print Character	38H	Return Country-
06H	Direct Console I/O		Dependent Info.
07H	Direct Console Input	39H	Create Sub-Directory
08H	Read Keyboard	3 AH	Remove a Directory
09H	Display String	ЗBН	Change the Current
OAH	Buffered Keyboard		Directory
ODII	Input	3CH	Create a File
OBH OCH	Check Keyboard Status	3DH	Open a File Handle
UCH	Flush Buffer, Read	3EH	Close a File Handle
ODH	Keyboard Disk Reset	3FH	Read From File/Device
OEH	Select Disk	40H	Write to a File/Device
OFH	Open File	41H 42H	Delete a Directory Entry
10H	Close File	42H 43H	Move a File Pointer
11H	Search for First Entry	43H 44H	Change Attributes I/O Control for Devices
12H	Search for Next Entry	44H 45H	Duplicate a File Handle
13H	Delete File	46H	Force a Duplicate of a
14H	Seguential Read	4011	Handle
15H	Sequential Write	47H	Return Name of Current
16H	Create File		Directory
17H	Rename File	48H	Allocate Memory
19H	Current Disk	49H	Free Allocated Memory
1 AH	Set Disk Transfer	4AH	Modify Allocated
	Address		Memory Blocks
21H	Random Read	4BH	Load and Execute a
22H	Random Write		Program (EXEC)
23H	File Size	4CH	Terminate a Process
24H	Set Relative Record	4DH	Retrieve the Return
25H	Set Vector		Code of a Child
27H	Random Block Read	4EH	Find Match File
28H	Random Block Write	4FH	Step Through a Di-
29H	Parse File Name		rectory Matching Files
2AH	Get Date	54H	Return Current Setting
2BH	Set Date		of Verify
2CH	Get Time	56H	Move a Directory Entry
2DH	Set Time	57H	Get/Set Date/Time of
2EH	Set/Reset Verify Flag		File
2FH	Get Disk Transfer		
	Address		

Function Name	Number	Function Name	Number
Allocate Memory	48H	Modify Allocated	
Auxiliary Input	03H	Memory Blocks	4AH
Auxiliary Output	04H	Move a Directory Entry	56H
Buffered Keyboard		Move a File Pointer	42H
Input	OAH	Open a File Handle	3DH
Change Attributes	43H	Open File	OFH
Change the Current		Parse File Name	29H
Directory	ЗBН	Print Character	05H
Check Keyboard Status	OBH	Random Block Read	27H
Close a File Handle	3EH	Random Block Write	28H
Close File	10H	Random Read	21H
CTRL C Check	33H	Random Write	22H
Create a File	3CH	Read From File/Device	ЗFН
Create File	16H	Read Keyboard	08H
Create Sub-Directory	39H	Read Keyboard and	
Current Disk	19H	Echo	OlH
Delete a Directory Entry	41H	Remove a Directory	ЗĂН
Delete File	13 H	Rename File	17H
Direct Console Input	07H	Retrieve the Return	
Direct Console I/O	06H	Code of a Child	4DH
Disk Reset	ODH	Return Current Setting	
Display Character	02H	of Verify	54H
Display String	09H	Return Country-	
Duplicate a File Handle	45H	Dependent Info.	38H
File Size	23H	Return Name of Current	
Find Match File	4EH	Directory	47H
Flush Buffer, Read		Search for First Entry	11H
Keyboard	OCH	Search for Next Entry	12H
Force a Duplicate of a		Select Disk	OEH
Handle	46H	Sequential Read	14H
Free Allocated Memory	49H	Sequential Write	15H
Get Date	2AH	Set Date	2BH
Get Disk Free Space	36H	Set Disk Transfer	
Get Disk Transfer		Address	1AH
Address	2FH	Set Relative Record	24H
Get DOS Version		Set Time	2DH
Number	30H	Set Vector	25H
Get Interrupt Vector	35H	Set/Reset Verify Flag	2EH
Get Time	2CH	Step Through a Di-	AFT
Get/Set Date/Time of		rectory Matching	4FH
File	57H	Terminate a Process	4CH
I/O Control for Devices	44H	Terminate Program	00H
Keep Process	31H	Write to a File/Device	40H
Load and Execute a	4557		
Program (EXEC)	4BH		

Interrupts Interrupts Interrupt Interrupt (in Numerical (Hex) (Decimal) Description Order) **Program Terminate** 20H 32 33 21H **Function Request** 22H 34 Terminate Address <CTRL C>Exit Address 23H 35 24H Fatal Error Abort 36 Address 37 Absolute Disk Read 25HAbsolute Disk Write 26H 38 27H 39 Terminate But Stay Resident RESERVED - DO NOT 28-40H 40-64 USE

Interrupts in Alphabetical	l Description	Interrupt in Hex	Interrupt in Dec
	Absolute Disk Read	25H	37
	Absolute Disk Write <ctrl c=""> Exit Address</ctrl>	26H 23H	$\frac{38}{35}$
	Fatal Error Abort	2011	00
	Address	$24 \mathrm{H}$	36
	Function Request	$21\mathrm{H}$	33
	Program Terminate RESERVED — DO NOT	20H	32
	USE	28-40H	40-64
	Terminate Address Terminate But Stay	22H	34
	Resident	27H	39

Overview

System Calls are procedures used to interface with I/O or to manage memory. They can be accessed from utility programs written in assembly language, and from some high level languages. Their use frees the programmer from having to perform primitive functions, and makes it easier to write machine-independent programs.

MS-DOS provides two types of system calls: interrupts and function requests. This chapter describes the environments from which these routines can be called, how to call them, and the processing performed by each.

Programming Considerations

	System calls can be invoked from Assembly Language, from GW BASIC, or from high-level languages like PASCAL and FORTRAN. This section describes the techniques for invoking calls and for returning control to MS-DOS.
Calling from Assembly Language	The system calls can be invoked from Assembly Language simply by moving any required data into registers and issuing an interrupt. Some of the calls destroy registers, so you may have to save registers before using a system call.
Calling from GW BASIC	The BLOAD and BSAVE commands are used for loading and saving machine language pro- grams. These are then called, using the CALL statement.
	The USR function calls an indicated machine language subroutine. The starting address of the subroutine must first be specified in a DEF USR statement.

Interrupts

MS-DOS reserves interrupts 20H through 3FH for its own use. The table of interrupt routine addresses (vectors) is maintained in locations 80H-FCH. User programs should only issue Interrupts 20H, 21H, 25H, 26H, and 27H. (Functions Requests 4CH and 31H are the preferred method for Interrupts 20H and 27H for versions of MS-DOS that are 2.0 and higher.

Interrupts 22H, 23H, and 24H are not interrupts that can be issued by user programs; they are simply locations where a segment and offset address are stored. For a discussion, see the section on Address Interrupts in this chapter.

Requirements Most of the MS-DOS function calls require input to be passed to them in registers. After setting the proper register values, the function may be invoked in one of the following ways:

- Place the function number in AH and execute a long call to offset 50H in your Program Segment Prefix. Note that programs using this method will not operate correctly on versions of MS-DOS that are lower than 2.0.
- Place the function number in AH and issue Interrupt 21H. All of the examples in this chapter use this method.
- An additional method exists for programs that were written with different calling conventions. This method should be avoided for all new programs. The function number is placed in the CL register and other registers are set according to the function specification. Then, an intrasegment call is made to location 5 in the current code segment. That location contains a long call to the MS-DOS function dispatcher. Register AX is always destroyed if this method is used; otherwise, it is the same as normal function calls. Note that this method is valid only for Function Requests 00H through 024H.

This chapter provides the following type of information for each DOS interrupt and function call:

- a description of the register contents required before the system call
- a description of the register contents after the system call
- a description of the processing performed
- an example of its use.
- RegistersWhen MS-DOS takes control after a function
call, it switches to an internal stack. Registers
not used to return information (except AX) are
preserved. The calling program's stack must be
large enough to accommodate the interrupt sys-
tem at least 128 bytes in addition to other
needs.
- Note The macro definitions and extended example for MS-DOS system calls 00H through 2EH can be found at the end of this chapter.

System Call Descriptions

Interrupts	The following are not true interrupts but rather storage locations for a segment and offset address:
•	Terminate Address (Interrupt 22H) CTRL C Exit Address (Interrupt 23H) Fatal Error Abort Address (Interrupt 24H)
	The interrupts are issued by MS-DOS under the specified circumstance. You can change any of these addresses with Function Request 25H (Set Vector) if you prefer to write your own interrupt handlers.
Programming Examples	A macro is defined for most system calls, then used in some examples. In addition, a few other macros are defined for use in the examples. The use of macros allows the examples to be more complete programs, rather than isolated uses of the system calls. All macro definitions are listed at the end of the chapter.
	The examples are not intended to represent good programming practice. In particular, error check- ing and good human interface design have been sacrificed to conserve space. You may, however, find the macros a convenient way to include sys- tem calls in your assembly language programs.
	A detailed description of each system call follows. They are listed in numeric order; the interrupts are described first, then the function requests.
Note	Unless otherwise stated, all numbers in the sys- tem call descriptions, both text and code, are in hex.

20H Program Terminate

Call	CS Segment address of Pr Prefix	rogram Segment
Return	None	
Remarks	 All open file handles are closed and the disk cache is cleaned. The current process is terminated and control returns to the parent process. This interrupt is almost always used in old .COM files for termination. The CS register must contain the segment address of the Program Segment Prefix before you call this interrupt. The following exit addresses are restored from the Program Segment Prefix: 	
	Exit Address	Offset
	Program Terminate <ctrl c=""> Critical Error</ctrl>	0AH 0EH 12H

All file buffers are flushed to disk.

20H Program Terminate

Note	Close all files that have changed in length before issuing this interrupt. If a changed file is not closed, its length is not recorded correctly in the directory. See Functions 10H and 3EH for a description of the Close File system calls.
	Interrupt 20H is provided for compatibility with versions of MS-DOS prior to 2.0. New programs should use Function Request 4CH, Terminate a Process.
Macro	terminate macro int 20H endm
Example	;CS must be equal to PSP values given at program ;start ;(ES and DS values) INT 20H ;There is no return from this interrupt

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21H Function Request

Call	AH Function number Other registers as specified in individual function
Return	As specified in individual function
Remarks	The AH register must contain the number of the system function. See the following section on Function Requests, in this chapter, for a descrip- tion of the MS-DOS system functions.
Note	No macro is defined for this interrupt, because all function request descriptions in this chapter that define a macro include Interrupt 21H.
Example	To call the Get Time function: mov ah,2CH ;Get Time is Function 2CH int 21H ;THIS INTERRUPT

22H Terminate Address

When a program terminates, control transfers to the address at offset 0AH of the Program Segment Prefix. This address is copied into the Program Segment Prefix, from the Interrupt 22H vector, when the segment is created. Interrupt 22H, then, is just a storage location for an address rather than a true interrupt.

23H <CTRL C> Exit Address

If the user types **CTRL C** during keyboard input or display output, control transfers to the INT 23H vector in the interrupt table. This address is copied into the Program Segment Prefix, from the Interrupt 23H vector, when the segment is created.

If the **CTRL C** routine preserves all registers, it can end with an IRET instruction (return from interrupt) to continue program execution. When the interrupt occurs, all registers are set to the value they had when the original call to MS-DOS was made. There are no restrictions on what a **CTRL C** handler can do — including MS-DOS function calls — so long as the registers are unchanged if IRET is used.

If Function 09H or 0AH (Display String or Buffered Keyboard Input) is interrupted by **CTRL C**, the three-byte sequence 03H-0DH-0AH (ETX-CR-LF) is sent to the display and the function resumes at the beginning of the next line.

If the program creates a new segment and loads a second program that changes the **CTRL C** address, termination of the second program restores the **CTRL C** address to its value before execution of the second program.

Like INT 22H, this is really not a true interrupt, but a storage location.

24H Fatal Error Abort Address

Call	If a fatal disk error occurs during execution of one of the disk I/O function calls, control transfers to the INT 24H vector in the vector table. This address is copied into the Program Segment Prefix, from the Interrupt 24H vector, when the segment is created.
Return	BP:SI contains the address of a Device Header Control Block from which additional informa- tion can be retrieved.
Note	Interrupt 24H is not issued if the failure occurs during execution of Interrupt 25H (Absolute Disk Read) or Interrupt 26H (Absolute Disk Write). These errors are usually handled by the MS-DOS error routine in COMMAND.COM that retries the disk operation, then gives the user the choice of aborting, retrying the operation, or ignoring the error. The following topics give you the information you need about interpreting the error codes, managing the registers and stack, and controlling the system's response to the error in order to write your own error-handling routines.
Error Codes	When an error-handling program gains control from Interrupt 24H, the AX and DI registers can contain codes that describe the error. If Bit 7 of AH is 1, the error is either a bad image of the File Allocation Table or an error which has oc- curred on a character device. The device header passed in BP:SI can be examined to determine which case exists. If the attribute byte high order bit indicates a block device, then the error was a bad FAT. Otherwise, the error is on a character device.

The following are error codes for Interrupt 24H:

Error Code	Description
0	Attempt to write on write-
	protected disk
1	Unknown unit
2	Drive not ready
3	Unknown command
4	Data error
5	Bad request structure length
6	Seek error
7	Unknown media type
8	Sector not found
9	Printer out of paper
Α	Write fault
В	Read fault
С	General failure

The user stack will be in effect (the first item described below is at the top of the stack), and will contain the following from top to bottom:

IP CS	MS-DOS registers from issuing INT 24H
FLAGS	
AX	User registers at time of original
BX	INT 21H request
CX	
DX	
SI	
DI	
BP	
DS	
ES	
IP	From the original INT 21H
CS	from the user to MS-DOS
FLAGS	

The registers are set such that if an IRET is executed, MS-DOS will respond according to (AL) as follows:

	 (AL) = 0 ignore the error = 1 retry the operation = 2 terminate the program via INT 23H
Note •	Before giving this routine control for disk errors, MS-DOS performs five retries.
•	For disk errors, this exit is taken only for errors occurring during an Interrupt 21H. It is not used for errors during Interrupts 25H or 26H.
•	This routine is entered in a disabled state.
•	The SS,SP,DS,ES,BX,CX, and DX registers must be preserved.
•	The interrupt handler should refrain from using MS-DOS function calls. If necessary, it may use calls 01H through 0CH. Use of any other call will destroy the MS-DOS stack and will leave MS-DOS in an unpredictable state.
•	The interrupt handler must not change the con- tents of the device header.
•	If the interrupt handler will handle errors rather than returning to MS-DOS, it should restore the application program's registers from the stack, remove all but the last three words on the stack, then issue an IRET. This will return to the pro- gram immediately after the INT 21H that expe- rienced the error. Note that if this is done, MS- DOS will be in an unstable state until a function call higher than 0CH is issued.

25H Absolute Disk Read

Call	AL Drive number (0 = A, 1 = B, etc.) DS:BX Disk Transfer Address CX Number of sectors DX Beginning relative sector
Return	Flags CF = 0 if successful = 1 if not successful AL Error code if CF = 1
Remarks	This interrupt transfers control to the MS-DOS BIOS. The number of sectors specified in CX is read from the disk to the Disk Transfer Address. Its requirements and processing are identical to Interrupt 26H, except data is read rather than written.

:

25H Absolute Disk Read

Note	All registers except the segment registers are destroyed by this call. Be sure to save any regis- ters your program uses before issuing the interrupt.			
	The system pushes the flags at the time of the call; they are still there upon return. (This is necessary because data is passed back in the flags). Be sure to pop the stack upon return to restore your stack pointer at the point of invocation.			
	If the disk operation was successful, the Carry Flag (CF) is 0. If the disk operation was not suc- cessful, CF is 1 and AL contains the MS-DOS error code (see Interrupt 24H earlier in this sec- tion for the codes and their meaning).			
Macro	abs_disk_read macro disk,buffer,num_sectors, start mov al,disk mov bx,offset buffer mov cx,num_sectors mov dx,start int 25H endm			

The following program copies the contents of a single-sided disk in drive A: to the disk in drive B:. It uses a buffer of 32K bytes:

prompt start buffer		``Any key to sta 0	arget in B'',13,10 rt. \$'' lup (?)) ;64 sectors
int_25 H :			see Function 09H see Function 08H
mov	7 CX,	5	;copy 5 groups of ;64 sectors
copy: pus	h cx		;save the loop ;counter
abs.	_disk	_read 0,buffer,	,
abs.	_disk	write 1, buffer,	64,start ;see INT ;26H
add	start	,64	;do the next 64 ;sectors
рор	CX		;restore the loop ;counter
loop	cop	у	• •

26H Absolute Disk Write

Call	AL Drive number (0 = A, 1 = B, etc.) DS:BX Disk Transfer Address CX Number of sectors DX Beginning relative sector
Return	FLAGS CF = 0 if successful = 1 if not successful AL Error code if CF = 1
Remarks	This interrupt transfers control to the MS-DOS BIOS. The number of sectors specified in CX is written from the Disk Transfer Address to the disk. Its requirements and processing are identi- cal to Interrupt 25H, except data is written to the disk rather than read from it.

26H Absolute Disk Write

Note	All registers except the segment registers are destroyed by this call. Be sure to save any regis ters your program uses before issuing the interrupt.			
	The system pushes the flags at the time of the call; they are still there upon return. (This is necessary because data is passed back in the flags). Be sure to pop the stack upon return to restore your stack pointer at the point of invocation.			
	If the disk operation was successful, the Carry Flag (CF) is 0. If the disk operation was not suc- cessful, CF is 1 and AL contains the MS-DOS error code (see Interrupt 24H earlier in this sec- tion for the codes and their meaning).			
Macro	abs_disk_write macro disk,buffer,num_sectors, start mov al,disk mov bx,offset buffer mov cx,num_sectors mov dx,start int 26H endm			

26H Absolute Disk Write

Example	The following program copies the conten single-sided disk in drive A: to the disk ir B:, verifying each write. It uses a buffer o bytes:			
	off on	equ 0 equ 1		
	prompt start	db ''Source in A, target in B'', 13,10 db ''Any key to start. \$'' dw 0		
	buffer	db 64 dup (512 dup (?))	; 64 sectors	
	int_26H:	display prompt read_kbd verify on mov cx,5	;see Function 09H ;see Function 08H ;see Function 2EH ;copy 5 groups of ;64 sectors	
	сору:	push cx	;save the loop ;counter	
		abs_disk_read 0,buffer,	64,start ;see INT ;25H	
		abs_disk_write 1,buffer,	64,start ;THIS ;INTERRUPT	
		add start,64	;do the next 64 ;sectors	
		рор сх	;restore the loop ;counter	
		loop copy verify off	;see Function 2EH	

27H Terminate But Stay Resident

Call	CCS:DX First byte following last byte of code		
Return	None		
Remarks	The Terminate But Stay Resident call is used to make a piece of code remain resident in the sys- tem after its termination. Typically, this call is used in .COM files to allow some device-specific interrupt handler to remain resident to process asynchronous interrupts.		
	DX must contain the number of bytes in the CS segment to be reserved. When Interrupt 27H is executed, the program terminates but is treated as an extension of MS-DOS; it remains resident and is not overlaid by other programs when it terminates.		
	If an executable file whose extension is .COM or .EXE ends with this interrupt, it becomes a resident operating system command.		
	This interrupt is provided for compatibility with versions of MS-DOS prior to 2.0. New programs should use Function 31H, Keep Process.		
Macro	stay_resident macro last_instruc mov dx,offset last_instruc inc dx int 27H endm		

27H Terminate But Stay Resident

Example	;CS must be equal to PSP values given at program ;start ;(ES and DS values) ;the variable Last Address must be equal ;to the offset of the last byte in the
	;program. mov DX,LastAddress inc dx int 27H ;There is no return from this interrupt

00H Terminate Program

Call	AH = 00H CS Segment address of Program Segment Prefix			
Return	None			
Remarks	Function 00H is called by Interrupt 20H; it per- forms the same processing.			
	The CS register must contain the segment address of the Program Segment Prefix before you call this interrupt.			
	The following exit addresses are restored from the specified offsets in the Program Segment Prefix:			
	Program terminateOAH <ctrl c="">OEHCritical error12H</ctrl>			
	All file buffers are flushed to disk.			
Warning	Close all files that have changed in length be- fore calling this function. If a changed file is not closed, its length is not recorded correctly in the directory. See Function 10H for a description of the Close File system call.			

00H Terminate Program

Macroterminate_program macro
xor ah,ah
int 21H
endmExample;CS must be equal to PSP values given at program start
;(ES and DS values)
mov ah,0
int 21H
;There are no returns from this interrupt

01H Read Keyboard and Echo

Call	AH = 01H			
Return	AL Character typed			
Remarks	Function 01H waits for a character to be typed at the keyboard, then echoes the character to the display and returns it in AL. If the character is CTRL C , Interrupt 23H is executed.			
Macro	read_kdb_and_echo macro mov ah,01H int 21H endm			
Example The following program both displays and prints characters as they are typed. If CR is pressed, the program sends Line Feed-Carriage Return to both the display and the printer:				
func_01	.H: read_kbd_and_ print_char cmp jne print_char display_char jmp	al al,0DH func_01H 10 10	;THIS FUNCTION ;see Function 05H ;is it a CR? ;no, print it ;see Function 05H ;see Function 02H ;get another character	

02H Display Character

Call	AH = 02H DL Character to be displayed				
Return	None				
Remarks	If CTRL C is typed, Interrupt 23H is issued.				
Macro	display_char macro character mov dl,character mov ah,02H int 21H endm				
Example	The following program converts lowercase char- acters to uppercase before displaying them:				
	func_02H: uppercase:	read_kbd cmp al,``a'' jl uppercase cmp al,``z'' jg uppercase sub al,20H display_char al jmp func_02H	;see FUNCTION 08H ;don't convert ;don't convert ;convert to ASCII code ;for uppercase ;THIS FUNCTION ;get another character		

03H Auxiliary Input

Call	AH = 0	AH = 03H			
Return	AL Char	AL Character from auxiliary device			
Remarks	auxilian charact This sy code.	 Function 03H waits for a character from the auxiliary input device, then returns the character in AL. This system call does not return a status or error code. If a CTRL C has been typed at console input, 			
		pt 23H is		a at console input,	
Macro	aux_i mov int end	21H			
Example	are rece printing	The following program prints characters as they are received from the auxiliary device. It stops printing when an end-of-file character (ASCII 26, or CTRL Z) is received:			
	cı je p:	rint_char	al, 1 AH continue al func_03 H	;THIS FUNCTION ;end of file? ;yes, all done ;see Function 05H ;get another character	
	continue: .	•			

04H Auxiliary Output

Call		AH = 04H DL Character for auxiliary device			
Retu	rn	None			
Remarks		This system call does not return a status or error code.			
		If a CTRL C has been typed at console input, Interrupt 23H is issued.			
Macro		aux_output macro character mov dl,character mov ah,04H int 21H endm			
Example		The following program gets a series of strings of up to 80 bytes from the keyboard, sending each to the auxiliary device. It stops when a null string (CR only) is typed:			
	string	db	82 dup(?)	;see Function OAH	
	func_04H:	get_stri cmp je xor mov mov	ng 80,string string[1],0 continue ch,ch c1, byte ptr string[1] bx,0	;see Function OAH ;null string? ;yes, all done ;zero high byte ;get string length ;set index to O	
	send_it:		bx,0 tput string[bx+2] bx send_it func_04H	;THIS FUNCTION ;bump index ;send another character ;get another string	
	continue:	,		, <u>, ,</u>	

05H Print Character

Call	AH = 05H DL Character for printer		
Return	None		
Remarks	If CTRL C has been typed at console input, Interrupt 23H is issued.		
Macro	print_char macro character mov dl,character mov ah,05H int 21H endm		

05H Print Character

Example		The following program prints a walking test pat- tern on the printer. It stops if CTRL C is pressed.			
	line_num	db	0		
	func_05 H :	mov add	bl,33 bl,line_num	;first printable ASCII ;character (!) ;to offset next character	
	print_it:	mov print_cha inc cmp	cx,80	;loop counter for line ;THIS FUNCTION ;move to next ASCII character ;last printable ASCII ;character (~)	
		jle mov	no_reset bl,33	;not there yet ;start over with (!)	
	no_reset:	loop print_cha print_cha inc cmp jle mov jmp	ar 10 line_num	;print another character ;carriage return ;line feed ;to offset 1st char. of line ;end of cycle? ;nope, not yet ;reset char offset ;continue	

06H Direct Console I/O

Call	AH = 06H DL See Text	
Return	AL If DL = FFH before call If Zero flag not set: Character from keyboard If Zero flag set: No character input	
Remarks	 Processing depends on the value in DL when the function is called: DL is FFH. If a character has been typed at the keyboard, it is returned in AL and the Zero flag is 0; if a character has not been typed, the Zero flag is 1. DL is not FFH. The character in DL is displayed. 	
Macro	This function does not check for CTRL C. dir_console_io macro switch mov dl,switch mov ah,06H int 21H endm	

06H Direct Console I/O

Example	The following program acts as a stopwatch. When a character is typed, it sets the system clock to zero and begins to continuously display the time. When a second character is typed the system stops updating the time display.		
time ten	db``00:00:00.00'',13,``\$'' db 10		
func_06H:	dir_console_io OFFH jz func_06H set_time 0.0.0.0	;THIS FUNCTION ;wait for keystroke ;see Function 2DH	
read_clock:	-,-,-,-	;see Function 2DH ;see Function 2CH ;see end of chapter ;see end of chapter ;see end of chapter ;see end of chapter ;see Function 09H ;THIS FUNCTION ;no char, keep updating	
continue:			

07H Direct Console Input

Call	AH = 07H		
Return	A	L Character from	keyboard
Remarks	This function does not echo the character or check for CTRL C. (For a keyboard input func- tion that echoes or checks for CTRL C , see Functions 01H or 08H.)		
Macro	dir_console_input macro mov ah,07H int 21H endm		
Example	The following program fragment prompts for a password (8 characters maximum) and places the characters into a string without echoing them:		
password prompt	db db	8 dup(?) ''Password: \$''	;see Function 09H for ;explanation of \$
func_07H:	mov	ay prompt cx,8 bx,bx	;see Function 09H ;maximum length of password ;so BL can be used as index
get_pass: continue:	dir_c cmp je	onsole_input al,ODH continue password[bx],al bx	;THIS FUNCTION ;was it a CR? ;yes, all done ;no, put character in string ;bump index ;get another character ;BX has length of password
·····			

08H Read Keyboard

· · · · · · · · · · · · · · · · · · ·			
Call	AH = 08H		
Return	AL Character from keyboard		
Remarks	If CTRL C is pressed, Interrupt 23H is executed. This function does not echo the character. (For a keyboard input function that echoes the charac- ter or does not check for CTRL C , see Functions 01H or 07H.)		
Macro	read_kbd macro mov_ah,08H int_21H endm		
Example	The following program fragment prompts for a password (8 characters maximum) and places the characters into a string without echoing them:		
password prompt	db 8 dup(?) db ''Password: \$''	;see Function 09H ;for explanation of \$	
func_08H:	display prompt mov cx,8 xor bx,bx	;see Function 09H ;maximum length of password ;BL can be an index	
get_pass: continue:	read_kbd; cmp al,ODH je continue mov password[bx],al inc bx loop get_pass	;THIS FUNCTION ;was it a CR? ;yes, all done	
continue.	•		

09H Display String

Call	DS:E	= 09H)X ring to be displayed	
Return	None	9	
Remarks	addr	nust contain the offset (fr ess in DS) of a string that string is displayed (the \$ i	ends with "\$".
Macro		play macro string mov dx,offset string mov ah,09H int 21H endm	
Example		following program display code of the key that is typ	
	table sixteen result	db ``0123456789ABCDE db 16 db ``-00H'',13,10,``\$''	;see text for ;explanation of \$
	func_09H:	read_kbd_and_echo convert al,sixteen,result[1] display result jmp_func_09H	;see Function 01H ;see end of chapter ;THIS FUNCTION ;do it again

0AH Buffered Keyboard Input

Call	AH = 0A DS:DX Input	AH buffer
Return	None	
Remarks		t contain the offset (from the segment in DS) of an input buffer of the g form:
	Byte	Contents
	1	Maximum number of characters in buffer, including the CR (you must set this value).
	2	Actual number of characters typed, not counting the CR (the function sets this value).
	3-n	Buffer; must be at least as long as the number in byte 1.
	Charact placed i until CI than the are igno display edited a	action waits for characters to be typed. There are read from the keyboard and in the buffer beginning at the third byte R is pressed. If the buffer fills to one less e maximum, additional characters typed ored and ASCII 7 (BEL) is sent to the until CR is pressed. The string can be s it is being entered. If CTRL C is typed, of 23H is issued.
		ond byte of the buffer is set to the of characters entered (not counting the

n	mov mov int endm The followi num) strin	ing program gets a g from the keyboar	rd and fills a 24-
l	ine by 80-c	haracter screen wi	th it:
buffer max_length chars_entered string strings_per_line	label db db db	byte ? ? 17 dup (?) 0	;maximum length ;number of chars. ;16 chars + CR ;how many strings
			;fit on line
crlf	db	13,10,``\$''	,
func_OAH:	get_string xor mov mov cbw div	17, buffer bx, bx bl, chars_entered buffer[bx+2], ``\$'' al, 50H chars_entered	;THIS FUNCTION ;so byte can be ;used as index ;get string length ;see Function 09H ;columns per line ;times string fits
	xor mov mov	ah,ah strings_per_line,ax cx,24	;on line ;clear remainder ;save col. counter ;row counter
display_screen:	push c x		;save it
display_line:	mov display loop display pop loop	cx,strings_per_line string display_line crlf cx display_screen	
	- 1-		,

0BH Check Keyboard Status

Call	AH =	AH = 0BH			
Return		FH = characters in type = no characters in type			
Remarks	ahea retui	Checks whether there are characters in the type ahead buffer. If so, AL returns FFH; if not, AL returns 0. If CTRL C is in the buffer, Interrupt 23H is executed.			
Macro	ch	leck_kbd_status macro mov ah,OBH int 21H endm			
Example		following program fra lays the time until any			
tim ten	-	db ''00:00:00.00'',13, db 10	10,``\$''		
fun	.c_OBH:	get_time convert ch,ten,time convert ch,ten,time[3] convert dh,ten,time[6] convert dl,ten,time[9] display time check_kbd_status cmp al,OFFH je all_done jmp func_OBH	;see Function 2CH ;see end of chapter ;see end of chapter ;see end of chapter ;see end of chapter ;see Function 09H ;THIS FUNCTION ;has a key been typed ;yes, go home ;no, keep displaying ;time		

all_done:

0CH Flush Buffer, Read Keyboard

Call	AH = 0CH AL 1, 6, 7, 8, or 0AH = The corresponding function is called. Any other value = return from function.
Return	AL 0 = Type-ahead buffer was flushed; no other processing performed.
Remarks	 The keyboard type-ahead buffer is emptied. Further processing depends on the value in AL when the function is called: 1, 6, 7, 8, or A: The corresponding MS-DOS function is executed. Any other value:
	No further processing; AL returns 0.
Macro	flush_and_read_kbd macro switch mov al,switch mov ah,OCH int 21H endm

0CH Flush Buffer, Read Keyboard

Example	characters as t	hey are typed ands Carriage	n displays and prints I. If CR is pressed, e Return-Line Feed to inter.
func_OCH:	flush_and_read print_char cmp jne print_char display_char print_char display_char jmp	d_kbd 1 al al,ODH func_OCH 10 13 13 func_OCH	;THIS FUNCTION ;see Function 05H ;is it a CR? ;no, print it ;see Function 05H ;see Function 02H ;see Function 05H ;see Function 02H ;see Function 02H ;get another character

0DH Disk Reset

Call	AH = 0DH
Return	None
Remarks	Function 0DH is used to ensure that the internal buffer cache matches the disks in the drives. If buffers have been modified, but not yet written to disk, this function writes them out and marks all buffers in the internal cache as free. Function 0DH flushes (frees) all file buffers. It does not update directory entries; you must close files that have changed to update their directory entries (see Function 10H, Close File). This func- tion need not be called before a disk change if all files that changed were closed. It is generally used to force a known state of the system; CTRL C interrupt handlers should call this function.
Macro	disk_reset macro disk mov ah,ODH int 21H endm
Example	mov ah,0DH int 21H ;There are no errors returned by this call.

0EH Select Disk

Call	AH = 0EH DL Drive num (0 = A:, 1 =		
Return	AL Number of	logical drives	
Remarks	-	e default disk. T	= A:, 1 = B:, etc.) is The number of
Macro	select_disk mov dl,c mov ah, int 211 endm	disk[-65] ;ASCI OEH	I offset
Example		g program fragm rently selected in	nent selects the n a 2-drive system:
	;	current_disk cmp al,00H je select_b select_disk ``A'' jmp continue	;see Function 19H ;drive A: selected? ;yes, select B ;THIS FUNCTION
		select_disk ``B''	;THIS FUNCTION

0FH Open File

Call		AH = 0FH DS:DX Unopened FCB
Return		AL 0 = Directory entry found FFH = No directory entry found
Remarks		DX must contain the offset (from the segment address in DS) of an unopened File Control Block (FCB). The disk directory is searched for the named file.
		If a directory entry for the file is found, AL returns 0 and the FCB is filled as follows:
	•	If the drive code was 0 (default disk), it is changed to the actual disk used $(1 = A; 2 = B;$ etc.). This lets you change the default disk with- out interfering with subsequent operations on this file.
	•	The Current Block field (offset 0CH) is set to zero.
	•	The Record Size (offset 0EH) is set to the system default of 128.
	•	The File Size (offset 10H), Date of Last Write (offset 14H), and Time of Last Write (offset 16H) are set from the directory entry.
		Before performing a sequential disk operation on the file, you must set the Current Record field (offset 20H). Before performing a random disk operation on the file, you must set the Relative Record field (offset 21H). If the default record size (128 bytes) is not correct, set it to the correct length.

0FH Open File

		f a dir eturns			file is not found, AL
Macro		mo mo int	ov ah,	offset fcb OFH	
Example] t	FEXTI If a pai the rou charac	FILE. rtial re tine th ters u	ASC that is or ecord is in the nat prints the	nts the file named n the disk in drive B:. buffer at end-of-file, partial record prints ers an end-of-file mark
	fcb		db	2, "TEXTFILEA	SC''
	buffer		db db	25 dup (?) 128 dup (?)	
			•		
	func_OF	H:	set_dt open f	a buffer Icb	;see Function 1AH ;THIS FUNCTION
	read_lin	e:	cmp je cmp jg	all_done al,00H check_more	;see Function 14H ;end of file? ;yes, go home ;more to come? ;no, check for partial ;record
	print_it:		mov xor print_ inc loop jmp	cx,128 si,si .char buffer[si] si print_it read_line	;yes, print the buffer ;set index to 0 ;see Function 05H ;bump index ;print next character ;read another record
	check_n	nore:	cmp jne	al,03H all_done	;part. record to print? ;no

find_eof:	mov xor cmp je print_	cx,128 si,si buffer[si],26 all_done char buffer[si]	;yes, print it ;set index to 0 ;end-of-file mark? ;yes ;see Function 05H
	inc	si	;bump index to next ;character
all_done:	loop close	find_eof fcb	;see Function 10H

10H Close File

Call	AH = 10H DS:DX Opened FCB
Return	AL 0 = Directory entry found FFH = No directory entry found
Remarks	DX must contain the offset (to the segment address in DS) of an opened FCB. The disk directory is searched for the file named in the FCB. This function must be called after a file is changed to update the directory entry. If a directory entry for the file is found, the entry
	is compared with the corresponding entries in the FCB. The directory entry is updated, if necessary, to match the FCB, and AL returns 0.
	If a directory entry for the file is not found, AL returns FFH.
Macro	close macro fcb mov dx,offset fcb mov ah,10H int 21H endm

Example	The following program checks the first byte of the file named MOD1.BAS in drive B: to see if it is FFH, and prints a message if it is:		
	message fcb	db "Not saved in ASCII format",13,10,"\$" db 2,"MOD1 BAS" db 25 dup (?)	
	buffer	db 128 dup (?)	
	func_10H:	set_dta buffer ;see Function 1AH open fcb ;see Function 0FH read_seq fcb ;see Function 14H cmp buffer,OFFH ;is first byte FFH? jne all_done ;no display message ;see Function 09H	
	all_done	display message ;see Function 09H close fcb ;THIS FUNCTION	

11H Search for First Entry

Call	AH = 11H DS:DX Unopened FCB
Return	AL 0 = Directory entry found FFH = No directory entry found
Remarks	DX must contain the offset (from the segment address in DS) of an unopened FCB. The disk directory is searched for the first matching name. The name can have the ? wild card char- acter to match any character. To search for hid- den or system files, DX must point to the first byte of the extended FCB prefix.
	If a directory entry for the filename in the FCB is found, AL returns 0 and an unopened FCB of the same type (normal or extended) is created at the Disk Transfer Address.
	If a directory entry for the filename in the FCB is not found, AL returns FFH.
Note	If an extended FCB is used, the following search pattern is used:
•	If the FCB attribute is zero, only normal file entries are found. Entries for volume label, sub- directories, hidden, and system files will not be returned.

•	If the attribute field is set for hidden or system files, or directory entries, it is to be considered as an inclusive search. All normal file entries plus all entries matching the specified attributes are returned. To look at all directory entries except the volume label, the attribute byte may be set to hidden + system + directory (all 3 bits on). If the attribute field is set for the volume label, it		
	is consider	red an exclusive search, and only the bel entry is returned.	ŗ
Macro	mov mov	first macro fcb dx,offset fcb ah,11H 21H	
Example		ving program verifies the existence of a d REPORT. ASM on the disk in drive	a
	yes	db "FILE EXISTS.\$"	
	no	db "FILE DOES NOT EXIST.\$"	
	fcb	db 2,"REPORT ASM" db 25 dup (?)	
	buffer	db 128 dup (?)	
	crlf	db 13,10 ``\$''	
	func_11H:	set_dta buffer ;see Function 1AH search_first fcb ;THIS FUNCTION cmp al,OFFH ;directory entry found je not_there ;no display yes ;see Function 09H jmp continue	?
	not_there: continue:	display no ;see Function 09H display crlf ;see Function 09H	
	continue.	see Function OPH	

•

12H Search for Next Entry

Call	AH = 12H DS:DX Unopened FCB
Return	AL 0 = Directory entry found FFH = No directory entry found
Remarks	DX must contain the offset (from the segment address in DS) of an FCB previously specified in a call to Function 11H (Search for First Entry). Function 12H is used after Function 11H to find additional directory entries that match a file- name that contains wild card characters. The disk directory is searched for the next matching name.
	If a directory entry for the filename in the FCB is found, AL returns 0 and an unopened FCB of the same type (normal or extended) is created at the Disk Transfer Address.
	If a directory entry for the filename in the FCB is not found, AL returns FFH.
Macro	search_next macro fcb mov dx,offset fcb mov ah,12H int 21H endm

Example	The following program displays the number of files on the disk in drive B:		
message files ten fcb buffer	<pre>db "No files",10,13,"\$" db 0 db 10 db 2,"??????????" db 25dup(?) db 128 dup(?) .</pre>		
func_12H: search_dir:	set_dta buffer search_first fcb cmp al,OFFH je all_done inc files search_next fcb	;see Function 1AH ;see Function 11H ;directory entry found? ;no, no files on disk ;yes, increment file ;counter ;THIS FUNCTION	
done:	cmp al,OFFH je done inc files jmp search_dir convert files,ten,message	;directory entry found? ;no ;yes, increment file ;counter ;check again ;see end of chapter	
all_done:	display message	;see Function 09H	

13H Delete File

Call	AH = 13H DS:DX Unopened FCB
Return	AL 0 = Directory entry found FFH = No directory entry found
Remarks	DX must contain the offset (from the segment address in DS) of an unopened FCB. The direc- tory is searched for a matching filename. The filename in the FCB can contain the ? wild card character to match any character.
	If a matching directory entry is found, it is deleted from the directory. If the ? wild card character is used in the filename, all matching directory entries are deleted. AL returns 0.
	If no matching directory entry is found, AL returns FFH.
Macro	delete macro fcb mov dx,offset fcb mov ah, 13H int 21H endm

Example			ach file on the disk in vritten before June 30,
year month day files ten message	dw db db db db	1984 6 30 0 10 ''NO FILES DELI	ETED.",13,10,``\$'' ;see Function 09H for
fcb	db db	2,``????????????' 25 dup(?)	;explanation of \$
buffer	db	128 dup (?)	
func_13H		dta buffer ch_first fcb al,OFFH all_done	;see Function 1AH ;see Function 11H ;directory entry found? ;no, no files on disk
compare:	cmp jg cmp jg cmp jge	next	;see end of chapter ;next several lines ;check date in directory ;entry against date ;above & check next file ;if date in directory ;entry isn't earlier. ;THIS FUNCTION ;bump deleted-files ;counter
next:	sear cmp je cmp je	compare	;see Function 12H ;directory entry found? ;yes, check date ;any files deleted? ;no, display NO FILES

13H Delete File

;message. convert files,ten,message ;see end of chapter all_done: display message ;see Function O9H

14H Sequential Read

Call	AH = 14H DS:DX Openeo	
Return	1 = EO 2 = DT	ad completed successfully F A too small F, partial record
Remarks	DX must contain the offset (from the segment address in DS) of an opened FCB. The record pointed to by the current block (offset 0CH) and Current Record (offset 20H) fields is loaded at the Disk Transfer Address, then the Current Record and, if necessary, the Current Block fields are incremented. The record size is set to the value at offset 0EH in the FCB.	
	AL return	ns a code that describes the processing:
	Code	Meaning
	0	Read completed successfully.
	1	End-of-file, no data in the record.
	2	Not enough room at the Disk Transfer Address to read one record; read canceled.
	3	End-of-file; a partial record was read and padded to the record length with zeros.

14H Sequential Read

Macro	read_seq macro fcb mov dx,offset fcl mov ah,14H int 21H endm	b
Example	TEXTFILE.ASC that its function is simila command. If a partia end of file, the routin record displays chart	am displays the file named at is on the disk in drive B:; r to the MS-DOS TYPE al record is in the buffer at the that displays the partial acters until it encounters an CII 26, or CTRL Z):
fcb	db 2, 'TEXTFILEAS db 25 dup (?)	C''
buffer	db 128 dup (?), ``\$''	
func_14H:	set_dta buffer open fcb	;see Function 1AH ;see Function OFH
read_line:	read_seq fcb cmp al,01H je all_done cmp al,00H jg check_more display buffer jmp read_line	;THIS FUNCTION ;end-of-file? ;yes ;more to come? ;no, check for partial record ;see Function 09H ;get another record
check_more:	cmp al,03H jne all_done xor si,si	;partial record in buffer? ;no, go home ;set index to 0
find_eof:	cmp buffer[si],26 je all_done display_char buffer[s inc si	;is character EOF? ;yes, no more to display

14H Sequential Read

;character jmp find_eof ;check next character all_done: close fcb ;see Function 10H

15H Sequential Write

Call	AH = 15H DS:DX Opened	
Return	01H = 1	Write completed successfully Disk full DTA too small
Remarks	DX must contain the offset (from the segment address in DS) of an opened FCB. The record pointed to by Current Block (offset 0CH) and Current Record (offset 20H) fields is written from the Disk Transfer Address, then the fields are incremented as necessary.	
	The record size is set to the value at offset 0EH in the FCB. If the Record Size is less than a sec- tor, the data at the Disk Transfer Address is written to a buffer; the buffer is written to disk when it contains a full sector of data, or the file is closed, or a Reset Disk system call (Function 0DH) is issued.	
	AL return	ns a code that describes the processing:
	Code	Meaning
	0	transfer completed successfully
	1	disk full; write canceled
	2	write canceled; the area beginning at the Disk Transfer Address is too small to hold a record of data without over- flowing or wrapping around a seg- ment boundary.

Macro	write_seq macro mov dx,offs mov ah,15H int 21H endm	et fcb	
Example	DIR.TMP on the disk number	he disk in er (0 = A:,	creates a file named drive B: that contains 1 = B:, etc.) and file- ry entry on the disk:
record_siz	e equ 14		;offset of Record Size ;field in FCB
fcb1 fcb2 buffer	db 2,"DIR db 25 dup (db 2,"????? db 25 dup (db 128 dup	(?) ???????'' ?)	
func_15H:	set_dta search_first f cmp je create mov	al,OFFH all_done fcb1	;see Function 1AH ;see Function 11H ;directory entry found? ;no, no files on disk ;see Function 16H rd_size],12
write_it: all_done:	write_seq search_next cmp je jmp close	fcbl	;set record size to 12 ;THIS FUNCTION ;see Function 12H ;directory entry found?

16H Create File

Call	AH = 16H DS:DX Unopened FCB
Return	AL 00H = Empty directory entry found FFH = No empty entry directory available
Remarks	DX must contain the offset (from the segment address in DS) of an unopened FCB. The direc- tory is searched for an empty entry or an exist- ing entry for the specified filename.
	If an empty directory entry is found, it is initial- ized to a zero-length file, the Open File system call (Function 0FH) is called, and AL returns 0. You can create a hidden file by using an extend- ed FCB with the attribute byte (offset FCB-1) set to 2.
	If an entry is found for the specified filename, all data in the file is released, making a zero-length file, and the Open File system call (Function 0FH) is issued for the filename (in other words, if you try to create a file that already exists, the existing file is erased, and a new, empty file is created).
	If an empty directory entry is not found and there is no entry for the specified filename, AL returns FFH.

Macro	create macro fch mov dx,offse mov ah,16H int 21H endm	et fcb	
Example	DIR.TMP on the disk number	he disk in er (0 = A:,	reates a file named drive B: that contains 1 = B:, etc.) and file- y entry on the disk:
record_siz	e equ 14		;offset of Record Size ;field of FCB
fcbl	db 2,``DIR db 25 dup (
fcb2	db 2,"????? db 25 dup (??????"	
buffer	db 128 dup	(?)	
func_16H:	set_dta search_first cmp je create mov	buffer fcb2 al,OFFH all_done fcb1 fcb1[reco	
write_it:	write_seq search_next cmp je jmp	fcb1 fcb2 al,OFFH all_done write_it	;see Function 15H ;see Function 12H ;directory entry found? ;no, go home ;yes, write the record
all_done:	close	fcbl	;see Function 10H

17H Rename File

Call	AH = 17H DS:DX Modified FCB
Return	AL 00H = Directory entry found FFH = No directory entry found or destination already exists
Remarks	DX must contain the offset (from the segment address in DS) of an FCB with the drive number and filename filled in, followed by a second file- name at offset 11H. The disk directory is search- ed for an entry that matches the first filename, which can contain the ? wild card character.
	If a matching directory entry is found, the file- name in the directory entry is changed to match the second filename in the modified FCB (the two filenames cannot be the same name). If the ? wild card character is used in the second file- name, the corresponding characters in the file- name of the directory entry are not changed. AL returns 0.
	If a matching directory entry is not found or an entry is found for the second filename, AL returns FFH.

Macro rename macro special_fcb mov dx,offset special_fcb mov ah,17H int 21H endm

Example

The following program prompts for the name of a file and a new name, then renames the file:

fcb		37 dup (?)
promptl	db	"Filename: \$"
prompt2	db	``New name: \$''
reply	db	17 dup(?)
crlf	db	13,10,``\$''

func_17H: display prompt1 ;see Function 09H get_string 15, reply ;see Function OAH :see Function 09H display crlf reply[2],fcb ;see Function 29H parse display prompt2 :see Function 09H get_string 15, reply ;see Function OAH display crlf ;see Function 09H parse reply[2],fcb[16] ;see Function 29H rename fcb **;THIS FUNCTION**

19H Current Disk

Call	AF	AH = 19H			
Return	(AL Currently selected drive (0 = A:, 1 = B:, etc.)			
Macro	r i	current_disk macro mov ah, 19H int 21H endm			
Example The following program displays the currently selected (default) drive:					
	message	db	``Current disk is \$''	;see Function 09H	
	crlf	db 13,10,`` \$ ''		;for explanation of \$	
	func_19H:	display message current_disk add al, 41H display_char al display crlf		;see Function 09H ;THIS FUNCTION ;ASCII offset ;see function 02H ;see function 09H	

1AH Set Disk Transfer Address

Call	AH = 1AH DS:DX Disk Transfer Address
Return	None
Remarks	DX must contain the offset (from the segment address in DS) of the Disk Transfer Address. Disk transfers cannot wrap around from the end of the segment to the beginning, nor can they overflow into another segment.
Note:	If you do not set the Disk Transfer Address, MS-DOS defaults to offset 80H in the Program Segment Prefix. The size of the buffer that the DTA points to must be greater than or equal to the record size at open file time.
Macro	set_dta macro buffer mov dx,offset buffer mov ah,1AH int 21H endm

1AH Set Disk Transfer Address

Example	verts B = 2, spond DAT	the le etc.), ing r on the	tter t ther ecord e dis	to its alpl n reads a l from a f k in drive	hab nd (file e B:	npts for a letter, con- etic sequence (A = 1, displays the corre- named ALPHABET . The file contains 26 ytes long:
record_size	equ	14		;offset of ;field of F		
relative_record	equ	33		•	Rela	ative Record
	•					
fcb	db db		LPH. lup (?		Γ"	
buffer	db		lup(?)			
prompt	db			,, ↓ ter: \$′′		
crlf	db		.0,``\$'			
	•	,_	-, ,			
func_1AH:		.dta b				;THIS FUNCTION
	ope		b	,		;see Function OFH
	mo],28	;set record size
get_char:		olay p		d_echo		;see Function 09H
	cm		i_and l,0DF			;see Function 01H ;just a CR?
	ie		ll_do			;yes, go home
	sub		l,41H			;convert ASCII
	Sub	u.	.,	•		;code to record #
	mo	7 fc	blrel	ative_rec	ord	
					;set relative record	
	dis	olay c	lay crlf			;see Function 09H
	rea	d_ran	fcb			;see Function 21H
	-	play buffer				;see Function 09H
	dis	olay c				;see Function 09H
	jmŗ		et_ch	ar		;get another character
all_done:	clos	se fo	eb			;see Function 10H

21H Random Read

Call	AH = 21 DS:DX Opene	H d FCB				
Return	01H = 02H =	Read completed successfully EOF DTA too small EOF, partial record				
Remarks	DX must contain the offset (from the segment address in DS) of an opened FCB. The Current Block (offset 0CH) and Current Record (offset 20H) fields are set to agree with the Relative Record field (offset 21H), then the record addressed by these fields is loaded at the Disk Transfer Address. AL returns a code that describes the processing:					
	Code Meaning					
	0	read completed successfully				
	1	End-of-file; no data in the record				
	2	not enough room at the Disk Transfer Address to read one record; read can- celed				
	3	End-of-file; a partial record was read and padded to the record length with zeros.				
Macro	mov d mov a	macro fcb x,offset fcb h,21H 21H				

21H Random Read

- v F S	erts the 3 = 2, et pondin DAT on	e letter to c.), then g record the disk	o its alphak reads and from a file	mpts for a letter, con- betic sequence (A = 1, displays the corre- named ALPHABET :. The file contains 26 ytes long:
record_size	equ]	.4	;offset of Re ;field of FC	
relative_record	equ 3	33		elative Record
fcb		` ALPHA 5 dup (?)	BETDAT''	
buffer		4 dup(?),	``\$''	
prompt		Inter lette		
crlf	db 13	3,10,``\$''		
func_21H: get_char:	open mov display read_k cmp je sub mov display read_n	fcb[recc y prompt bd_and al,ODH all_don al,41H fcb[rela y crlf an fcb y buffer	_echo e tive_record	;set relative record ;see Function 09H ;THIS FUNCTION ;see Function 09H ;see Function 09H ;get another character
all_done:	close	fcb		;see Function 10H

22H Random Write

Call	AH = 221 DS:DX Opene				
Return	01H =	Write completed successfully Disk full DTA too small			
Remarks	DX must contain the offset from the segment address in DS of an opened FCB. The Current Block (offset 0CH) and Current Record (offset 20H) fields are set to agree with the Relative Record field (offset 21H), then the record addressed by these fields is written from the Disk Transfer Address. If the record size is smaller than a sector (512 bytes), the records are buffered until a sector is ready to write.				
	AL returns a code that describes the processing:				
	Code	Meaning			
	0	Write completed successfully			
	1	disk is full			
	2	write canceled; the area beginning at the Disk Transfer Area is too small to hold a record of data without over- flowing or wrapping around a seg- ment boundary.			
Macro	mov d mov a	macro fcb lx,offset fcb .h,22H 21H			

22H Random Write

Example	The following program prompts for a letter, converts the letter to its alphabetic sequence (A = 1, B = 2, etc.), then reads and displays the corresponding record from a file named ALPHABETDAT on the disk in drive B:. After displaying the record, it prompts the user to enter a changed record. If the user types a new record, it is written to the file; if the user just presses CR , the record is not replaced. The file contains 26 records; each record is 28 bytes long:			
record_size	equ l	;field of F		
relative_reco	rd equ 33	3 ;offset of I ;field of F	Relative Record CB	
fcb		ALPHABETDAT '' dup (?)		
buffer		dup(?),13,10,``\$''		
promptl		nter letter: \$"		
prompt2		lew record(CR for 1	no change): \$ ′′	
crlf	db 13	3,10,``\$''		
reply	db 30) dup (32)		
blanks	db 28	3 dup (32)		
func_22H:	- -	buffer fcb fcb[record_size],2	;see Function 1AH ;see Function OFH 8:set record size	
get_char:	display read_k cmp	prompt1 bd_and_echo al,ODH all_done al,41H fcb[relative_recor	;see Function 09H ;see Function 01H ;just a CR? ;yes, go home ;convert ASCII ;code to record #	
			;set relative record	

display	/ crlf	;see Function 09H
read_r	an fcb	THIS FUNCTION
display	7 buffer	;see Function 09H
display	v crlf	;see Function 09H
display	v prompt2	;see Function 09H
get_str	ing 29, reply	;see Function 09H
display	v crlf	;see Function 09H
cmp	reply[1],0	;was anything typed
		;besides cr?
je	get_char	;no
		;get another character
xor	bx,bx	;to load a byte
mov	bl,reply[1]	;use reply length as
		;counter
move_	string blanks, buffer	, 28
		;see chapter end
move_	string reply[2], buffe	er, b x
		;see chapter end
write_r	an fcb	THIS FUNCTION
jmp	get_char	;get another character
close	fcb	;see Function 10H

all_done:

23H File Size

Call	AH = 23H	
	DS:DX Unopened FCB	
Return	AL 00H = Directory entry found FFH = No directory entry found	
Remarks	DX must contain the offset (from the segment address in DS) of an unopened FCB. You must set the Record Size field (offset 0EH) to the proper value before calling this function. The disk directory is searched for the first matching entry.	
	If a matching directory entry is found, the Rela- tive Record field (offset 21H) is set to the number of records in the file, calculated from the total file size in the directory entry (offset 10H) and the Record Size field of the FCB (offset 0EH). AL returns 00.	
	If no matching directory entry is found, AL returns FFH.	
Note	If the value of the Record Size field of the FCB (offset 0EH) doesn't match the actual number of characters in a record, this function may not return the correct file size. If the default record size (128) is not correct, you must set the Record Size field to the correct value before using this function.	

			· · · · · ·
Macro		,offset fcb ,23H	
Example	a file, oper the FCB to	ns the file to s 80H, issues ys the file siz	prompts for the name of set the Record Size field of a File Size system call, ze and number of records
fcb prompt msgl msg2 crlf reply sixteen	db db db db db db db	37 dup(?) "File name: 5 "Record leng "Records: ", 13,10,"\$" 17 dup(?) 16	, jth: ″,13,10,``\$''
func_23H:	display prom get_string 1 cmp jne jmp		;see Function 09H ;see Function 0AH ;just a CR? ;no, keep going ;yes, go home
get_length:	display crlf parse open file_size fcb mov	reply[2],fcb fcb si,33	;see Function 09H ;see Function 29H ;see Function 0FH ;THIS FUNCTION ;offset to Relative ;Record field
convert_it:	mov cmp je	di,9 fcb[si],0 show_it	;reply in msg2 ;digit to convert? ;no, prepare message

	convert fcb[si],sixteen,msq	y2[di]
	inc	si	;bump n-o-r ind ex
	inc	di	;bump message index
	jmp	convert_it	;check for a digit
show_it:	convert fcb[14],sixteen,ms	sg1[15]
	display msg	1	;see Function 09H
	display msg	2	;see Function 09H
	jmp	func23H	;get a filename
all_done:	close	fcb	;see Function 10H

24H Set Relative Record

Call	AH = 24H DS:DX Opened FCB
Return	None
Remarks	DX must contain the offset (from the segment address in DS) of an opened FCB. The Relative Record field (offset 21H) is set to the same file address as the Current Block (offset 0CH) and Current Record (offset 20H) fields.
Macro	set_relative_record macro fcb mov dx,offset fcb mov ah,24H int 21H endm
Example	The following program copies a file using the Random Block Read and Random Block Write system calls. It speeds the copy by setting the record length equal to the file size and the record count to 1, and using a buffer of 32K bytes. It positions the file pointer by setting the Current Record field (offset 20H) to 0 and using Set Rela- tive Record to make the Relative Record field (offset 21H) point to the same record as the com- bination of the Current Block (offset 0CH) and Current Record (offset 20H) fields:

24H Set Relative Record

current_record fsize	equ equ	32 16	;offset of Current Record ;field of FCB ;offset of File Size ;field of FCB
fcb filename prompt1 prompt2 crlf	db db db	37 dup (?) 17 dup(?) "File to copy: \$'' "Name of copy: \$'' 13,10,"\$'	;see Function 09H for ;explanation of \$
file_length buffer	dw db	? 32767 dup(?)	
func_24H:	<pre></pre>		;see Function 1AH ;see Function 09H ;see Function 0AH ;see Function 09H ;see Function 29H ;see Function 0FH ;set Current Record ;field ;THIS FUNCTION ;get file size ;save it for ;ran_block_write ;see Function 27H ;see Function 09H ;see Function 09H ;see Function 09H ;see Function 29H ;THIS FUNCTION

mov ax,file_length

ran_block_write fcb, 1,ax close fcb ;get original file ;length ;see Function 28H ;see Function 10H

25H Set Vector

Call	AH = 25H AL Interrupt number DS:DX Interrupt-handling routine		
Return	None		
Remarks	Function 25H should be used to set a particular interrupt vector. The operating system can then manage the interrupts on a per-process basis. Note that programs should never set interrupt vectors by writing them directly in the low memory vector table.		
	DX must contain the offset (to the segment address in DS) of an interrupt-handling routine. AL must contain the number of the interrupt handled by the routine. The address in the vec- tor table for the specified interrupt is set to DS:DX.		
Macro	set_vector macro interrupt, seg_addr,off_addr push ds mov ax,seg_addr mov ds,ax mov dx,off_addr mov al,interrupt mov ah,25H int 21H pop ds endm		
Example	lds dx,intvector mov ah,25H mov al,intnumber int 21H ;There are no errors returned		

27H Random Block Read

Call	AH = 27H DS:DX Openeo CX Numbe		
Return	AL 00H = Read completed successfully 01H = EOF 02H = End of segment 03H = EOF, partial record CX Number of blocks read		
Remarks	DX must contain the offset (to the segment address in DS) of an opened FCB. CX must con- tain the number of records to read; if it contains 0, the function returns without reading any records (no operation). The specified number of records, calculated from the Record Size field (offset 0EH), is read starting at the record speci- fied by the Relative Record field (offset 21H). The records are placed at the Disk Transfer Address.		
	AL return	ns a code that describes the processing:	
	Code	Meaning	
	0	Read completed successfully	
	1	End-of-file; no data in the record	
	2	not enough room at the Disk Transfer Address to read one record without overflowing a segment boundary; read cancelled	
	3	End-of-file; a partial record was read and padded to the record length with zeros	

27H Random Block Read

	CX returns the number of records read; the Cur- rent Block (offset 0CH), Current Record (offset 20H), and Relative Record (offset 21H) fields are set to address the next record.			
Macro	ran_bloc	mov mov mov mov	acro fcb,cou dx,offset fcb cx,count word ptr fck ah,27H 21H	
Example	Random copy by record le buffer of record (c Function	a Block Re specifyin ength equa 32K byte compare t a 28H tha	ad system g a record c al to the fil s; the file i o the samp t specifies	es a file using the call. It speeds the count of 1 and a e size, and using a s read as a single le program for a record length of 1 the file size):
current_reco	current_record equ 32			ffset of Current Record eld
fsize	equ	16	;0	ffset of File Size eld
fcb filename prompt1 prompt2 crlf file_length buffer	db 1 db " db " db 1 db 1	87 dup (?) .7 dup(?) File to cop Name of c .3,10,``\$'' 82767 dup	ору: \$′′ ;е	ee Function 09H for xplanation of \$
func_27H:	set_dt	ta buffer	;s	ee Function 1AH

27H Random Block Read

display prompt1 get_string 15,filename display crlf parse filename[2],fcb open fcb mov fcb[current_record],0

set_relative_record fcb mov ax,word ptr fcb[fsize] mov file_length,ax

ran_block_read fcb,1,ax display prompt2 get_string 15,filename display crlf parse filename[2],fcb create fcb mov fcb[current_record],0

set_relative_record fcb
mov ax,file_length

ran_block_write fcb,1,ax close fcb :see Function 09H :see Function OAH :see Function 09H :see Function 29H :see Function OFH set Current Record :field :see Function 24H :get file size :save it for :ran_block_write THIS FUNCTION see Function 09H see Function OAH :see Function 09H :see Function 29H ;see Function 16H ;set Current Record :field ;see Function 24H ;get original file ;size ;see Function 28H

28H Random Block Write

· · ·			
Call	- • • • • •		
Return	01H =] 02H =] CX	Write completed successfully Disk full End of segment er of blocks written	
Remarks	DX must contain the offset (to the segment address in DS) of an opened FCB; CX must con- tain either the number of records to write or 0. The specified number of records (calculated from the Record Size field, offset 0EH) is written from the Disk Transfer Address. The records are writ- ten to the file starting at the record specified in the Relative Record field (offset 21H) of the FCB. If CX is 0, no records are written, but the File Size field of the directory entry (offset 10H) is set to the number of records specified by the Rela- tive Record field of the FCB (offset 21H); alloca- tion units are allocated or released, as required.		
	AL return	ns a code that describes the processing:	
	Code	Meaning	
	0	Write completed successfully	
	1	Disk full. No records written.	
	2	Not enough room at the Disk Transfer Address to write one record without overflowing a segment boundary; write canceled.	

	CX returns the number of records written; the current block (offset 0CH), Current Record (offset 20H), and Relative Record (offset 21H) fields are set to address the next record.			
Macro	ran_ł	mov dx, mov cx,	rd ptr fcb[14],rec_size 28 H	
Example	Rand syste count 1, and copie write tion 2	om Block Read m calls. It copie t equal to the fil d using a buffer d with one disk (compare to the	am copies a file using the and Random Block Write as by specifying a record e size and a record length of of 32K bytes; the file is access each to read and e sample program of Func- ies a record count of 1 and a o file size):	
current_record	l equ equ	32 16	;offset of Current Record ;field ;offset of File Size ;field	
fcb filename prompt1 prompt2 crlf num_recs buffer	db db db db db dw	37 dup (?) 17 dup(?) "File to copy: \$" "Name of copy: 13,10,"\$" ? 32767 dup(?)	;see Function 09H for	

28H Random Block Write

func_28H:	display	buffer prompt1 15,filename crlf filename[2],fcb fcb fcb[current_record],0	;see Function 1AH ;see Function 09H ;see Function 0AH ;see Function 09H ;see Function 29H ;see Function 0FH ;set Current Record ;field
	set_relativ	e_record fcb	;see Function 24H
	mov	ax,word ptr fcb[fsize]	;get file size
	mov	num_recs, a x	;save it for
			;ran_block_write
	ran_block	_read fcb,num_recs,1	;see Function 27H
	display	prompt2	;see Function 09H
	get_string	15,filename	;see Function OAH
	display	crlf	;see Function 09H
	parse	filename[2],fcb	;see Function 29H
	create	fcb	;see Function 16H
	mov	fcb[current_record],0	;set Current Record ;field
		e_record fcb _write fcb,num_recs, l fcb	;see Function 24H ;THIS FUNCTION ;see Function 10H

29H Parse File Name

Call	AH = 29H AL Controls parsing (see text) DS:SI String to parse ES:DI Unopened FCB
Return	AL 00H = No wild card characters 01H = Wild-card characters used FFH = Drive letter invalid DS:SI First byte past string that was parsed ES:DI Unopened FCB
Remarks	SI must contain the offset (to the segment ad- dress in DS) of a string (command line) to parse; DI must contain the offset (to the segment ad- dress in ES) of an unopened FCB. The string is parsed for a filename of the form d:filename.ext; if one is found, a corresponding unopened FCB is created at ES:DI. Bits 0-3 of AL control the parsing and process- ing. Bits 4-7 are ignored:

29H Parse File Name

Bit	Value	Meaning
0	0	All parsing stops if a file separator is encountered.
	1	Leading separators are ignored.
1	0	The drive number in the FCB is set to 0 (default drive) if the string does not contain a drive number.
	1	The drive number in the FCB is not changed if the string does not con- tain a drive number.
2	0	The filename in the FCB is set to 8 blanks if the string does not contain a filename.
	1	The filename in the FCB is not changed if the string does not con- tain a filename.
3	0	The extension in the FCB is set to 3 blanks if the string does not contain an extension.
	1	The extension in the FCB is not changed if the string does not con- tain an extension.
		me or extension includes an asterisk ining characters in the name or

(*), all remaining characters in the name or extension are set to question mark (?).

Filename separators:

:.;, = + / "[] \land >| space tab

Filename terminators include all the filename separators plus any control character. A filename cannot contain a filename terminator; if one is encountered, parsing stops.

If the string contains a valid filename:

- AL returns 1 if the filename or extension contains a wild card character (* or ?); AL returns 0 if neither the filename nor extension contains a wild card character.
- DS:SI point to the first character following the string that was parsed.
- ES:DI point to the first byte of the unopened FCB.

If the drive letter is invalid, AL returns FFH. If the string does not contain a valid filename, ES:DI+1 points to a blank (ASCII 20H).

29H Parse File Name

Macro	mov push	string, fcb si, offset string di, offset fcb es ds es al,0FH ;bits 0, ah,29H 21H es	1, 2, 3 on
Example		ng program ver ed in reply to th	ifies the existence of ne prompt:
fcb prompt reply yes no crlf		ne: \$'' (?) XISTS'', 13,10,``\$ OES NOT EXIST	
func_29H:	display get_string display parse search_first cmp je display jmp	al,OFFH not_there yes continue	;see Function 09H ;see Function 0AH ;see Function 09H ;THIS FUNCTION ;see Function 11H ;dir. entry found? ;no ;see Function 09H
not_there: continue:	display	no	

2AH Get Date

Call	AH = 2AH
Return	CX Year (1980-2099) DH Month (1-12) DL Day (1-31) AL Day of week (0 = Sunday, 6 = Saturday)
Remarks	This function returns the current date set in the operating system as binary numbers in CX and DX: CX Year (1980-2099) DH Month (1 = January, 2 = February, etc.) DL Day (1-31) AL Day of week (0 = Sunday, 1 = Monday, etc.)
Macro	get_date macro mov ah,2AH int 21H endm
Example	The following program gets the date, increments the day, increments the month or year, if neces- sary, and sets the new date:

2AH Get Date

month	db	31,28,31,30,3	31,30,31,31,30,31,30,31
func_2AH: month_ok:	get_date inc xor mov dec cmp jle mov inc cmp jle mov inc set_date cx,c	month_ok dl,1 dh dh,12 month_ok dh,1 cx	;see above ;increment day ;so BL can be used as index ;move month to index register ;month table starts with 0 ;past end of month? ;no, set the new date ;yes; set day to 1 ;and increment month ;past end of year? ;no, set the new date ;yes, set the month to 1 ;increment year ;THIS FUNCTION

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2BH Set Date

Call	AH = 2BH CX Year (1980-2099) DH Month (1-12) DL Day (1-31)
Return	AL 00H = Date was valid FFH = Date was invalid
Remarks	Registers CX and DX must contain a valid date in binary: CX Year (1980-2099) DH Month (1 = January, 2 = February, etc.) DL Day (1-31) If the date is valid, the date is set and AL returns 0. If the date is not valid, the function is canceled and AL returns FFH.
Macro	set_date macro year,month,day mov cx,year mov dh,month mov dl,day mov ah,2BH int 21H endm

2BH Set Date

Example	the day,		im gets the date, increments the month or year, if neces- w date:
month	db	31,28,31,30,	31,30,31,31,30,31,30,31
func_2BH: month_ok:	get_date inc xor mov dec cmp jle mov inc cmp jle mov inc set date cx,d	month_ok dl,1 dh dh,12 month_ok dh,1 cx	;see Function 2AH ;increment day ;so BL can be used as index ;move month to index register ;month table starts with 0 ;past end of month? ;no, set the new date ;yes, set day to 1 ;and increment month ;past end of year? ;no, set the new date ;yes, set the month to 1 ;increment year ;THIS FUNCTION

2CH Get Time

Call	AH = 2CH
Return	CH Hour (0-23) CL Minutes (0-59) DH Seconds (0-59) DL Hundredths (0-99)
Remarks	This function returns the current time set in the operating system as binary numbers in CX and DX: CH Hour (0-23) CL Minutes (0-59) DH Seconds (0-59) DL Hundredths of a second (0-99)
Macro	get_time macro mov ah,2CH int 21H endm
Example	The following program continuously displays the time until any key is pressed:

2CH Get Time

time	db	``00:00:00.00	0",13,`` \$ "
ten	db	10	
func_2CH: all_done:	convert dl	l,ten,time[3] h,ten,time[6] l,ten,time[9] me	;THIS FUNCTION ;see end of chapter ;see end of chapter ;see end of chapter ;see end of chapter ;see Function 09H ;see Function 0BH ;has a key been pressed? ;yes, terminate ;no, display time

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2DH Set Time

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Call	AH = 2DH CH Hour (0-23) CL Minutes (0-59) DH
	Seconds (0-59)
	DL Hundredths (0-99)
Return	AL 00H = Time was valid
	FFH (255) = Time was invalid
Remarks	Registers CX and DX must contain a valid time in binary:
	CH Hour (0-23)
	CL Minutes (0-59)
	DH Seconds (0-59)
	DL Hundredths of a second (0-99)
	If the time is valid, the time is set and AL returns 0. If the time is not valid, the function is canceled and AL returns FFH (255).
Macro	set_time macro hour,minutes,seconds,hundredths mov ch,hour mov cl,minutes mov dh,seconds mov dl,hundredths mov ah,2DH int 21H endm

Example	The following program acts as a stopwatch. When a character is typed, it sets the system clock to zero and begins to continuously display the time. When a second character is typed the system stops updating the time display.		
time	db	``00:00:00.0C)″.13.`` \$ ″
ten	db	10	,,_0,, ¢
	•		
func_2DH:	dir_console_io	OFFH	;see Function 06H
	jz	func_2DH	;wait for keystroke
	set_time	0,0,0,0	;THIS FUNCTION
read_clock:	get_time		;see Function 2CH
	convert ch,ten,t		;see end of chapter
	convert cl,ten,t		;see end of chapter
	convert dh,ten,t		;see end of chapter
	convert d1,ten,t	ime[9]	;see end of chapter
	display time		;see Function 09H
	dir_console_io	OFFH	;THIS FUNCTION
	jz	read_clock	;no char, keep updating
continue:	•		

2EH Set/Reset Verify Flag

Call		CH Do not Verify	verify	
Return	None			
Remarks	or 0 (wri	AL must be either 1 (verify after each disk write) or 0 (write without verifying). MS-DOS checks this flag each time it writes to a disk.		
	on when disk erro	n writing ors are r will pro	hally off; you may wish to turn it g critical data to disk. Because are and verification slows writ- bbably want to leave it off at	
Macro	verify ma mov mov int endm	acro swit al,switc ah,2EH 21H		
Example	single-s	The following program copies the contents of a single-sided disk in drive A: to the disk in drive B:, verifying each write. It uses a buffer of 32K bytes:		
	on off	equ equ	1 0	
	prompt start	db db dw	"Source in A, target in B",13,10 "Any key to start. \$" 0	
	buffer	db	64 dup (512 dup(?)) ;64 sectors	

2EH Set/Reset Verify Flag

func_2EH: display prompt read_kbd verify on mov cx,5

copy: push cx abs_disk_read 0,buffer,64,start abs_disk_write 1,buffer,64,start add start,64 pop cx loop copy verify off ;see Function 09H ;see Function 08H ;THIS FUNCTION ;copy 64 sectors ;5 times ;save counter ;see Interrupt 25H ;see Interrupt 26H ;do next 64 sectors ;restore counter ;do it again ;THIS FUNCTION

2FH Get Disk Transfer Address

Call	AH = 2FH
Return	ES:BX Points to Disk Transfer Address
Macro	; get_dta macro mov 2h,2fh int 21h endm

30H Get DOS Version Number

Call	AH = 30H
Return	AL Major version number AH Minor version number BH OEM number BL:CX User number (24 bits)
Remarks	On return, AL.AH will be the two-part version designation; i.e., for MS-DOS 1.28, AL would be 1 and AH would be 28. For pre-1.28 DOS AL = 0. Note that version 1.1 is the same as 1.10, not the same as 1.01.
Macro	; get_version_num macro mov ah,30h _int 21h endm

31H Keep Process

Call	AH = 31H AL Exit code DX Memory size, in paragraphs
Return	None
Remarks	This call terminates the current process and attempts to set the initial allocation block to a specific size in paragraphs. It will not free up any other allocation blocks belonging to that process. The exit code passed in AX is retriev- able by the parent via Function 4DH. This method is preferred over Interrupt 27H and has the advantage of allowing more than 64K to be kept.
Macro	; keep_process macro exitcode, parasize mov al, exitcode mov dx, parasize mov ah, 31h int 21h endm

33H <CTRL C> Check

Call	$\begin{array}{l} AH = 33H \\ AL \\ Function \\ 00H = Request current state \\ 01H = Set state \\ DL (if setting state) \\ 00H = Off \\ 01H = On \end{array}$
Return	DL 00H = Off 01H = On
Remarks	MS-DOS ordinarily checks for a CTRL C on the controlling device only when doing function call operations 01H-0CH to that device. Function 33H allows the user to expand this checking to include any system call. For example, with the CTRL C trapping off, all disk I/O will proceed without interruption; with CTRL C trapping on, the CTRL C interrupt is given at the system call that initiates the disk operation.
Note	Programs that wish to use calls 06H or 07H to read CTRL C 's as data must ensure that the CTRL C check is off.
Error Returns	AL = FF The function passed in AL was not in the range 0:1.

33H <CTRL C> Check

Macro

; ctrl_c_check macro switch,val mov dl,val mov al,switch mov ah,33h int 21h endm

35H Get Interrupt Vector

1	
Call	AH = 35H AL Interrupt number
Return	ES:BX Pointer to interrupt routine
Remarks	This function returns the interrupt vector asso- ciated with an interrupt. Note that programs should never get an interrupt vector by reading the low memory vector table directly.
Macro	; get_vector macro interrupt mov al,interrupt mov ah,35h int 21h endm

36H Get Disk Free Space

Call	AH = 36H DL Drive (0 = Default, 1 = A, etc.)
Return	AX FFFF if drive number is invalid; otherwise sectors per cluster BX Available clusters CX Bytes per sector DX Clusters per drive
Remarks	This function returns free space on a disk along with additional information about the disk.
Error Returns	AX = FFFF The drive number given in DL was invalid.
Macro	; get_disk_space macro drive mov d1,drive mov ah,36h int 21h endm

38H Return Country-Dependent Information

Call	AH = 38H DS:DX Pointer to 32-byte memory area AL Function code.
Return	Carry set: AX 2 = file not found Carry not set: DX:DS filled in with country data
Remarks	The value passed in AL is either 0 (for current country) or a country code. Country codes are typically the international telephone prefix code for the country. If $DX = -1$, then the call sets the current country (as returned by the $AL = 0$ call) to the country code in AL. If the country code is not found, the current country is not changed.
Note	 Applications must assume 32 bytes of information. This means the buffer pointed to by DS:DX must be able to accommodate 32 bytes. This function is fully supported only in versions of MS-DOS 2.01 and higher. It exists in MS-DOS 2.0, but is not fully implemented. This function returns, in the block of memory pointed to by DS:DX, information pertinent to international applications. The contents of the block are shown in the following table.

WORD Date/time format
5 BYTE ASCIIZ string currency symbol
2 BYTE ASCIIZ string thousands separator
2 BYTE ASCIIZ string decimal separator
2 BYTE ASCIIZ string date separator
2 BYTE ASCIIZ string time separator
1 BYTE Bit field
1 BYTE Currency places
1 BYTE time format
DWORD Case Mapping call
2 BYTE ASCIIZ string data list separator
· · · · · · · · · · · · · · · · · · ·

The format of most of the entries is ASCIIZ (a NUL terminated ASCII string), but a fixed size is allocated for each field for easy indexing into the table.

The date/time format (see table) has the following values:

0 — USA standard	h:m:s m/d/y
1 — Europe standard	h:m:s d/m/y
2 — Japan standard	y/m/d h:m:s

The bit field contains 8 bit values. Any bit not currently defined must be assumed to have a random value.

Bit 0 = 0 If currency symbol precedes the currency amount.

- = 1 If currency symbol comes after the currency amount.
- Bit 1 = 0 If the currency symbol is directly adjacent to the currency amount.
 - = 1 If there is a space between the currency symbol and the amount.

The time format has the following values:

- 0 12 hour time
- 1 24 hour time

The currency places field indicates the number of places which appear after the decimal point on currency amounts.

The Case Mapping call is a FAR procedure which will perform country specific lower-touppercase mapping on character values from 80H to FFH. It is called with the character to be mapped in AL. It returns the correct upper case code for that character, if any, in AL. AL and the FLAGS are the only registers altered. It is allowable to pass this routine codes below 80H; however nothing is done to characters in this range. In the case where there is no mapping, AL is not altered.

Error Returns AX 2 = file not found

The country passed in AL was not found (no table for specified country).

38H Return Country-Dependent Information

;

Macro

get_country_info macro buffer, country mov dx,offset buffer mov al,country ;country = 0 mov ah,38h int 21h endm

39H Create Sub-Directory

Call	AH = 39H DS:DX Pointer to path name
Return	Carry set: AX 3 = path not found 5 = access denied Carry not set: No error
Remarks	Given a pointer to an ASCIIZ name, this func- tion creates a new directory entry at the end.
Error Returns	 AX 3 = path not found The path specified was invalid or not found. 5 = access denied The directory could not be created (no room in parent directory), the directory/ file already existed or a device name was specified.
Macro	; mkdir macro name mov dx,offset name mov ah,39h int 21h endm

3AH Remove a Directory

Call	AH = 3AH DS:DX Pointer to path name
Return	Carry set: AX 3 = path not found 5 = access denied 16 = current directory Carry not set: No error
Remarks	Function 3AH is given an ASCIIZ name of a directory. That directory is removed from its parent directory.
Error Returns	 AX 3 = path not found The path specified was invalid or not found. 5 = access denied The path specified was not empty, not a directory, the root directory, or contained invalid information. 16 = current directory The path specified was the current direc- tory on a drive.
Macro	; rmdir macro name mov dx,offset name mov ah,3ah int 21h endm

3BH Change the Current Directory

and the second	
Call	AH = 3BH DS:DX Pointer to path name
Return	Carry set: AX 3 = path not found Carry not set: No error
Remarks	Function 3BH is given the ASCIIZ name of the directory which is to become the current directory. If any member of the specified pathname does not exist, then the current directory is unchanged. Otherwise, the current directory is set to the string.
Error Returns	AX 3 = path not found The path specified in DS:DX either indi- cated a file or the path was invalid.
Macro	; chdir macro name mov dx,offset name mov ah,3bh int 21h endm

3CH Create a File

Call	AH = 3CH DS:DX Pointer to path name CX File attribute
Return	Carry set: AX 3 = path not found 4 = too many open files 5 = access denied Carry not set: AX is handle number
Remarks	Function 3CH creates a new file or truncates an old file to zero length in preparation for writing. DS:DX must point to an ASCIIZ path to the file. If the file did not exist, then the file is created in the appropriate directory and the file is given the attribute found in CX. The given attribute byte is placed at offset 0BH in the file's directory entry. See the section on "Diskette Directory" in chapter 5 for details about the attribute byte. The file handle returned has been opened for read/write access.

Error Returns	AX 3 = path not found The path specified was invalid. 4 = too many open files 5 = access denied The attributes specified in CX contained
	one that could not be created (directory, volume ID), a file already existed with a more inclusive set of attributes, or a direc- tory existed with the same name. The file was created with the specified attrib- utes, but there were no free handles available for the process, or the internal system tables were full.
Macro	; create_file macro name,attrib mov dx,offset name mov cx,attrib mov ah,3ch int 21h endm

3DH Open a File Handle

Call	AH = 3DH AL Access 0 = file opened 1 = file opened 2 = file opened reading an DS:DX pointer to path	for writing for both ad writing
Return	Carry set: AX 2 = file not for 4 = too many 5 = access de 12 = invalid a Carry not set AX is handle	y open files nied ccess
Remarks	Function 3DH a file.	ssociates a 16-bit handle with a
	The following v	alues are allowed:
	ACCESS	Function
	0 1 2	opened for reading opened for writing opened for both reading and writing.
	DS:DX point to opened.	an ASCIIZ name of the file to be
	the file and the	pointer is set at the first byte of record size of the file is 1 byte. e handle must be used for sub-

sequent I/O to the file.

Error Returns	AX 2 = file not found
	The path specified was invalid or not found.
	4 = too many open files
	There were no free handles available in the current process or the internal system tables were full.
	5 = access denied
	The user attempted to open a directory or volume-id, or open a read-only file for writ- ing.
	12 = invalid access
	The access specified in AL was not in the range 0:2.
Macro	; open_handle macro name, access mov dx,offset name mov al,access mov ah,3dh int 21h endm

3EH Close a File Handle

Call	AH = 3EH BX File handle
Return	Carry set: AX 6 = invalid handle Carry not set: No error
Remarks	If BX is passed a file handle (like that returned by Functions 3CH, 3DH, or 45H), Function 3EH closes the associated file. Internal buffers are flushed to disk.
Error Returns	AX 6 = invalid handle The handle passed in BX was not currently open.
Macro	; close_handle macro handle mov bx,handle mov ah,3eh int 21h endm

3FH Read From File/Device

Call	AH = 3FH DS:DX Pointer to buffer CX Bytes to read BX File handle
Return	Carry set: AX 5 = error set: 6 = invalid handle Carry not set: AX = number of bytes read
Remarks	Function 3FH transfers a specified number of bytes from a file into a buffer location. It is not guaranteed that the number of bytes requested will be read; for example, reading from the key- board will read at most one line of text. If the returned value is zero, then the program has tried to read from the end of file. All I/O is done using normalized pointers; no segment wraparound will occur.
Error Returns	 AX 5 = access denied The handle passed in BX was opened in a mode that did not allow reading. 6 = invalid handle The handle passed in BX was not cur- rently open.

3FH Read From File/Device

Macro

; read_from_handle macro buffer,bytes,handle mov dx,offset buffer mov cx,bytes mov bx,handle mov ah,3fh int 21h endm

40H Write to a File or Device

Call	AH = 40H DS:DX Pointer to buffer CX Bytes to write BX File handle
Return	Carry set: AX 5 = access denied 6 = invalid handle Carry not set: AX = number of bytes written
Remarks	Function 40H transfers a specified number of bytes from a buffer into a file. It should be regarded as an error if the number of bytes writ- ten is not the same as the number requested. The write system call with a count of zero (CX = 0) will set the file size to the current position. Allocation units are allocated or released as required. All I/O is done using normalized pointers; no segment wraparound will occur.

40H Write to a File or Device

Error Returns	AX 5 = access denied
	The handle was not opened in a mode that allowed writing.
	6 = invalid handle
	The handle passed in BX was not cur- rently open.
Macro	; write_to_handle macro buffer,bytes,handle mov dx,offset buffer mov cx, bytes mov bx,handle mov ah,40h int 21h endm

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41H Delete a Directory Entry

Call	AH = 41H DS:DX Pointer to path name
Return	Carry set: AX 2 = file not found 5 = access denied Carry not set: No error
Remarks	Function 41H deletes the file named in the ASCIIZ string pointed to by DS:DX.
Error Returns	 AX 2 = file not found The path specified was invalid or not found. 5 = access denied The path specified was a directory or readonly.
Macro	; erase macro name mov dx,offset name mov ah,41h int 21h endm

42H Move File Pointer

Call	AH = 42H CX:DX Distance AL Method or (see text) BX File hand	-	
Return	6 = invali Carry not se		
Remarks	Function 42H moves the read/write pointer according to one of the following methods:		
	Method	Function	
	0	the pointer is moved to offset bytes from the beginning of the file	
	1	the pointer is moved to the current location plus offset	
	2	the pointer is moved to the end of file plus offset	
		ld be regarded as a 32-bit integer cupying the most significant 16 bits.	

42H Move File Pointer

Error Returns	AX 1 = invalid function
	The function passed in AL was not in the range 0:2.
	6 = invalid handle
	The handle passed in BX was not cur- rently open.
Macro	; move_pointer macro highword,lowword,switch, handle mov dx,lowword mov cx,highword mov al,switch mov bx,handle mov ah,42h int 21h endm

,

43H Change Attributes

Call	AH = 43H DS:DX Pointer to path name AL Function 00 Return in CX 01 Set to CX CX (if AL = 01) Attribute to be set	
Return	Carry set: AX 1 = invalid function 3 = path not found 5 = access denied Carry not set: CX attributes (if AL = 00)	
Remarks	Given an ASCIIZ name pointed to by DS:DX, Function 42H will set/get the attributes of the file to those given in CX. See the section on "Diskette Directory" in chapter 5 for a descrip- tion of the attribute byte. A function code is passed in AL:	
	AL Function	
	0 return the attributes of the file in CX	
	1 set the attributes of the file to those in CX	

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43H Change Attributes

Error Returns	AX 1 = invalid function
	The function passed in AL was not in the range 0:1.
	3 = path not found
	The path specified was invalid.
	5 = access denied
	The attributes specified in CX contained one that could not be changed (directory, volume ID).
Macro	; change_attrib macro name,attrib,switch mov dx,offset name mov cx,attrib mov al,switch mov ah,43h int 21h

endm

44H I/O Control for Devices

$\begin{array}{l} AH = 44H \\ BX \\ Handle \\ BL \\ Drive (for function codes 4 and 5; \\ 0 = default, 1 = A:, etc.) \\ DS:DX \\ Data or buffer \\ CX \\ Bytes to read or write \\ AL \\ Function code; see text \end{array}$
Carry set: AX 1 = invalid function 5 = access denied 6 = invalid handle 13 = invalid data Carry not set: Function Code = 2,3,4,5 AX = Count transferred Function Code = 6,7 AL 00 = Not ready FF = Ready
 Function 44H sets or gets device information associated with an open handle, or sends/receives a control string to a device handle or device. The inputs to AL are function numbers, for which there are returns. The function number values and functions are discussed below. The following values are allowed in AL as function codes:

44H I/O Control for Devices

Call	Function
0	get device information (returned in DX)
1	set device information (as determined by DX)
2	read CX number of bytes into DS:DX from device control channel
3	write CX number of bytes from DS:DX to device control channel
4	read CX number of bytes into DS:DX from disk (drive number in BL)
5	write CX number of bytes from DS:DX to disk (drive number in BL)
6	get input status
7	get output status
This function can be used to get information about device channels. Calls can be made on regular files, but only calls 0,6 and 7 are defined in that case (AL = 0,6,7). All other calls return an invalid function error.	
AL = 0 ar	of DX are defined as follows for calls and $AL = 1$. Note that the upper byte e zero on a set call.

Calls 0,1:

15 14 13 1	2 11 10 9 8	765	<u>54</u>	3	<u>2</u> 1	0
R C e T s R L	Reserved	I E I S O Z D F V E V	AP VE C	S C L	S S	S C I
	if this channe if this channe (Bits 8-15 = 0	el is a d	lisk	file		
If ISDEV =	1					
RAW = 1 $= 0$ $SPECL = 1$ $ISCLK = 1$ $ISNUL = 1$ $ISCOT = 1$	if End Of File if this device if this device	is in R is cool is spec is the is the is the	aw xed cial cloc null cons	k de dev sole	evice vice outj	put
CTRL = 0 if this device cannot do control strings via calls $AL = 2$ and $AL = 3$ CTRL = 1 if this device can process control strings via calls $AL = 2$ and $AL = 3$. NOTE that this bit cannot be set.						
If ISDEV =	0					
Bits 0-5 are	channel has t the block dev	vice nu		4	r th	e

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channel (0 = A:, 1 = B:, ...)

NOTE: Bits 15,8-13,4 are reserved and should not be altered.

Calls 2..5: These four calls allow arbitrary control strings to be sent or received from a device. The call syntax is the same as the read and write system calls, except for 4 and 5, which take a drive number in BL instead of a handle in BX.

An invalid function error is returned if the CTRL bit (see above) is 0.

An access denied error is returned by calls AL = 4,5 if the drive number is invalid.

Calls 6,7: These two calls allow the user to check if a file handle is ready for input or output. Status of handles open to a device is the intended use of these calls, but status of a handle open to a disk file is allowed, and is defined as follows:

For input:

• Always ready (AL = FF) until EOF reached, then always not ready (AL = 0) unless current position changed via Function Request 42H (LSEEK).

For output:

• Always ready (even if disk full).

The status is defined at the time the system is CALLED. On future versions, by the time control is returned to the user from the system, the status returned may NOT correctly reflect the true current state of the device or file.

44H I/O Control for Devices

Error Returns	AX 1 = invalid function
	The function passed in AL was not in the range 0:7.
	5 = access denied (calls AL = 4,5)
	6 = invalid handle
	The handle passed in BX was not cur- rently open.
	13 = invalid data
Macro	; io_ctrl_dev macro handle,buffer,bytes,switch mov bx,handle ;or 8-bit drive number mov dx,offset buffer mov cx,bytes mov a1,switch mov 2h,44h int 21h endm

45H Duplicate a File Handle

Call	AH = 45H BX File handle
Return	Carry set: AX 4 = too many open files 6 = invalid handle Carry not set: AX = new file handle
Remarks	Function 45H takes an already opened file han- dle and returns a new handle that refers to the same file at the same position.
Error Returns	 AX 4 = too many open files There were no free handles available in the current process or the internal system tables were full. 6 = invalid handle The handle passed in BX was not cur- rently open.
Example	mov bx,fh mov ah,45H int 21H ;ax has the returned handle

46H Force a Duplicate of a Handle

Call	AH = 46H BX Existing file handle CX New file handle
Return	Carry set: AX 4 = too many open files 6 = invalid handle Carry not set: No error
Remarks	Function 46H takes an already opened file han- dle and returns a new handle that refers to the same file at the same position. If there was already a file open on handle CX, it is closed first.
Error Returns	AX 4 = too many open files The internal system tables were full. 6 = invalid handle The handle passed in BX was not cur- rently open.
Example	mov bx,fh mov cx,newfh mov ah,46H int 21H

47H Return Name of Current Directory

Call	AH = 47H DS:SI Pointer to 64-byte memory area DL Drive number		
Return	Carry set: AX 15 = invalid drive Carry not set: No error		
Remarks	Function 47H returns an ASCIIZ string giving the name of the current directory for a particular drive. The directory is root-relative and does not contain the drive specifier or leading path separator. The drive code passed in DL is $0 =$ default, $1 = A$; $2 = B$; etc.		
Error Returns	AX 15 = invalid drive The drive specified in DL was invalid.		
Macro	; duplicate_handle macro handle mov bx,handle mov ah,45h int 21h endm		

48H Allocate Memory

Call	AH = 48H BX Size of memory to be allocated in paragraphs		
Return	Carry set: AX 7 = arena trashed 8 = not enough memory BX Maximum size that could be allocated Carry not set: AX:0 Pointer to the allocated memory		
Remarks	Function 48H returns a pointer to a free block of memory that has the requested size in paragraphs.		
Error Returns	 AX 7 = arena trashed The internal consistency of the memory arena has been destroyed. This is due to a user program changing memory that does not belong to it, thus destroying the memory manager allocation marks. 8 = not enough memory The largest available free block is smaller than that requested or there is no free block. 		

48H Allocate Memory

Macro

; force_handle macro old,new mov bx,old mov cx,new mov ah,46h int 21h endm

49H Free Allocated Memory

Call	AH = 49H ES Segment address of memory area to be freed		
Return	Carry set: AX 7 = arena trashed 9 = invalid block Carry not set: No error		
Remarks	Function 49H returns a piece of previously allo- cated memory to the system pool.		
Error Returns	 AX 7 = arena trashed The internal consistency of the memory arena has been destroyed. This is due to a user program changing memory that does not belong to it, thus destroying the memory manager allocation marks. 9 = invalid block The block passed in ES is not one allocated via Function Request 48H. 		
Macro	; cur_dir_name macro buffer,drive mov si,offset buffer mov d1,drive mov ah,47h int 21h endm		

4AH Modify Allocated Memory Blocks

Call	AH = 4AH ES Segment address of memory area BX Requested memory area size	
Return	Carry set: AX 7 = arena trashed 8 = not enough memory 9 = invalid block BX Maximum size possible Carry not set: No error	
Remarks	Function 4AH will attempt to grow/shrink an allocated block of memory.	
Error Returns	 AX 7 = arena trashed The internal consistency of the memory arena has been destroyed. This is due to a user program changing memory that does not belong to it, thus destroying the memory manager allocation marks. 8 = not enough memory There was not enough free memory after the specified block to satisfy the grow request. 9 = invalid block The block passed in ES is not one allo- cated via this function. 	

4AH Modify Allocated Memory Blocks

Macro

; alloc_mem macro size mov bx,size mov ah,48h int 21h endm

4BH Load and Execute a Program (EXEC)

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Call	ES:BX Point AL 00 = 1	BH For to pathname For to parameter block Load and execute program Load program	
Return	2 = f 8 = r 10 = k	nvalid function ile not found not enough memory oad environment oad format ot set:	
Remarks	This function allows a program to load another program into memory and optionally begin exe- cution of it. DS:DX points to the ASCIIZ name of the file to be loaded. ES:BX points to a parameter block for the load. A function code is passed in AL:		
	ĀL	Function	
	0	load and execute the program. A pro- gram header is established for the pro- gram and the terminate and CTRL C addresses are set to the instruction after the EXEC system call.	
	3	load (do not create) the program header, and do not begin execution. This is use- ful in loading program overlays.	

For each value of AL, the block has the format shown in the following table.

AL = 0 - load/execute program

WORD segment address of environment.

DWORD pointer to command line at 80H of Program Segment Prefix

DWORD pointer to default FCB to be passed at 5CH of PSP

DWORD pointer to default FCB to be passed at 6CH of PSP

AL = 3 - load overlay

WORD segment address where file will be loaded.

WORD relocation factor to be applied to the image.

Note that all open files of a process are duplicated in the child process after an EXEC. This is extremely powerful; the parent process has control over the meanings of stdin, stdout, stderr, stdaux and stdprn. The parent could, for example, write a series of records to a file, open the file as standard input, open a listing file as standard output and then EXEC a sort program that takes its input from stdin and writes to stdout. Also inherited (or passed from the parent) is an "environment." This is a block of text strings (less than 32K bytes total) that convey various configurations parameters. The format of the environment is as follows:

(paragraph boundary)

BYTE ASCIIZ string 1	
BYTE ASCIIZ string 2	
BYTE ASCIIZ string n	
BYTE of zero	

Typically the environment strings have the form:

parameter = value

For example, COMMAND.COM might pass its execution search path as:

PATH=A:\BIN;B:\BASIC\LIB

A zero value of the environment address causes the child process to inherit the parent's environment unchanged.

4BH Load and Execute a Program (EXEC)

AX 1 = invalid function
The function passed in AL was not 0 or 3 .
2 = file not found
The path specified was invalid or not found.
8 = not enough memory
There was not enough memory for the process to be created.
10 = bad environment
The environment was larger than 32Kb.
11 = bad format
The file pointed to by DS:DX was in .EXE format and contained information that was internally inconsistent.
; free_memory macro address mov ax,address mov es,ax mov ah,49h int 21h endm

4CH Terminate a Process

Call	AH = 4CH AL = Return code			
Return	None			
Remarks	Function 4CH terminates the current process and transfers control to the invoking process. In addition, a return code may be sent. All files open at the time are closed.			
	This method is preferred over all others (Inter- rupt 20H, JMP 0) and has the advantage that CS:0 does not have to point to the Program Header Prefix.			
Macro	; modify_memory macro address,size mov ax,address mov es,ax mov bx,size mov ah,4ah int 21h endm			

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4DH Retrieve the Return Code of a Child

Call	AH = 4DH	
Return	AX Exit code	
Remarks	Function 4DH returns the Exit code specified by a child process. It returns this Exit code only once. The low byte of this code is that sent by the Exit routine. The high byte is one of the following:	
	0 - Terminate/abort 1 - CTRL C 2 - Hard error 3 - Terminate and stay resident	
Macro	exec macro path, param, switch mov dx, offset path mov bx, offset param mov al, switch mov ah, 4bh int 21h endm	

4EH Find Match File

Call	AH = 4EH DS:DX Pointer to pathname CX Search attributes	
Return	Carry set: AX 2 = file not found 18 = no more files Carry not set: No error	
Remarks	Function 4EH takes a pathname with wild car characters in the last component (passed in an ASCIIZ string pointed to by DS:DX) along wit a set of attributes (passed in CX) and attempts to find all files that match the pathname and have a subset of the required attributes. A datablock at the current DTA is written that contains information in the following form:	
	find_buf_reservedDB 21 DUP (?); Reserved*find_buf_attrDB ? ;attribute foundfind_buf_timeDW ? ;timefind_buf_dateDW ? ;datefind_buf_size_lDW ? ;low(size)find_buf_size_hDW ? ;high(size)find_buf_pnameDB 13 DUP (?) ;packed namefind_buf ENDSFind_buf (for the form	
	*Reserved for MS-DOS internal use on subsequent find_nexts	
	To obtain the subsequent matches of the path- name, see the description of Function 4FH.	

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4EH Find Match File

Error Returns	AX 2 = file not found
	The path specified in DS:DX was an invalid path.
	18 = no more files
	There were no files matching this specifi- cation.
Macro	; terminate_process macro code mov al,code mov ah,4ch int 21h endm

4FH Step Through a Directory Matching Files

Call	AH = 4FH
Return	Carry set: AX 18 = no more files Carry not set: No error
Remarks	The current DTA address must point at a block returned by Function 4EH (see Function 4EH).
Error Returns	AX 18 = no more files There are no more files matching this pattern.
Macro	; retrieve_code macro mov ah,4dh int 21h endm

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54H Return Current Setting of Verify After Write Flag

Call	AH = 54H		
Return	AL Current verify flag value		
Remarks	The current value of the verify flag is returned in AL.		
Macro	; find_match macro name,attrib mov dx,offset name mov cx,attrib mov ah,4eh int 21h endm		

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56H Move a Directory Entry

Call	AH = 56H DS:DX Pointer to pathname of existing file ES:DI Pointer to new pathname
Return	Carry set: AX 2 = file not found 5 = access denied 17 = not same device Carry not set: No error
Remarks	Function 56H attempts to rename a file into another path. The paths must be on the same device.
Error Returns	AX 2 = file not found
Neturns	
	The file name specifed by DS:DX was not found.
	5 = access denied
	The path specified in DS:DX was a direc- tory or the file specified by ES:DI already exists or the destination directory entry could not be created.
	17 = not same device
	The source and destination are on differ- ent drives.

56H Move a Directory Entry

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Macro

step_match macro mov ah,4fh int 21h endm

57H Get/Set Date/Time of File

Call	AH = 57H AL $00 = get date and time$ $01 = set date and time$ BX File handle $CX (if AL = 01)$ Time to be set $DX (if AL = 01)$ Date to be set
Return	Carry set: AX 1 = invalid function 6 = invalid handle Carry not set: No error CX/DX set if function 0
Remarks	Function 57H returns or sets the last-write time for a handle. These times are not recorded until the file is closed.
	A function code is passed in AL:
	0 return the time/date of the handle in CX/DX
	1 set the time/date of the handle to CX/DX
	The format for the date and time is the same as the date and time fields for a directory entry, except that the individual bytes in each word are reversed. The high order portion of the time is in CL, and the high order portion of the date is in DL.

57H Get/Set Date/Time of File

Error Returns	AX 1 = invalid function	(
	The function passed in AL was not in the range 0:1.	
	6 = invalid handle	
	The handle passed in BX was not currently open.	
Macro	; check_verify_flag macro mov ah,54h int 21h endm	

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Macro

Note

These macro definitions apply to system call examples 00H through 57H.

; Interrupts ******* ;ABS_DISK_READ abs_disk_read macro disk, buffer, num_sectors, first_sector al.disk mov bx,offset buffer mov mov cx,num_sectors mov dx,first_sector 25H int ;interrupt 25H fqoq endm ; ;ABS_DISK_WRITE abs_disk_write macro disk, buffer, num_sectors, first_sector mov al,disk bx,offset buffer mov mov cx,num_sectors mov dx,first_sector 26H int ;interrupt 26H popf endm ; stay_resident macro last_instruc ;STAY_RESIDENT dx,offset last_instruc mov inc dx int 27H ;interrupt 27H endm Functions ******

```
;
                               ;READ_KBD_AND_ECHO
read kbd_and_echo macro
                               :function 1
  mov
         ah.1
         21H
  int
  endm
;
                               :DISPLAY_CHAR
display_char macro character
         dl.character
  mov
                               ;function 2
         ah.2
  mov
         21H
  int
  endm
;
                                :AUX_INPUT
aux_input macro
                                :function 3
         ah.3
  mov
  int
          21H
  endm
                                :AUX_OUTPUT
aux_output macro
                                ;function 4
          ah.4
  mov
          21H
  int
  endm
                                ;PRINT_CHAR
print_char macro character
          dl.character
   mov
          ah,5
                                ;function 5
   mov
          21H
  int
   endm
                                ;DIR_CONSOLE_IO
dir_console_io macro switch
   mov dl,switch
                                ;function 6
   mov
          ah,6
          21H
   int
   endm
                                :DIR_CONSOLE_INPUT
dir_console_input macro
                                ;function 7
          ah,7
   mov
          21H
   int
   endm
;
                                :READ_KBD
read_kbd macro
                                :function 8
   mov
          ah,8
   int
          21H
   endm
```

display macro string :DISPLAY dx, offset string mov ah,9 ;function 9 mov 21H int endm ; get_string macro limit, string ;GET_STRING mov string,limit mov dx,offset string mov ah,0AH ;function OAH 21H int endm check_kbd_status macro :CHECK_KBD_STATUS mov ah,0BH :function OBH 21H int endm flush_and_read_kbd macro switch ;FLUSH_AND_READ_KBD al,switch mov mov ah.0CH ;function OCH int 21H endm reset_disk macro :RESET DISK ah.0DH :function ODH mov int 21H endm select_disk macro disk ;SELECT_DISK dl,disk[-65] mov mov ah.OEH ;function OEH 21H int endm open macro fcb ;OPEN mov dx,offset fcb ah,OFH mov ;function OFH 21Hint endm

; close macro fcb CLOSE: dx, offset fcb mov ;function 10H mov ah.10H 21Hint endm ; ;SEARCH_FIRST search_first macro fcb dx,offset fcb mov ;function 11H ah,11H mov 21Hint endm ; search_next macro fcb :SEARCH_NEXT dx,offset fcb mov mov ah,12H ;function 12H int 21H endm ;DELETE delete macro fcb mov dx,offset fcb ;function 13H mov ah,13H 21H int endm ; ;READ_SEQ read_seg macro fcb dx,offset fcb mov ah,14H ;function 14H mov int 21Hendm ï write_seq macro fcb ;WRITE_SEQ dx,offset fcb mov ;function 15H ah,15H mov int 21H endm ; create macro fcb :CREATE dx.offset fcb mov ;function 16H ah,16H mov 21H int endm

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; rename macro special_fcb ;RENAME dx,offset special_fcb mov ah.17H :function 17H mov 21H int endm ; current_disk macro ;CURRENT_DISK mov ah.19H :function 19H 21H int endm ; ' set_dta macro buffer ;SET_DTA mov dx,offset buffer ah,1AH ;function 1AH mov int 21H endm ; read_ran macro fcb ;READ_RAN mov dx.offset fcb mov ah,21H ;function 21H int 21H endm write_ran macro fcb WRITE_RAN dx.offset fcb mov mov ah,22H :function 22H int -21H endm file_size macro fcb ;FILE_SIZE dx,offset fcb mov mov ah.23H :function 23H 21H int endm

```
;
set_relative_record macro fcb
                                  :SET_RELATIVE_RECORD
          dx.offset fcb
  mov
          ah.24H
                                  :function 24H
  mov
  int
          21H
  endm
ï
set_vector macro interrupt, seg_addr, off_addr ;SET_VECTOR
  push
         ds
  mov
         ax, seq_addr
  mov
         ds.ax
  mov dx,off_addr
         al,interrupt
  mov
         ah.25H
                                  :function 25H
  mov
          21H
  int
  endm
ran_block_read macro fcb,count,rec_size;RAN_BLOCK_READ
          dx.offset fcb
  mov
  mov
          cx,count
          word ptr fcb[14], rec_size
  mov
          ah,27H
                                  :function 27H
  mov
  int
          21H
  endm
ran_block_write macro fcb,count,rec_size;RAN_BLOCK_WRITE
          dx,offset fcb
  mov
  mov
          cx,count
          word ptr fcb[14], rec_size
  mov
                                  :function 28H
          ah,28H
  mov
          21H
  int
  endm
```

parse macro filename, fcb ;PARSE mov si, offset filename mov di,offset fcb push es push ds pop es al,OFH mov mov ah,29H ;function 29H 21H int pop es endm ; get_date macro ;GET_DATE ah.2ÅH mov ;function 2AH int 21H endm ; set_date macro year, month, day :SET_DATE mov cx,year mov dh,month mov dl,day mov ah,2BH :function 2BH 21H int endm ; get_time macro :GET_TIME mov ah,2CH ;function 2CH int 21H endm SET_TIME ; set_time macro hour, minutes, seconds, hundredths mov ch,hour mov cl, minutes mov dh,seconds mov dl, hundredths mov ah,2DH ;function 2DH int 21H endm

```
VERIFY
verify macro switch
              al.switch
  mov
                                    :function 2EH
              ah.2EH
  mov
              21H
  int
  endm
;
                                    ;GET_DTA
get_dta macro
              ah,2FH
  mov
              21H
  int
  endm
;
                                    :GET_VERSION_NUM
get_version_num macro
  mov
              ah,30H
              21H
  int
  endm
keep_process macro exitcode, parasize ;KEEP_PROCESS
              al, exitcode
  mov
              dx, parasize
  mov
              ah,31H
  mov
  int
               21H
  endm
                                    ;CTRL_C_CHECK
ctrl_c_check macro switch,val
               d1,val
   mov
   mov
               al.switch
              ah,33H
   mov
               21H
   int
   endm
;
                                     ;GET_VECTOR
get_vector macro interrupt
               al, interrupt
   mov
               ah.35H
   mov
   int
               21H
   endm
                                     GET_DISK_SPACE
get_disk_space macro drive
               d1,drive
   mov
               2h,36H
   mov
               21H
   int
   endm
```

```
get_country_info macro buffer, country ;GET_COUNTRY_INFO
  mov
               dx,offset buffer
  mov
               al,country
                                     ;country = 0
               ah,38H
  mov
  int
               21H
  endm
mkdir macro name
                                     ;MKDIR
              dx.offset name
  mov
              ah,39H
  mov
  int
               21H
  endm
;
rmdir macro name
                                     :RMDIR
  mov
              dx,offset name
  mov
               ah,3AH
  int
               21H
  endm
chdir macro name
                                     :CHDIR
  mov
              dx,offset name
  mov
              ah,3BH
  int
              21H
  endm
;
create_file macro name,attrib
                                    :CREATE_FILE
  mov
              dx.offset name
  mov
              cx, attrib
  mov
              ah,3CH
  int
              21H
  endm
open_handle macro name,access
                                    ;OPEN_HANDLE
              dx,offset name
  mov
  mov
              al, access
              2h,3DH
  mov
  int
              21H
  endm
```

```
close_handle macro handle
                                     CLOSE_HANDLE
               bx,handle
  mov
               2h,3EH
  mov
  int
               21H
  endm
;
read_from_handle macro buffer, bytes, handle
                                     :READ_FROM_HANDLE
               dx,offset buffer
  mov
               cx, bytes
  mov
               bx.handle
  mov
               ah,3FH
  mov
  int
               21H
  endm
write_to_handle macro buffer, bytes, handle
                                     ;WRITE_TO_HANDLE
               dx,offset buffer
  mov
               cx.bytes
  mov
               bx,handle
  mov
               ah.40H
  mov
               21H
  int
  endm
;
                                     ;ERASE
erase macro name
               dx,offset name
  mov
               ah.41H
  mov
               21H
  int
  endm
;
move_pointer macro highword,lowword,switch,handle
                                     :MOVE_POINTER
  mov
               dx,lowword
               cx, highword
  mov
               al,switch
  mov
               bx,handle
  mov
               ah,42H
  mov
               21H
  int
  endm
```

```
change_attrib macro name,attrib,switch ;CHANGE_ATTRIB
   mov
               dx,offset name
   mov
               cx,attrib
   mov
               al.switch
   mov
               2h,43H
  int
               21H
  endm
io_ctrl_dev macro handle, buffer, bytes, switch
                                     ;IO_CTRL_DEV
  mov
               bx.handle
                                     ;or 8-bit drive number
  mov
               dx.offset buffer
               cx, bytes
  mov
  mov
               al,switch
  mov
               ah.44H
  int
               21H
  endm
duplicate_handle macro handle
                                     ;DUPLICATE_HANDLE
  mov
               bx.handle
  mov
               ah.45H
  int
               21H
  endm
force_handle macro old, new
                                     FORCE_HANDLE
  mov
              bx.old
  mov
               cx,new
  mov
               ah,46H
  int
               21H
  endm
cur_dir_name macro buffer,drive
                                     CUR_DIR_NAME
  mov
              si,offset buffer
  mov
              d1,drive
  mov
              ah,47H
  int
              21H
  endm
```

```
:ALLOC_MEM
alloc_mem macro size
              bx.size
  mov
              ah.48H
  mov
              21H
  int
  endm
                                 :FREE_MEMORY
free_memory macro address
              ax.address
  mov
  mov
              es,ax
              ah,49H
  mov
              21H
  int
  endm
;
modify_memory macro address,size ;MODIFY_MEMORY
  mov
              ax,address
  mov
              es.ax
              bx,size
  mov
              ah.4ÅH
  mov
              21H
  int
  endm
                                  :EXEC
exec macro path, param, switch
              dx, offset path
  mov
             bx,offset param
  mov
              al,switch
  mov
              ah,4BH
  mov
  int
              21H
  endm
;
                                  :TERMINATE_PROCESS
terminate_process macro code
  mov
              al,code
  mov
              ah,4CH
              21H
  int
  endm
;
                                  :RETRIEVE_CODE
retrieve_code macro
              ah,4DH
  mov
              21H
  int
  endm
```

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find_match macro name,attrib ;FIND_MATCH mov dx.offset name mov cx,attrib mov ah.4EH int 21H endm step_match macro ;STEP_MATCH mov ah.4FH int 21H endm check_verify_flag macro ;CHECK_VERIFY_FLAG mov ah.54H int 21H endm ; rename macro old, new ;RENAME mov dx.offset old mov di,offset new mov ah,56H int 21H endm date_time_of_file macro switch, handle, date, time :DATE_TIME_OF_FILE mov al,switch mov bx,handle mov cx,time mov dx,date mov ah,57H int 21H endm

```
*******
 General
move_string macro source, destination, num_bytes
                                       ;MOVE_STRING
   push
               es
                ax,ds
   mov
   mov
                es,ax
                si.offset source
    mov
                di, offset destination
    mov
                cx,num_bytes
    mov
rep movs
                es:destination,source
                es
    gog
    endm
;
;
convert macro value, base, destination ;CONVERT
        local
                table,start
                start
        imp
                "0123456789ABCDEF"
table
        db
start:
                al,value
        mov
        xor
                ah,ah
                bx,bx
        xor
        div
                base
                bl,al
        mov
                al,cs: table[bx]
        mov
                destination, al
        mov
                bl,ah
        mov
                al,cs: table[bx]
        mov
                destination[1],al
        mov
        endm
```

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		;CONVERT_TO_BINAR
	local	ten,start,calc,mult,no_mult
	jmp	start
ten	db	10
start:	mov	value,O
	xor	CX,CX
	mov	cl,number
	xor	si,si
calc:	xor	a x ,ax
	mov	al,string[si]
	sub	al,48
	cmp	cx,2
	jl	no_mult
	push	CX
	dec	CX
mult:	mul	cs:ten
	loop	mult
	pop	CX
no_mult:	add	value,ax
	inc	si
	loop	calc
	endm	
;	• • •	
convert_d	ate macro	dir_entry
	mov	dx,word ptr dir_entry[25]
	mov	cl,5
	shr	dl,cl
	mov	dh,dir_entry[25]
	and	dh,1fh
	xor	CX,CX
	mov	cl,dir_entry[26]
shr	cl,1	
add	cx,1980	

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ROM BIOS Service Routines

- Overview
- Conventions
- Interrupt Vector Listing
- Video Control
- Diskette Services
- Communications Services
- Keyboard Handling
- Printer Routines
- Miscellaneous ROM BIOS Services
- Bypassing the BIOS
- CONFIG.SYS

ROM BIOS Service Routines

Overview

This chapter describes the ROM BIOS service routines that are provided to perform the more low-level functions that you may need in your assembly language programs. Because these are low-level routines, they provide more direct access to the hardware than the DOS routines. However, they do not provide some of the protection and conveniences that the DOS routines give. Be sure to check the chapter on "System Calls" to make your choice between similar DOS and BIOS calls. Access to the BIOS service routines is through the 8086 software interrupts. The routines are called with conventions that are very similar to the conventions for calling DOS routines.

To issue a BIOS interrupt, use the Interrupt statement to select the desired interrupt:

INT 11H

Some interrupts, like Interrupt 11H (Equipment List), perform only one function. Others, like Interrupt 13H (Diskette Services), have several sub-functions that you can call. To select a subfunction, move the number of the sub-function into the AH register.

This chapter describes the register usage for each of the BIOS service routines. It is usually wise to save all important registers before calling a BIOS service routine.

Interrupt Vector List

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Interrupt Number (Hex)	Name
5	Print Screen
10	Video
11	Equipment Check
12	Determine Memory Size
13	Diskette
14	Communications
16	Keyboard
17	Printer
19	Bootstrap

Video Control

Introduction	The video controller on the standard AT&T Per- sonal Computer 6300 supports both monochrome and color monitors and produces text or graph- ics for both color and monochrome. Interrupt 10H has the BIOS services to support all of these modes. This section describes the details that pertain to each major type of video access.
Monochrome Text Mode	The monochrome text modes are mode 0 — 40x25 characters and mode 2 — 80x25 charac- ters. The monochrome text mode uses 32K start- ing at B8000H. For each screen position, there are two bytes in memory. The first byte is the ASCII code for the character to be displayed. The second byte is the "attribute" that specifies how the character is to be displayed. This attribute byte controls brightness, underlining, and blinking. The low order nybble of the attribute byte gov- erns the character being displayed according to the following table:
	¥-1
	Value Meaning

Value	Meaning
0	Character is black
1	Character is normal (white)
	intensity, underlined
7	Character is normal (white)
	intensity
\mathbf{F}	Character is high intensity white

Any other value for the low nybble selects a particular gray character intensity.

The high order nybble of the attribute byte governs the character background and blinking. A displayed character will blink if the high order bit of its attribute byte is set. The remaining ROM BIOS Service Routines

> three bits select the gray scale of the background — again, 000 is black and 111 is white. Note that inverse video can be obtained by forcing a black character on a white background, i.e. an attribute byte of 70H.

The first two bytes in the display memory control the character in the top left corner of the screen. The next two bytes control the character in the top row, in the second column position, and so on.

At the end of each line, the display memory returns to the first column of the next line. There are no gaps in the display storage, and no boundaries between one line and the next.

Eight pages of memory are used to build up to eight separate screens. Only one page is active at any time, but you can switch the active page number and thereby display screens very rapidly.

The display pages are numbered 0 - 7 for 40x25 mode and 0 - 3 for 80x25 mode. Page 0 starts at memory location B8000H. For 40 column mode, the pages occur at 2K intervals; for 80 column, at 4K intervals. A total of 32K of memory is used.

Color Text Modes

The color text modes are mode 1 - 40x25 color mode and mode 3 - 80x25 color.

Memory usage for the color text modes is similar to the method used for monochrome text. Two bytes of memory are used for each character position: the first is the ASCII code for the character and the second is the attribute byte. The attribute byte specifies blinking, brightness, and color.

The attribute bytes in color text mode operate much the same way as they do in monochrome text modes with two major differences:

• Instead of bits 0-3 and 4-7 selecting the gray scale of the foreground and background, they select foreground and background colors according to the following chart:

	E	Bit		
d	с	b	a	Color
0	0	0	0	Black
0	0	0	1	Blue
0	0	1	0	Green
0	0	1	1	Cyan
0	1	0	0	Red
0	1	0	1	Magenta
0	1	1	0	Brown
0	1	1	1	White
1	0	0	0	Grey
1	0	0	1	Lt. blue
1	0	1	0	Lt. green
1	0	1	1	Lt. cyan
1	1	0	0	Lt. red
1	1	0	1	Lt. magenta
1	1	1	0	Yellow
1	1	1	1	High intensity white

ROM BIOS Service Routines

	Note that since background color is determined by a three-bit value, only the first eight colors apply to that field.
•	There is no underline attribute possible in color mode. As can be seen by the chart above, attri- bute settings that produce an underline in monochrome mode produce a blue character in color mode.
	The display memory maps to the character posi- tions exactly as it does in monochrome text mode.
Color Graphics Mode	There is one color graphics mode: mode 4 — medium resolution (320x200) color graphics. For any color display, you can use up to four colors. You select from one of two "palettes," each of which provides three colors. You select a "back- ground" color to be used as the fourth color.
	Palette 0 contains green, yellow, and red. Palette 1 contains cyan (light blue), magenta, and white.
	320 pixels can be displayed on each of 200 lines. Each line takes 80 bytes or 640 bits of display memory. Each color pixel use two bits of memory. Since two bits give you four possible combinations, for each pixel you specify either the background color or one of the three colors in the current palette. The leftmost pixels are represented by the high order bits in the byte.

Display memory for color graphics mode starts at location B8000H and is divided into four 8K blocks. Starting at B8000, the first 8000D bytes contain the pixel data for the even scan lines on page zero. That is, the first 80 bytes describe line 0, the next 80H describe line 2, and so on through line 198. The odd lines are described in the 8K block starting at BA000. The same pattern is repeated for page one in the next 16K block, with the even lines starting at BC000 and the odd lines starting at BE000. High Memory for high resolution 640x200 mono-Resolution chrome graphics is handled similarly to 320x200 Monochrome color graphics. The only difference is that Graphics instead of memory containing two bits of color information per pixel, each pixel can only be on or off and is thus represented by one bit. In this way eight pixels can be represented in a byte instead of four, so that a scan line takes as many bytes as in color graphics mode even though it contains twice as many pixels. As in color graphics mode, the leftmost pixels are represented in the high order bits of each byte. Line mapping is exactly as described above for color graphics mode. In high resolution monochrome graphics the background color is always black and the foreground color is chosen by bits 0-3 of the color select register.

ROM BIOS Service Routines

Super High Resolution Monochrome Graphics

Super high resolution 640x400 monochrome graphics mode maps one bit per pixel with the leftmost pixel represented at the high end of the byte, just like high resolution 640x200 mode. Also like high resolution mode, super high mode maps onto a black background with a foreground color chosen by the color select register. The memory mapping, however, takes up all 32K of display memory for a single page. Memory is broken up into four 8K segments, with each segment containing the data for every fourth scan line. Thus display memory looks like this:

Memory

location	Contains pixels for line numbers
B8000	0, 4, 8, 396
B9F3F	Not used.
BA000	1, 5, 9, 397
BBF3F	Not used.
BC000	2, 6, 10, 398
BDF3F	Not used.
BE000	3, 7, 11, 399
BFF3F	Not used.

Set Mode and Clear Screen	Input: (AH) = 0 (AL) contains the CRT mode value Text Modes: (AL) = 0 40x25 monochrome (AL) = 1 40x25 color (AL) = 2 80x25 monochrome (AL) = 3 80x25 color
	Graphics modes: (AL) = 4 320x200(medium resolution), color (AL) = 5 320x200(medium resolution), monochrome (AL) = 6 640x200 black/white (high resolution) (AL) = 40H graphics 640x400 monochrome super high resolution (AL) = 48H graphics 640x400 monochrome tiny text (80x50 text)
Set Cursor Type	Input: (AH) = 1 Low order 5 bits of (CH) = start line for cursor. Note Do not set the high bits of CH: unpredictable results will occur. Low order 5 bits of (CL) = end line for cursor.
Set Cursor Position	Input: (AH) = 2 (DH,DL) = Row,Column (Position 0,0 is upper left.) (BH) = page number (must be 0 for super-res graphics mode.)

Read Cursor Position	Input: (AH) = 3 (BH) = page number (must be 0 for super-res graphics mode.) Output: (DH,DL) = row, column of current cursor (CH,CL) = current cursor start and end lines
Read Light Pen Position	Input: (AH) = 4 Output: (AH) = 0 light pen switch not triggered (AH) = 1 valid light pen value obtained: (DH,DL) = row, column of character light pen position (CH) = raster line (0-199) (BX) = pixel column (0-319 for medium resolution, 0-639 for high resolution.)
Select Active Page Number	Valid only for modes $(0 - 6)$ Input: (AH) = 5 (AL) = 0-15 for modes 0, 1 = 0-7 for modes 2, 3 = 0.1 for modes 4, 6

= 0-1 for modes 4, 6

•

Scroll Active Page up	<pre>Input: (AH) = 6 (AL) = number of lines blanked at bottom of window by scrolling up. AL = 0 means blank entire window. (CH,CL) = row, column of upper left corner of scroll (DH,DL) = row, column of lower right corner of scroll (BH) = attribute to be used on blank line(s).</pre>
Scroll Active Page Down	<pre>Input: (AH) = 7 (AL) = number of lines blanked at top of window by scrolling down. AL = 0 means blank entire window. (CH,CL) = row, column of upper left corner of scroll (DH,DL) = row, column of lower right corner of scroll (BH) = attribute to be used on blank line(s).</pre>
Character Handling	The next three video services perform character input/output for the CRT. If your program dis- plays characters to the screen while in graphics modes, the characters are formed from a charac- ter generator image that is maintained in the ROM. However, only the first 128 characters are encoded there. If you want to create your own characters, either for the purposes of doing character graphics or implementing a foreign language alphabet, you must set up a table of code points for 128 new characters and initialize the pointer at interrupt 1F (address 0007CH) to point to the 1K table. These codes can then be accessed by referring to characters 128-255.

	When you write characters to the screen in text mode, if you send more characters to be written than will fit on one line, the extra characters automatically wrap around to the beginning to the next line. In graphics mode, the character handling routines only produce correct results
	for characters contained on the same row (con- tinuation to succeeding lines does not work.)
Read Attribute or Character at Current Cursor Position	Input: (AH) = 8 (BH) = current display page Output: (AL) = character read (AH) = attribute of character read
Write Attribute and Character at Current Cursor Position	<pre>Input: (AH) = 9 (BH) = current display page (CX) = count of characters to write (AL) = character to write (BL) = attribute of character (if text mode)</pre>
Write Character Only at Current Cursor Position	Input: (AH) = OAH (BH) = current display page (CX) = count of characters to write (AL) = character to write

Set Color Pallette	Input: (AH) = OBH (BH) = color palette ID (0-127) (BL) = color value to be used with that color ID (BL) = 0 selects the background color (0-15) Color ID = 1 selects the palette to be used: 0 = green/red/yellow 1 = cyan/magenta/white
Write Dot	Input: (AH) = OCH (DX) = row number (CX) = column number (AL) = color value. If bit 7 of AL = 1, the color value is exclusive OR'd with the current contents of the dot.
Read Dot	Input: (AH) = ODH (DX) = row number (CX) = column number Output: (AL) = the dot read

Write Teletype	This routine is used by the "TYPE" command and other DOS commands to display data on the screen.
	Input: (AH) = OEH (AL) = character to write (BL) = foreground color in graphics mode
	Note Screen width is controlled by previous mode set.
Current Video State	Input: (AH) = OFH
	Output: (AL) = current mode (AH) = number of character columns on screen (BH) = current active display page

Diskette Services

Introduction	Interrupt 13H is the BIOS routine for diskette services. There are six services provided by INT 13H.
Input	 (AH) = 0 Reset Diskette System (AH) = 1 Read status of diskette system into AL (AH) = 2 Read sectors into memory (AH) = 3 Write sectors from memory to diskette (AH) = 4 Verify the specified sectors (AH) = 5 Format a track
	Additional settings for read, write, verify, and format:
	 (DL) = drive number (0 - 3 allowed, value checked) (DH) = head number (0 - 1 allowed, value not checked) (CH) = track number (0-39 allowed, value not checked)
	Additional settings for read, write, and verify:
	 (CL) = sector number (1-9, value not checked) (AL) = number of sectors (max = 9, value not checked)
	ES:BX = address of buffer (not required for verify) For the format operation, ES:BX points to the collection of address fields for the track. There must be one of these fields for every sector on the track. Each field has four bytes:
	Offset 0 = track number 1 = head number 2 = sector number 3 = number of bytes/ sector (00 = 128, 01 = 256, 02 = 512, 03 = 1024)

Output	(AH) = Status of operation:
	01 bad command
	02 address mark not found
	03 write was requested on write-protected disk
	04 requested sector not found
	08 DMA overrun
	09 DMA transfer crossed a 64K boundary
	10 read data error detected by CRC
	20 diskette controller chip failed
	40 seek to desired track failed
	80 device timeout
	(CY) = 0 successful operation (CY) = 1 unsuccessful operation (AH has details)
	For read, write, and verify these registers are preserved: DS, BX, DX, CH, and CL.
	(AL) = number of sectors read; this value may be incorrect if a timeout occurred.
	NOTE
	If an error is reported by the diskette, reset the diskette, then retry the operation. On read opera- tions, no motor start delay is taken, so your code should retry three times to make sure that a read error is not caused by motor start-up.

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Communications Services

Introduction	comn port. comn I/O.	nunications th You should us nunications; t	brough the se a polling his is not i	serial, RS232C communications g technique in your nterrupt-driven ed through BIOS
Initialize the Communica- tions Port	(AH) (DX)		for initial	
76 —Baud Rat	•	4 3 —Parity—	2 Stopbit	1 0 —Word length—
000 - 110 ba 001 - 150 010 - 300 011 - 600 100 - 1200 101 - 2400 110 - 4800	ud	00 - None 01 - Odd 11 - Even	0 - 1 1 - 2	10 - 7 bits 11 - 8 bits

111 - 9600

Output:

Condition is set according to the same conventions as in "Get Comm Port Status" (see below).

Send Character	Input: (AH) = 1 (DX) = RS232 channel to be used (0 or 1) (AL) = the character to be sent.
	Output: (AL) is preserved. (AH) — if the operation was unsuccessful, bit 7 is set. The other bits in (AH) are set as they are in "Get Comm Port Status" if the operation was successful.
Receive Character	<pre>Input: (AH) = 2 (DX) = RS232 channel to be used (0 or 1) Output: (AL) = the received character. (AH) = status of operation, if (AH) = 0, the oper- ation was successful. If the high order bit of (AH) is set, a timeout error aborted the operation and the rest of (AH) can be ignored. Any other setting of (AH) indi- cates errors in the receive character operation.</pre>

Get Comm	Input:
Port Status	(AH) = 3
	(DX) = RS232 channel to be used (0 or 1)
	Output
	(AX) = status:
	(AH) = line control status
	bit $7 = timeout$
	bit 6 = transmission shift reg. empty
	bit $5 =$ transmission holding reg. empty
	bit $4 = break detect$
	bit $3 =$ framing error
	bit $2 = parity error$
	bit 1 = overrun error
	bit $0 = $ data ready
	(AL) = modem status
	bit 7 = received line signal detect
	bit $6 = ringing detect$
	bit $5 = data$ set ready
	bit $4 = $ clear to send
	bit 3 = delta receive line signal detect
	bit $2 =$ trailing edge ring detected
	bit $1 = $ delta data set ready
	bit $0 = \text{delta clear to send}$

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Keyboard Handling

Introduction Interrupt 16H provides the keyboard handling functions through three sub-functions. Most keys return two values: a scan code and a character code. The scan code is the same as the key number (see diagram below), and the character code is the ASCII superset interpretation of the key (including coincident SHIFTs or CTRLs). Check the section on "DOS Interrupts and Function Calls" to select either the BIOS keyboard routines or the DOS routines.

F1 F2 3B 3C	ESC 1 2 3 4 5 6 7 8 9 0 = ± + NUM LOCK LOCK 01 02 03 04 05 06 07 08 09 A B C D E 145 46	
F3 F4 3D 3E	المستعلما ليشتعا لتثثيا لتشتعا لسنينا ليستعا لستعا ليستعا ليستعا ليستعا ليستعا ليستعا ليستعا ليستعا ليستعا ليس	4A
F5 F6 3F 40	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	
F7 F8	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	51
F9 F10 43 44	ALT CAPS LOCK INS DEL 53	

CHARACTER CODES

ASCII Decimal	Value Hex	Character	Control Character	ASCII Decimal	Value Hex	Character
000	00	(null)	NUL	032	20	(space)
001	01		SOH	033	21	!
002	02	ĕ	STX	034	22	"
003	03	¥	ETX	035	23	#
004	04	© ♥ ♥ ♥	EOT	036	24	\$
005	05	±	ENQ	037	25	%
006	06	±	ACK	038	26	&
007	07	(beep)	BEL	039	27	,
008	08		\mathbf{BS}	040	28	(
009	09	(tab)	\mathbf{HT}	041	29)
010	0A	(line feed)	\mathbf{LF}	042	2A	*
011	0B	(home)	VT	043	2B	+
012	0C	(form feed)	FF	044	2C	,
013	0D	(carriage	CR	045	2D	-
		return)				
014	$0\mathbf{E}$	53	SO	046	$2\mathrm{E}$	
015	$0\mathbf{F}$	¢	SI	047	2F	/
016	10		DLE	048	30	0
017	11	-	DC1	049	31	1
018	12	‡	DC2	050	32	2
019	13	!!	DC3	051	33	3
020	14	भ 9 ↓	DC4	052	34	4
021	15	9	NAK	053	35	5
022	16	1	SYN	054	36	6
023	17	Ī	\mathbf{ETB}	055	37	7
024	18	+	CAN	056	38	8
025	19	¥	$\mathbf{E}\mathbf{M}$	057	39	9
026	1 A	-	SUB	058	3 A	:
027	1B	◀	ESC	059	$3\mathbf{B}$;
028	1C	(cursor	\mathbf{FS}	060	3C	<
		right)				
029	1D	(cursor left)	\mathbf{GS}	061	3D	=
030	$1\mathrm{E}$	(cursor up)	\mathbf{RS}	062	3E	> ?
031	1F	(cursor	US	063	3F	?
		down)				

CHARACTER CODES (Cont'd)

ASCII Decimal	Value Hex	Character	Control Character	ASCII Decimal	Value Hex	Character
064	40	@		096	60	©
065	41	Ă		097	61	а
066	42	В		098	62	b
067	43	С		099	63	с
068	44	D		100	64	d
069	45	E		101	65	е
070	46	\mathbf{F}		102	66	f
071	47	G		103	67	g
072	48	Н		104	68	h
073	49	I		105	69	i
074	4A	J		106	6A	j
075	4B	K		107	6B	k
076	4C	\mathbf{L}		108	6C	1
077	4D	М		109	6D	m
078	$4\mathrm{E}$	Ν		110	6E	n
079	4F	0		111	6F	0
080	50	Р		112	70	р
081	51	Q		113	71	q
082	52	\mathbf{R}		114	72	r
083	53	S		115	73	S
084	54	Т		116	74	t
085	55	U		117	75	u
086	56	V		118	76	v
087	57	W		119	77	W
088	58	Х		120	78	х
089	59	Y		121	79	У
090	5A	Z		122	7A	Z
091	5B	[123	7B	{
092	5C	N		124	7C	k t
093	5D]		125	7D	}
094	5E	^		126	7E	~
095	5F			127	7F	

ASCII Decimal	Value Hex	Character	ASCII Decimal	Value Hex	Character
128	80	С	160	A0	á
129	81	С ü	161	A 1	í
130	82	é	162	A2	ó
131	83	â	163	A 3	ú
132	84	ä	164	A4	ñ
133	85	à	165	A5	${f \widetilde{n}}{f N}$
134	86	a	166	A6	
135	87	ç	167	A 7	a o v
136	88	¢ ê ĕ	168	A 8	- Z
137	89	ĕ	169	A9	—
138	8A	è	170	AA	
139	8B	й î Ă	171	AB	1/2
140	8C	1	172	AC	1⁄4
141	8D	1,	173	AD	i
142	$8\mathbf{E}$	A	174	\mathbf{AE}	«
143	8F	Å	175	\mathbf{AF}	»
144	90	É	176	B 0	3335
145	91	æ	177	B1	~~~
146	92	Æ	178	B2	
147	93	ô 0 0	179	B3	I
148	94	Ő	180	B4	-1
149	95	ò	181	B5	=
150	96	û u y Ö Ü	182	B6	-1
151	97	ù	183	B7	-т-
152	98	Ÿ,	184	B8	4
153	99	Ö	185	B9	Ŧ
154	9A		186	BA	N
155	9B	¢	187	BB	-1
156	9C	£	188	\mathbf{BC}	-1
157	9D	¥	189	BD	لا
158	9E	Pt	190	BE	_
159	9F	f	191	\mathbf{BF}	-

CHARACTER CODES (Cont'd)

ASCII Decimal	Value Hex	Character	ASCII Decimal	Value Hex	Character
192	C0	L	224	EO	α
193	C1	т	225	$\mathbf{E1}$	β
194	C2	T	226	$\mathbf{E2}$	Г
195	C3	F	227	E3	π
196	C4	_	228	$\mathbf{E4}$	Σ
197	C5	+	229	E5	σ
198	C6	Þ	230	E6	μ
199	C7	ŀ	231	$\mathbf{E7}$	τ
200	C8	Ŀ	232	$\mathbf{E8}$	ō.
201	C9	ſŕ	233	$\mathbf{E9}$	•
202	$\mathbf{C}\mathbf{A}$	<u>77</u>	234	EA	Ω
203	CB	<u> </u>	235	\mathbf{EB}	δ
204	$\mathbf{C}\mathbf{C}$	ŀ	236	\mathbf{EC}	∞,
205	CD	—	237	\mathbf{ED}	ø
206	CE	· 4F	238	\mathbf{EE}	E
207	\mathbf{CF}	<u> </u>	239	EF	\cap
208	D0	_11_	240	F0	=
209	D1	Ŧ	241	F1	±
210	D2		242	F2	\geq
211	D3	u	243	F3	≥ ≤
212	D4	E	244	F4	ſ
213	D5	F	245	F5	J
214	D6	π-	246	F6	÷
215	D7	H	247	$\mathbf{F7}$	*
216	D8	+	248	F8	0
217	D9	L	249	F9	•
218	DA	Г	250	FA	•
219	DB		251	\mathbf{FB}	\checkmark
220	DC	-	252	\mathbf{FC}	n
221	DD		253	\mathbf{FD}	2
222	DE	1	254	\mathbf{FE}	
223	DF		255	\mathbf{FF}	(blank)

Read Next ASCII Character	Input: (AH) = 0
Character	Output: (AL) = character code (AH) = scan code
	Note
	This routine will not return execution to the call- ing program until it has a keystroke to report.
Check if Keystroke Available	This routine is used to check to see if a keystroke has been entered. Use this function if you want to continue processing whether or not a key has been pressed.
	Input: (AH) = 1
	Output: Z flag = 1 — no code available Z flag = 0 — code is available If a character is available, it is stored in AX in the same format as for the "Read Next ASCII Character" call. However, the code also remains in the keyboard buffer, so that a "Read Next ASCII Character" call returns this character's code value again.

Get Current Input: **Shift Status** (AH) = 2

Output: (AL) = current shift status

Shift States

]	Bit	Subject matter	Meaning, when bit is 1
ł	7 6 5 4	Insert Caps-Lock Num-Lock Scroll-Lock	state active state active state active state active
ć	4 3 2 1 0	Alt shift Ctrl shift left-hand shift right-hand shift	key depressed key depressed key depressed key depressed

Printer Routines

		of BIOS routines communicates with ter through interrupt 17H.
Print a Character		he character to be printed rinter port number (0-3)
	C	if character not printed due to timeout. Otherwise, bits are set as they are in Get Printer Status" call.
Initialize Printer Port	Input: (AH) = 1 (DX) = p	rinter port number (0-3)
	Output: (AH) = p	rinter status (see below)
Get Printer Status	Input: (AH) = 2 (DX) = pr	rinter port number (0-3)
	Output:	
	Bit	Meaning if Set (equal to 1)
	7	not busy
	6	acknowledge
	5	out of paper
	4	selected
	3	I/O error
	2 1	not used not used
	$1 \\ 0$	timeout (set by software)
		er is connected, 10H and 90H are statuses. Otherwise 30H is healthy.

Miscellaneous ROM BIOS Services

System Reset	If you issue issue interrupt 19H, the system bootstraps itself in much the same way as it does with the Ctrl-Alt-Delete key sequence. The only difference is that Ctrl-Alt-Delete causes diagnostics to be run, whereas Interrupt 19H causes an immediate system load.
Print Screen	To obtain a printed copy of what is on the screen, issue a request for interrupt 5H. This produces exactly the same result as pressing the shift and PrtSc keys. This routine works in either text or graphics modes. Unrecognizable characters are printed as blanks.

List optional equipme Simply issue an i is necessary. Out		e this routine to obtain a list of the uipment attached to your system. ue an interrupt 11H; no register set-up y. Output (starting with the most sig- of (AX)) is as follows:
	Bit	Meaning
	AH 7-6 5 4 3-1 0	number of printer adapters (0-3) not used game adapter attached, or not number of communications adapters (0-7) not used
	AL 7-6 5-4 3-2	 number of diskette drives minus 1, if bit 0 is set. starting video mode: 01 — graphics card display,40 columns,b/w 10 — graphics card display,80 columns,b/w 11 —monochrome card display amount of memory on system board: 00 — 16KB Base 01 — 32KB Base 10 — 48KB Base 11 — 64KB Base not used diskettes are attached; refer to bits 7 and 6.
Determine Memory Size	in the addr ter set-up is switches or amount of board and	2H gives the total amount of memory ess space, up to a megabyte. No regis- required. The BIOS reads the the system board and adds the memory on a memory expansion returns the total in (AX). The amount is expressed as the number of 1K

This section explains how you can either replace one of the BIOS service routines with a program of your own or add a "front-end" so that you perform some preprocessing immediately prior to using a particular BIOS routine.

When the system is powered on, low memory is initialized with the addresses of all of the BIOS interrupt routines. To replace a BIOS routine, change the address in the interrupt table to the address of the code which you want to execute in place of the BIOS code. To perform preprocessing before handing execution on to the BIOS code:

- 1 replace the address of the BIOS routine with the address of your program
- 2 transfer execution to the BIOS routine at the end of your program.

Be sure to use the "Set Vector" system call (Function Request 25H) to replace the BIOS routine addresses instead of writing directly to low memory.

CONFIG.SYS

The special file CONFIG.SYS is processed automatically when DOS starts. As with the batch file AUTOEXEC.BAT, this processing is automatic. DOS will simply look at the root directory to see if the file is there.

CONFIG.SYS is a text file that can be edited by EDLIN or any other text editor that produces ASCII files. Five commands can be used in the CONFIG.SYS file. Each command changes a system parameter.

BREAK ON/OFF
 Changes the way DOS checks for a CTRL/BREAK

- **BUFFERS=xx** Sets the number of data buffers that DOS uses.
- **DEVICE**=[d:] [path] filename [.ext] Adds a nonstandard device driver to DOS.

FILES=xx

Sets the number of files that can use ASCIIZ strings.

- SHELL=[d:] [path] filename [.ext] [d:] [path] /P Specifies an alternate command processor.
- **Break** Normally, DOS checks for a CTRL/BREAK only when it is doing input or output. Some programs do very little (if any) input or output for long periods of time. The BREAK ON command sets DOS to check for a CTRL/BREAK when any DOS function is called.

	BREAK OFF resets the default so that DOS only checks for a CTRL/BREAK during input and output. This command can be used to over- ride a BREAK ON that was set by CONFIG SYS.
Buffers	The number of buffers has an effect on both the speed of disk I/O and available memory. A larger number of buffers allocates more memory to the system for operations. This is highly desirable for systems with large amounts of RAM that will be used for database applica- tions. It is highly undesirable for systems with minimal RAM that do little work with disk files.
	The system default is BUFFERS=2, which is adequate for most purposes and requires only 1K of RAM. If your system will be doing a signifi- cant amount of data handling, especially on a hard disk, BUFFERS=4 would improve access times at a cost of only 1K of internal memory.
Device	When DOS is first started, it loads all of the standard device drivers for the keyboard, screen and so on. If your system requires a special device driver, this command tells DOS where to find it. The device driver will then be loaded as an extension to DOS.
	Device drivers are .COM files with a specific structure described in Chapter 9. The command DEVICE=ANSI.SYS causes DOS to replace the standard display and keyboard device drivers with the extended screen and keyboard support that the extended functions require.

	If you wish to load several special device drivers, you must use a DEVICE command for each one.	
Files	Opening a file with an ASCIIZ string eliminates the traditional direct handling of a File Control Block (FCB). DOS will handle all these things for you by creating and maintaining FCBs internally. To do this, it needs memory. Each file requires 39 bytes of memory.	
	The FILES command sets aside memory for this operation. The default is FILES=8. The maxi- mum is FILES=99. This is the limit for the entire system. A particular process (or program) can still have only 20 files open at once.	
Shell	The COMMAND.COM file that DOS uses as its "front end" processor can be replaced by another command processor. The SHELL command spec- ifies the file to be used and the default path for processing commands. The command processor must be able to read and execute commands, and handle interrupts 22H, 23H, and 24H.	
	Since COMMAND.COM handles internal com- mands, .BAT file execution, and .EXE file load- ing, these functions will be unavailable unless the new command processor duplicates them.	

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9 MS-DOS Device Drivers

- Overview
- MS-DOS Device Drivers
- Asynchronous Communications Element
- DMA Controller
- Floppy Diskette Interface and Controller
- Hard Disk Controller
- Keyboard Interface
- Parellel Printer Interface
- Programmable Interrupt Controller
- Programmable Interval Timer
- Real Time Clock and Calendar
- Serial Communications Controller
- Speaker
- Video Controller

Overview

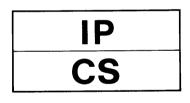
Interested Audience	This section contains information on how to write device drivers. You may not use it often since many input and output capabilities are implemented by the BIOS routines discussed in Section 6. BIOS routines allow you to do general input and output without a detailed understand- ing of the hardware and shield your program from hardware changes.						
	However, there are times when BIOS routines do not perform the necessary function or do so in an inefficient fashion. Then your own driver is necessary. Implementation of operating sys- tems, of high speed graphics packages, and of unusual keyboard mapping are examples of software which require specialized drivers.						
Pro- grammable	This is a list of programmable devices.						
	INS	8350B					
Devices	1110	0000D	Asynchronous Communications Element				
Devices	INTEL	8237A	Element DMA Controller				
Devices	INTEL NECE	8237A uPD765	Element DMA Controller Floppy Diskette Controller				
Devices	INTEL NECE DTC	8237A uPD765 5150BX	Element DMA Controller Floppy Diskette Controller Hard Disk Controller				
Devices	INTEL NECE	8237A uPD765	Element DMA Controller Floppy Diskette Controller				
Devices	INTEL NECE DTC INTEL	8237A uPD765 5150BX 8041	Element DMA Controller Floppy Diskette Controller Hard Disk Controller Keyboard Interface Programmable Interrupt				
Devices	INTEL NECE DTC INTEL INTEL	8237A uPD765 5150BX 8041 8259A 8253	Element DMA Controller Floppy Diskette Controller Hard Disk Controller Keyboard Interface Programmable Interrupt Controller Programmable Interval Timer				

Port Addresses	A port is a place to read or write information to an I/O device. An I/O device is hardware which the CPU controls. It is both input and output peripherals as well as hardware such as the DMA controller, the Interrupt controller and the Interval Timer. Each device needs different information, but they all need some combination of control, status, and data.			
	Each port has an address. Sixteen of the twenty possible address lines are available for I/O addressing. This means there are 65,535 possible port addresses.			
I/O Instructions	IN and OUT instructions distinguish an I/O access from a memory access. These instructions translate into control signals which define the direction and path of the data.			
	The port address can be specified in one of two ways — fixed or variable. In the fixed method, the absolute port address is specified in the instruction. The following instruction is an example of fixed port addressing:			
	OUT 020H, AL			
	Only 8-bit port addresses can be used in this format.			
	The variable method allows 16-bit port addresses to be specified. In this case, the port address is loaded into the DX register and then the DX register is used in the I/O instruction. An example of variable port addressing follows:			
	MOV DX,03F2H OUT DX,AL			

Interrupts External devices do not need the CPU's attention all the time. When they need servicing, they ask for it either by interrupting or by setting a polled flag. External interrupts are ignored when the CLI instruction has cleared the interrupt enable flag and are recognized when the STI instruction has set the flag.

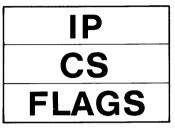
> The first 1024 bytes of memory contain an interrupt table. This table has 255 interrupt pointers defining the start address of interrupt service routines. This is the pointer format.

INTERRUPT POINTER



When the CPU recognizes the interrupt, an 8-bit interrupt type identifies the device. The interrupt type is an index into the table of pointers. To obtain the interrupt pointer address, the type is multiplied by four. The CPU saves the flag register on the stack, disables interrupts and single step mode, and saves the CS and IP registers on the stack. Then the interrupt pointer is loaded into IP and CS, and control is transferred to the interrupt service routine. The stack looks like this when the service routine gets control. Interrupt Devices

SYSTEM STACK



When the service routine begins, interrupts are disabled. Depending on the nature of the application, interrupts can be enabled immediately or just prior to releasing control.

The service routine must preserve the value of all internal registers. Therefore it saves the registers it uses on the stack. Before returning, it restores these registers from the stack.

To return control to the interrupt program, the service routine executes IRET. All the information necessary to do this was carefully placed on the stack

Interrupt Devices	INS	8250B	Asynchronous Communi- cations Element
	INTEL	8237A	DMA Controller
	NEC	uPD765	Floppy Diskette Controller
	DTC	5150BX	Hard Disk Controller
	INTEL	8041	Keyboard Interface
	INTEL	8259A	Programmable Interrupt
			Controller
	INTEL	8253	Programmable Interval
			Timer
		58174A	Real Time Clock and
			Calendar
	AMD	Z8530	Serial Communications
			Controller

Block Diagrams

Block diagrams are a pictorial description of the electrical connection between the CPU, the interface, and the external device. In general, the CPU's bus signals appear on the left. The middle of the diagram describes the internals of the interface. The right side of the diagram describes the electrical interface. This physically connects the interface to the external device. The connection is often through a dual inline package (DIP) of pins. Each pin carries one signal.

Individual signals are represented by lines. Busses are shown as double lines. Each of these have arrows which indicate the direction of the data. Often they are bidirectional.

There are several common CPU control bus signals. There mnemonics and definitions follow:

• A0-A19

These are the lines used to transmit the address of memory or the address of an I/O port. Only A0-A15 are used for I/O addressing.

• CS

This signal selects the chip. No reading or writing will occur unless the device is selected.

• D0-D7

These are the bidirectional data lines used to exchange information with a memory location or an I/O port. D7 is the most significant bit.

• INT0-INT7

These are the priority interrupt request lines. See the description of the Interrupt Controller. • IORD

This signal indicates that an input port address has been placed on the address bus. The data at the specified port is to be placed on the data bus.

• IOWR

This signal indicates that an output port address has been placed on the address bus and the data has been placed on the data bus to be output to the specified port.

• RESET

This signal resets the system to a predetermined state.

MS-DOS Device Drivers

What Is A device driver is binary code which manipua Device lates hardware in the MS-DOS environment. A Driver? special header at the beginning identifies it as a driver, defines the strategy and interrupt entry points, and describes various attributes of the device. The file must have an origin of zero. There are two kinds of devices: Character devices Block devices Character devices perform serial character I/O like CONSOLE, AUXILIARY, and PRINTER. These devices are named and users open channels to do I/O to them. Block devices are the disk drivers on the system. They perform random I/O in pieces called blocks. This is usually the physical sector size. These devices are not named as the character devices are, and cannot be opened directly. Instead they are identified by drive letters (A:.B:.C:. etc.). Drive letters are assigned to device drivers based on their ordering in the CONFIG.SYS file. Starting with the letter 'A', each device driver is assigned as many consecutive alphabetic characters as the driver has units. The theoretical limit is 63, but after 26 the drive letters are nonalphabetic (such as] and ^). Character devices cannot define multiple units because they have only one name.

Headers	A device header is required at the beginning of a device driver. A device header looks like this: DWORD pointer to next device (Must be set to -1)
	WORD attributes Bit 15 = 1 if char device, 0 if blk if bit 15 is 1 Bit 0 = 1 if current sti device Bit 1 = 1 if current sto device Bit 2 = 1 if current NUL device Bit 3 = 1 if current CLOCK dev Bit 4 = 1 if special Bits 5-12 Reserved; must be set to 0 Bit 14 is the IOCTL bit Bit 13 is the NON IBM FORMAT bit
	WORD pointer to device strategy entry point
	WORD pointer to device interrupt entry point
	8-BYTE character device name field Character devices set a device name. For block devices the first byte is the number of units
	The strategy and interrupt routines are in the same segment as this device header.

MS-DOS Device Drivers

The pointer to the next device header field is a Pointer to Next Device double word field, offset followed by segment. MS-DOS chains the device headers together Field using this field. If you have a single device header in your driver, initialize this field to -1. If you have more than one device header, the first word of the double word pointer is the offset of the next driver's Device Header. The attribute field is used to tell the system Attribute Field whether this device is a block or character device (Bit 15). Most other bits are used to give selected character devices special treatment and are meaningless on a block device. For example, assume that you have a new standard input and output device driver. Besides installing the driver, you must tell MS-DOS that you want this new driver to override the current standard input and standard output device. This is accomplished by setting the attributes to the desired characteristics, so you set Bits 0 and 1 to 1. Similarly, a new CLOCK device could be installed by setting the appropriate attribute. Although there is a NUL device attribute, it is reserved for MS-DOS. The NON PC-DOS FORMAT bit applies only to block devices and affects the operation of the BUILD BPB (Bios Parameter Block) device call. The implementation of all block devices is PC-DOS software and hardware compatible. The IOCTL bit is meaningful for both types of devices. This bit tells MS-DOS whether the device can handle control strings with the IOCTL system call. Function 44H.

	If a driver cannot process control strings, this bit is 0. MS-DOS returns an error if an attempt is made to handle control strings. A device which can process control strings sets the IOCTL bit to 1. For drivers of this type, MS-DOS calls IOCTL INPUT and OUTPUT device func- tions to send and receive IOCTL strings.
	The IOCTL functions allow data outside of the normal user's reads and writes to be sent to the driver. The interpretation of this information is up to the driver.
Strategy and Interrupt Routines	These two fields are the entry points of the strat- egy and interrupt routines. They are word values and they must be in the same segment as the Device Header.
Name Field	This 8-byte field contains the name of a charac- ter device or the number of units of a block device. If it is a block device, the number of units can be put in the first byte. This is optional because MS-DOS fills in this location with the value returned by the driver's INIT code.
How to Create a Device Driver	To create a device driver, write a binary file with a Device Header at the beginning of the file. The code originates at 0.

	MS-DOS always processes installable device drivers before handling the default devices. To install a new CON device, simply name the device CON. Remember to set the standard input device and standard output device bits in the attribute word on the new CON device. The scan of the device list stops on the first match, so the installable device driver takes precedence. MS-DOS installs the driver anywhere in
	memory; therefore, be careful with memory ref- erences. Do not expect the driver to be loaded in the same place.
Installation of Device Drivers	MS-DOS allows new device drivers to be installed dynamically at boot time. This is accomplished by INIT code in the BIOS which processes the CONFIG.SYS file.
	At load time, DOS searches the root directory for a file named CONFIG.SYS. Declare the files containing your device drivers using the DEVICE command.
	DEVICE = [C:] [path] filename [.ext]
	DOS loads your drivers as an extension of itself. Include a separate DEVICE command for each driver to be loaded.

Request Header

When MS-DOS calls a device driver to perform a function, it passes a Request Header in ES:BX to the strategy entry point. This is a fixed length header followed by data pertinent to the operation being performed. It is the device driver's responsibility to preserve the machine state. For example, save all registers on entry and restore them on exit. There is enough room on the stack when strategy or interrupt is called to do about 20 pushes. If more stack is needed, the driver sets up its own stack.

The following figure illustrates a Request Header.

REQUEST HEADER ->

BYTE length of record (the length in bytes of pertinent data, plus the length of this Request Header)

BYTE unit code The subunit the operation is for (minor device) (no meaning on character devices)

BYTE command code

WORD status

8 bytes **RESERVED**

Unit Code

If your device driver has three units, then the possible values of the unit code field are 0, 1, and 2.

Command Code Field		ommand code field in the Request Header ave the following values:
С	ommand	
\mathbf{C}	ode	Function
0		INIT
1		MEDIA CHECK
		(Block only, NOP for character)
2		BUILD BPB "
3		IOCTL INPUT
		(Only called if device has IOCTL)
4		INPUT (Read)
5		NON-DESTRUCTIVE INPUT NO WAIT
		(Char devices only)
6		INPUT STATUS "
7		INPUT FLUSH "
8		OUTPUT (Write)
9		OUTPUT (Write) with verify
1(0	OUTPUT STATUS "
11	1	OUTPUT FLUSH "
12	2	IOCTL OUTPUT
		(Only called if device has IOCTL)

Status Word The following figure illustrates the status word in the Request Header.

1	5	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
F F F	5 2 2	I	RES	ER	VEI)	B U S	D O N		EF		~-	ג C 5 מ	-		

The status word is set by the driver interrupt routine.

Bit 8 is the done bit. When set, it means the operation is complete.

Bit 15 is the error bit. If it is set, then the low 8 bits indicate the error. The errors are:

- 0 Write protect violation
- 1 Unknown Unit
- 2 Drive not ready
- 3 Unknown command
- 4 CRC error
- 5 Bad drive request structure length
- 6 Seek error
- 7 Unknown media
- 8 Sector not found
- 9 Printer out of paper
- A Write fault
- **B** Read Fault
- C General failure

Bit 9 is the busy bit which is set only by status calls.

- For output on character devices: If bit 9 is 1 on return, a write request waits for completion of a current request. If it is 0, there is no current request and a write request starts immediately.
- For input on character devices with a buffer: If bit 9 is 1 on return, a read request goes to the physical device. If it is 0 on return, then there are characters in the device buffer and a read returns quickly. MS-DOS assumes all character devices have an input type-ahead buffer. Devices that do not have a type-ahead buffer return busy=0 so that MS-DOS does not wait for nonexistent buffer input.

Media Check and Build BPB

MEDIA CHECK and BUILD BPB are used with block devices only. MS-DOS calls MEDIA CHECK first for a drive unit and passes its current media descriptor byte. MEDIA CHECK returns one of the following results:

- Media Not Changed current DPB and media byte are OK.
- Media Changed Current DPB and media are wrong. MS-DOS invalidates buffers for this unit and calls the device driver to build the BPB.
- Not Sure If there are dirty buffers for this unit, MS-DOS assumes the DPB and media byte are OK. If nothing is dirty, MS-DOS assumes the media has changed. It invalidates buffers for the unit and calls the device driver to build the BPB.
- Error If an error occurs, MS-DOS sets the error code.

MS-DOS calls BUILD BPB under the following conditions:

- If Media Changed is returned
- If Not Sure is returned and there are no dirty buffers
- **Init Routine** The Init Routine is called only once when the device is installed. It returns a location DS:DX which is a pointer to the first free byte of memory after the device driver. To save space, this pointer method can be used to delete initialization code that is only used once.

Additional information that block drivers return is:

- The number of units
- A pointer to a BPB
- The media decriptor

The number of units determines the logical device names. This mapping is determined by the position of the driver in the device list and by the number of units on the device.

BPB blocks are used to build an internal MS-DOS data structure for each of the units. The driver passes MS-DOS a pointer to an array of n word BPB pointers, where n is the number of units. If all units are the same, they can share a BPB to save space. This array must be before the free space pointer since MS-DOS builds an internal DOS structure starting at this free byte. The defined sector size must be less than or equal to the maximum sector size defined at INIT time; otherwise, the install fails.

The media descriptor byte means nothing to MS-DOS. It is passed to drivers so that they know what parameters MS-DOS is currently using for a drive unit.

Block devices are either dumb or smart. A dumb device defines a unit and an internal DOS structure for each possible media drive combination. For example, unit 0 =drive 0 single side, unit 1 =drive 0 double side. In this case, media descriptor bytes mean nothing.

A smart device allows multiple media per unit.
In this case, the BPB table returned by INIT
defines space large enough to accommodate the
largest possible media supported. Smart drivers
use the media descriptor byte to pass informa-
tion about the media currently in a unit.

Function
CallStrategy routines are called with ES:BX point-
ing to the Request Header. The interrupt rou-
tines get the pointers to the Request Header
from the queue that the strategy routines store
them in. The command code in the Request
Header tells the driver which function to
perform.

All DWORD pointers are stored offset first, then segment.

INIT

Command code = 0

INIT - ES:BX ->

13-BYTE Request Header
BYTE # of units
DWORD break address
DWORD pointer to BPB array (Not set by character devices)

The number of units, break address, and BPB pointer are set by the driver. On entry, the DWORD points to the character after the '=' on the line in CONFIG.SYS. This allows drivers to scan the CONFIG.SYS invocation line for arguments. If there are multiple device drivers in a single .COM file, the ending address returned by the last INIT is the one MS-DOS uses. All of the device drivers in a single .COM file return the same ending address.

Media Check Command Code = 1

MEDIA CHECK - ES:BX ->

13-BYTE	Request Header
BYTE med	ia descriptor from DPB
BYTE retur	rned

In addition to setting the status word, the driver sets the return byte to one of the following:

- -1 Media has been changed
- 0 Don't know if media has been changed
- 1 Media has not been changed

If the driver can return -1 or 1 because it has a door-lock or other interlock mechanism, MS-DOS performance is enhanced because MS-DOS does not need to reread the FAT for each directory access.

Build BPB (BIOS Parameter Block)	Command code = 2 BUILD BPB - ES:BX -> 13-BYTE Request Header
	BYTE media descriptor from DPB
	DWORD transfer address (Points to one sector worth of scratch space or first sector of FAT depending on the value of the NON PC-DOS FORMAT bit)
	DWORD pointer to BPB
	If the NON PC-DOS FORMAT bit is 1, then the DWORD transfer address points to a sector scratch buffer.

If the NON PC-DOS FORMAT bit is 0, then this buffer contains the first sector of the first FAT and the driver must not alter this buffer.

The first sector of the first FAT must be located in the same sector for all media. This is because the FAT sector is read BEFORE the media is actually determined. Use this mode to read the FAT ID byte.

In addition to setting status word, the driver must set the pointer to the BPB on return.

To allow different OEMs to read each other's disks, the information relating to the BPB for the media is kept in the boot sector of the media. The format of the boot sector is:

	3 BYTE near JUMP to boot code						
	8 BYTES OEM name and version						
	WORD bytes per sector						
	BYTE sectors per allocation unit						
	WORD reserved sectors						
B	BYTE number of FATs						
P B	WORD number of root dir entries						
В	WORD number of sectors in logical image						
	BYTE media descriptor						
	WORD number of FAT sectors						
	WORD sectors per track						
	WORD number of heads						
	WORD number of hidden sectors						

Sectors per track, number of heads, and number of hidden sectors are optional. They are intended to help the BIOS understand the media. Sectors per track may be redundant since it can be calculated from total size of the disk. Number of heads supports different multi-head drives with the same storage capacity but a different number of surfaces. Number of hidden sectors supports drive-partitioning schemes.

Media Descriptor Byte	The last two digits of the FAT ID byte are called the media descriptor byte. Currently, the media descriptor byte has been defined for a few media types.				
	Bit	Meaning			
	0	1 = 2 sided;	0 = not 2 sided		
	1	1 = 8 sector;	0 = not 8 sector		
	2	1 = removable;	0 = not removable		
	3-6	must be set to 1			
	7	1 = not 80 track;	0 = 80 track		
	5 1/4" d FEh FCh FFh FDh 7Dh	160K 180K 320K	formatted single sided formatted single sided		
	HDU:	F8h			
		-	bytes map directly to FAT e F8-FF, media bytes can		

Although these media bytes map directly to FAT ID bytes which must be F8-FF, media bytes can, in general, be any value in the range 0-FF.

Read or Write	Command codes = 3,4,8,9, and 12 READ or WRITE - ES:BX (Including IOCTL) ->				
	13-BYTE Request Header				
	BYTE media descriptor from DPB				
	DWORD transfer address				
	WORD byte/sector count				
	WORD starting sector number (Ignored on character devices)				
	In addition to setting the status word, the driver				

In addition to setting the status word, the driver must set the sector count to the actual number of sectors (or bytes) transferred. No error check is performed on an IOCTL I/O call. The driver must set the return sector (byte) count to the actual number of bytes transferred.

A user program can not request an I/O of more than FFFFH bytes and cannot wrap around in the transfer segment.

Non	Command code = 5	
Destructive		
Read No Wait	NON DESTRUCTIVE READ NO WAIT - ES:BX ->	
	13-BYTE Request Header	

BYTE read from device

If the character device returns busy bit = 0 (characters in buffer), then the next character that would be read is returned. This character is not removed from the input buffer, hence the term Non Destructive Read. Basically, this call allows MS-DOS to look ahead one input character.

Status Command codes = 6 and 10

STATUS Calls - ES:BX ->

13-BYTE Request Header

The driver sets the status word and the busy bit as follows:

- For output on character devices: If bit 9 is 1 on return, a write request waits for completion of a current request. If it is 0, there is no current request and a write request starts immediately.
- For input on character devices with a buffer: A return of 1 means a read request goes to the physical device. If it is 0 on return, then there are characters in the device's buffer and a read returns quickly. A return of 0 also indicates that the user has typed something. MS-DOS assumes that all character devices have an input typeahead buffer. Devices that do not have a typeahead buffer return busy = 0 so that the DOS does not wait for something to get into a nonexistent buffer.

Flush

Command codes = 7 and 11

FLUSH Calls - ES:BX ->

13-BYTE Request Header

The FLUSH call tells the driver to terminate all pending requests. This call is used to flush the input queue on character devices.

Clock Device One of the special enhancements for the Safari-3 is the battery-backed 58174A clock-calender chip and related driver. This chip is integrated into the system as the CLOCK device and is accessed with the TIME and DATE command.

This CLOCK device defines and performs functions like any other character device. When a read or write to this device occurs, exactly 6 bytes are transferred. The first two bytes are the count of days since 1-1-80. The third byte is minutes, the fourth, hours, the fifth, hundredths of seconds, and the sixth, seconds.

Reading the CLOCK device gets the date and time; writing to it sets the date and time.

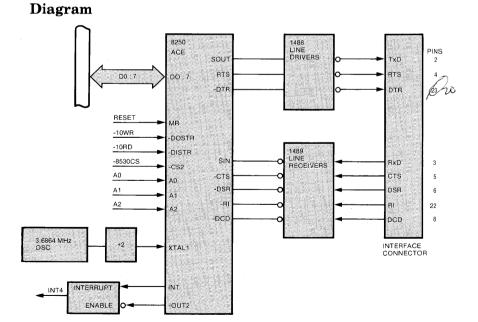
Asynchronous Communications Element

Functional Description

Block

The Asynchronous Communications Element (ACE) performs serial-to-parallel conversion on input data characters received from a modem and parallel-to-serial conversion on output data characters received from the CPU. You can read the status of transfer operations at any time. This device gives you modem control capability.

The baud rate and serial interface characteristics are programmable. The ACE has a softwaretailored interrupt system whose interrupt request is on INT4.

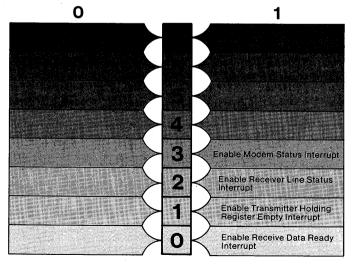


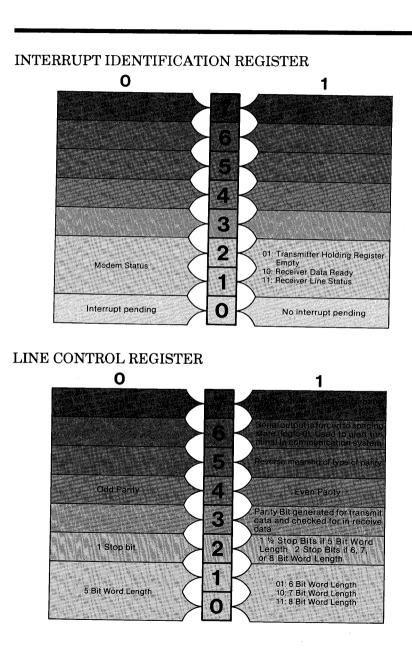
Registers

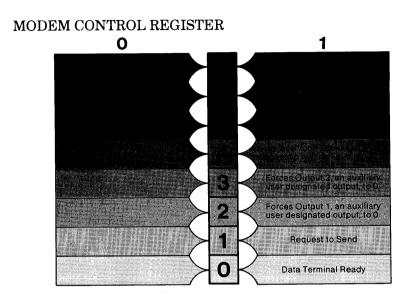
PORT A	В	NAME	READ/ WRITE	DESCRIPTION
3F8	2F8	DATA	R∕W W	Receive Buffer, Transmitter Holding Register
3F9	2F9	INTERRUPT ENABLE	W	See layout
3FA	2FA	INTERRUPT IDENTIFICATION	R	See layout
3FB	2FB	LINE CONTROL	R/W	See layout
3FC	2FC	MODEM CONTROL	R/W	See layout
3FD	2FD	LINE STATUS	R	See layout
3FE	2FE	MODEM STATUS	R/W	See layout
3FF	2FF	SCRATCH	R/W	Scratch pad register
3F8	2F8	DIVISOR LATCH	W	Least significant byte
3F9	2F9	DIVISOR LATCH	W	Most significant byte

Layout

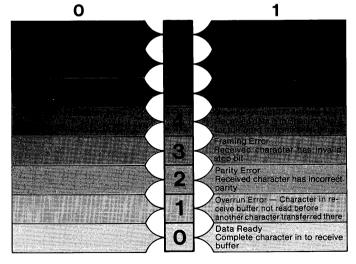
INTERRUPT ENABLE REGISTER

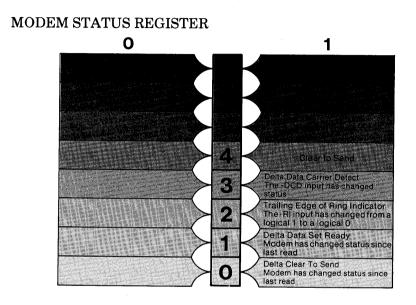






LINE STATUS





- **Functions** IDENTIFY INTERRUPTS INPUT: INTERRUPT IDENTIFICATION REGISTER
 - READ LINE STATUS INPUT: LINE STATUS REGISTER
 - READ MODEM STATUS INPUT: MODEM STATUS REGISTER
 - RECEIVE CHARACTER INPUT: DATA
 - SEND CHARACTER OUTPUT: DATA

٠	SET BAUD RATE To set the baud rate, you load the divisor which yields the correct rate (16 x divisor = clock fre- quency (1.8432 MHz)/baud rate x 16)
	OUTPUT: LINE CONTROL REGISTER BIT 7 = 1 DIVISOR LATCH - Least significant byte DIVISOR LATCH - Most significant byte
•	SET INTERRUPTS OUTPUT: INTERRUPT ENABLE REGISTER
٠	WRITE LINE CONTROL CHARACTERISTICS OUTPUT: LINE CONTROL REGISTER
•	WRITE MODEM CONTROL CHARACTERISTICS OUTPUT: MODEM CONTROL REGISTER
Sequencing and Timing	To transmit a character, first issue a Request to Send and Data Terminal Ready to the Modem Control Register. Then wait for the Modem Stat- us to have Data Set Ready and Clear to Send set. When the Transmitter Holding Register is empty as indicated in the Line Status Register, write the character to the data register.
	To receive a character, set Data Terminal Ready in the Modem Control Register. Then wait for Data Set Ready in the Modem Status Register. When Data Ready in the Line Status Register is set, input the character from the data register.

The following table states the divisors to use to obtain a given baud rate.

BAUD RATES USING 1.8432 MHz CLOCK

DIVISOR
1047
768
384
192
96
64
58
48
32
24
16
12

If you wish to use the break control feature to alert a terminal in a communication system, the following sequence assures that no erroneous or extraneous characters are transmitted.

- Load an all 0's pad character into the transmitter holding register.
- Set break when the transmitter holding register is empty.
- Wait for transmitter empty (Bit 6 = 1 in Line Status Register) and clear break.

Note that the transmitter operates normally during a break sequence and can be used as a character timer to establish an accurate break length.

If the ACE is programmmed to interrupt, the interrupt is on INT4. The ACE acknowledges the highest priority interrupt as indicated in this chart. The Interrupt Identification Register states which interrupt is pending.			
TYPE	SOURCE – RESET		
Receiver Line Status	Overrun Error — Read Line Status Register		
Received Data Ready Transmitter Holding Register Empty Modem Status	Parity Error Framing Error Break Interrupt Receive Data Ready — Read data Transmitter Holding — Write data Register Empty Clear To Send — Read Modem Status Register Data Set Ready Ring Indicator Data Carrier Detect		

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Sample Program	;This program sets the b LINE_CTL EQU 3FB DVSR_L EQU 3F8 DVSR_M EQU 3F9	DVSR_L EQU 3F8		
	SET_BAUD: MOV AL,080H MOV DX,LINE_CTL OUT DX,AL	;access divisor ;latch		
	MOV AX,096 MOV DX,DVSR_L	divisor for 1200 baud;		
	OUT DX,AL	;least significant byte		
	MOV DX,DVSR_M MOV AL,AH OUT DX,AL	;most significant byte		
	XOR AL,AL MOV DX,LINE_CTL OUT DX,AL RET	;turn off access to latch		

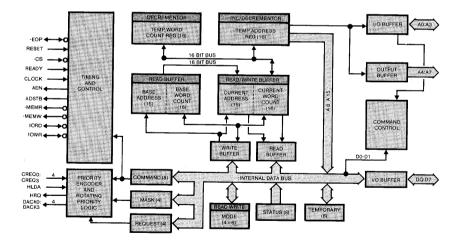
DMA Controller

Functional Description	The DMA controller allows devices to transfer data directly to and from memory without CPU involvement. It has four channels.
	Channel 0 has the highest priority and is used to refresh memory. The Interval Timer is pro- grammed to periodically request a dummy DMA transfer. This creates a memory read cycle which refreshes memory.
	Channel 1 is available on the I/O expansion bus to support high speed transfer between I/O devices and memory. Channel 3 has the lowest priority.
	Channel 3 is dedicated to the hard disk con- troller. Channel 2 is dedicated to the floppy disk controller.
	The DMA controller has four transfer modes. Single transfer mode makes only one transfer. Block transfer mode continues transferring until the count goes from 0 to FFFFH. Demand transfer allows transfers to continue until the I/O device has exhausted its capacity. The cas- cade mode allows more than one DMA controller to be used and is not applicable in the AT&T Personal Computer 6300.
	When autoinitialize is requested, the original values of the Current Address and Current Count registers are restored at the end of the operation.

The DMA controller has two types of priority schemes. The fixed scheme bases the priority on the descending value of their numbers. In this scheme, Channel 3 has the lowest priority. The second scheme is rotating priority. The last channel to get service becomes the lowest priority channel.

Compressed Timing allows greater throughput by compressing the transfer time into two clock cycles.





Registers

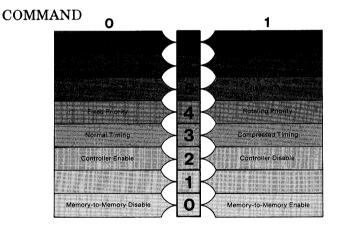
PORT	NAME	READ/ WRITE	DESCRIPTION
0	CHANNEL 0 ADDRESS	w	16 bit address
1	CHANNEL 0 COUNT	W	1's complement of # of bytes
			to transfer
0	CHANNEL 0 CURRENT ADDRESS		16 bit address
1	CHANNEL 0 CURRENT COUNT	R	1's complement of # of bytes to transfer
2	CHANNEL 1 ADDRESS	W	16 bit address
3	CHANNEL 1 COUNT	W	1's complement of # of bytes
			to transfer
2	CHANNEL 1 CURRENT ADDRESS		16 bit address
3	CHANNEL 1 CURRENT COUNT	\mathbf{R}	1's complement of # of bytes
			to transfer
4	CHANNEL 2 ADDRESS	W	16 bit address
5	CHANNEL 2 COUNT	W	1's complement of # of bytes
			to transfer
4	CHANNEL 2 CURRENT ADDRESS		16 bit address
5	CHANNEL 2 CURRENT COUNT	R	1's complement of # of bytes to transfer
6	CHANNEL 3 ADDRESS	W	16 bit address
7	CHANNEL 3 COUNT	W	1's complement of # of bytes to transfer
6	CHANNEL 3 CURRENT ADDRESS	R	16 bit address
7	CHANNEL 3 CURRENT COUNT	R	1's complement of # of bytes
•			to transfer
8	STATUS	R	See layout
8	COMMAND	W	See layout
9	REQUEST	W	See layout
Α	SINGLE MASK	W	See layout
В	MODE	W	See layout
С	CLEAR FLIP/FLOP	W	Execute prior to read or
			write of address or count
D	TEMPORARY	R	Contains last byte of
			memory-to-memory transfer

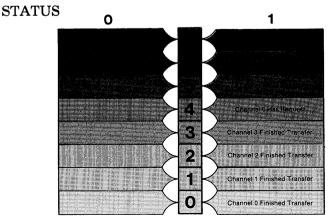
Registers

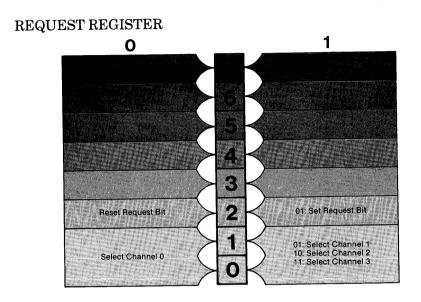
- D MASTER CLEAR
- E CLEAR MASK
- F WRITE ALL MASK
- 80 CHANNEL 0 SEGMENT
- 82 CHANNEL 1 SEGMENT
- 81 CHANNEL 2 SEGMENT
- 83 CHANNEL 3 SEGMENT

Layout

- W Any write clears controllerW Clear mask, all channels
 - accept DMA commands
- W See layout
- W Address segment nybble

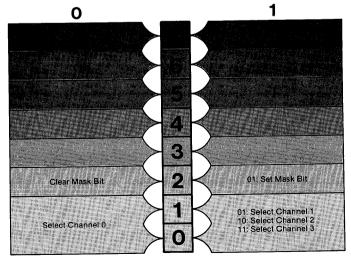


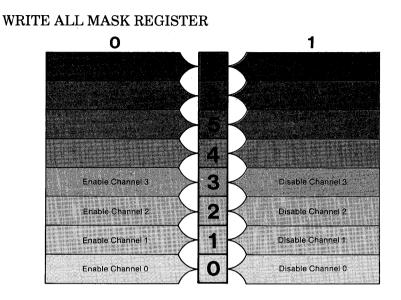




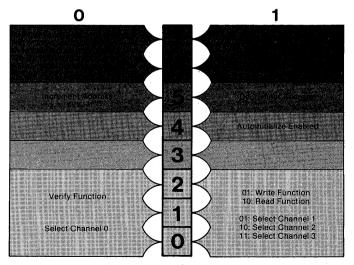
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MARK REGISTER





MODE



Functions • DISABLE CONTROLLER This function disables the controller. OUTPUT: COMMAND REGISTER BIT 2 = 1

• MASTER CLEAR CONTROLLER This function clears the controller. The Command, Status, Request, Temporary and Flip/Flop Registers are cleared. OUTPUT: MASTER CLEAR

DMA READ, WRITE OR VERIFY • This function sets up the controller to do the desired operation. **OUTPUT: CLEAR FLIP/FLOP** MODE REGISTER BITS 0-1 channel **BITS 2-3 function** BIT 4 autoinitialize BIT 5 address increment or decrement BITS 6-7 mode ADDRESS REGISTER 16 BIT address, first output the LSB and then the MSB SEGMENT NYBBLE One nybble. The significant nybble of the segment register is in bits 12-15. Rotate to Bits 0-3 before output. COUNT REGISTER 16 bit 1's complement of the # of bytes. First output the LSB and then the MSB.

- REQUEST DMA SERVICE This is a software request for DMA services. OUTPUT: REQUEST REGISTER
- READ STATUS This function reads the channel status. INPUT: STATUS REGISTER
- WRITE COMMAND REGISTER This function controls the operation of the DMA controller. OUTPUT: COMMAND REGISTER
- WRITE ALL MASK REGISTER This function enables and disables automatic DMA transfer for all channels. OUTPUT: WRITE ALL MASKS REGISTER
- WRITE MASK REGISTER This function enables and disables automatic DMA transfers for a channel. OUTPUT: MASK REGISTER
- WRITE MODE REGISTER This function specifies the mode for the specified channel. OUTPUT: MODE REGISTER
 - CLEAR MASKS This function clears all the masks so that all channels accept DMA commands. OUTPUT: CLEAR MASK REGISTER

Sequencing and Timing	When the system is powered-up, it is recom- mended that all mode registers be set with valid data even if the channel is not used.		
	Before loading the address and count registers, disable the controller (BIT 2 of COMMAND REGISTER) or mask the channel. This prevents erroneous transfers before a complete address is loaded.		
	A write to the Clear Flip/Flop sets the controller so that an access to an address or count is to the upper and lower byte in the correct sequence.		
Sample Program	;This program initializ ;at start-up COMMAND EQU MODE EQU INIT_CHAN: MOV AL,04H OUT COMMAND,A MOV AL,041H OUT MODE,AL RET	J B ;disable controller	

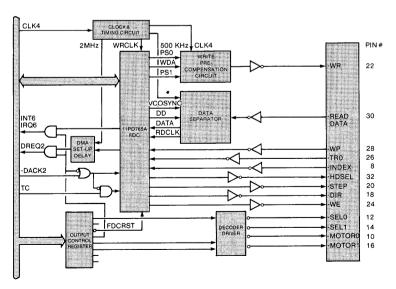
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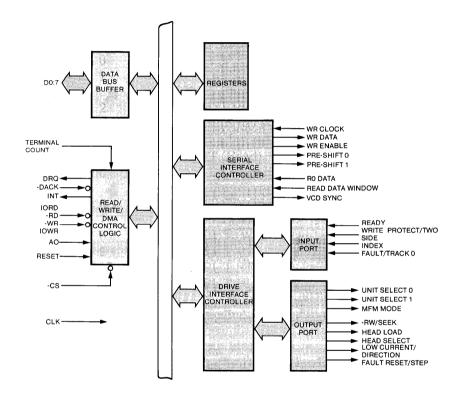
Floppy Diskette Interface and Controller

Functional Description	The diskette interface and NEC uPD765 con- troller read and write 5 1/4 inch diskettes on as many as two drives. Single density (FM) or dou- ble density (MFM) formats are supported. Single density diskettes contain 163,840 bytes and dou- ble density diskettes contain 327,680 bytes.
	Each sector on the diskette contains an ID field and the Data field. The ID field contains the cylinder number, the head number, the sector number and the number of bytes per sector.
	The diskette controller performs 15 separate functions. It operates in either DMA or non-

DMA mode. Interrupts can be enabled on INT6.

Block Diagrams





Registers

PORT NAME

3F2 I	INTERFACE	OUTPUT	CONTROL
-------	-----------	--------	---------

- 3F4 FDC MAIN STATUS REGISTER
- 3F5 FDC DATA

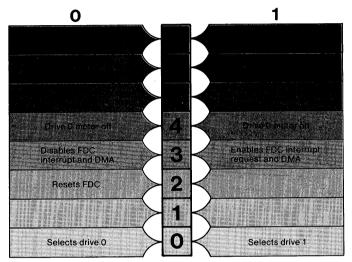
READ/ WRITE

DESCRIPTION

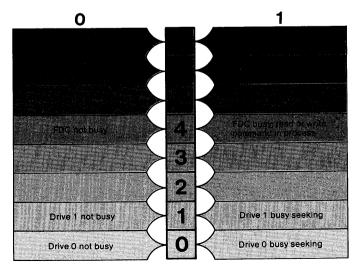
- W See layout
- R See layout
- R/W Transfers data, commands, parameters, and status

Layout

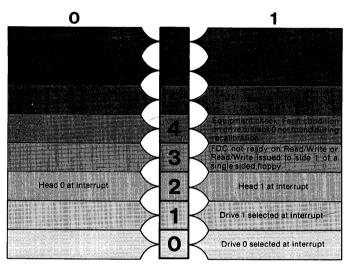
INTERFACE OUTPUT CONTROL



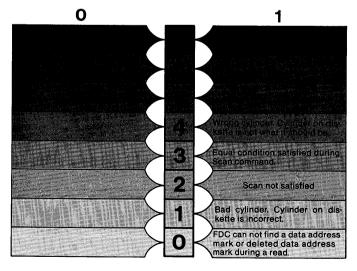
FDC MAIN STATUS REGISTER (MSR)



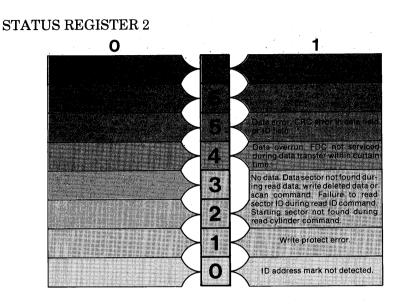
STATUS REGISTER 0



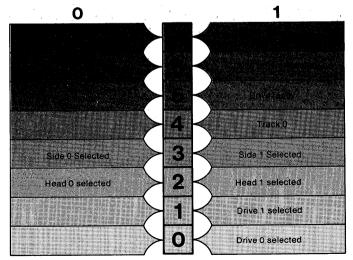
STATUS REGISTER 1



Floppy Diskette Interface and Controller



STATUS REGISTER 3



Parameters

SYMBOL	NAME	DESCRIPTION
DTL	Data Length	Only applies when there are 128 bytes per sector. If so, number of bytes to read or write. Otherwise, DTL = FF.
EOT	End of Track	Last sector number on cylinder. If there are 8 sectors per cylinder, then EOT = 8 .
GPL	Gap Length	Gap 3 length between sectors. Different for format and read/write commands.
HD	Head	Selected Head number.
HLT	Head Load Time	4ms to 508ms in 4ms increments for 8Mhz clock. In this case, 4ms.
HUT	Head Unload Time	Oms to 480ms in 32ms increments for 8Mhz clock. This is the amount of time to wait after a read or write before the heads are unloaded. If a new command is issued quickly, this saves head load time.
MF	MF or MFM Mode	0 = MF, 1 = MFM
МТ	Multi-track	MT = 1, multi-track operation. After com- pleting an operation on side 0, the FDC con- tinues on side 1.
Ν	Number of bytes/ sector	0 = 128 bytes, $1 = 256$ bytes, $2 = 512$ bytes 3 = 1024 bytes
ND	Non-DMA	$0 = DMA \mod 1 = \text{non-DMA mode}$
SRT	Step Rate Time	32ms to 2ms in 2 ms increments for 8Mhz clock. This is the amount of time to move the head from track to track. At 48 TPI, SRT = 6 ms. At 96 TPI, SRT = 4ms.
ST0-ST3	Status Registers	See layout
STP	Scan Test Flag	STP = 1, sector by sector compare STP = 2, alternate sectors
US0,US1	Unit Select	USx = 0, drive not selected USx = 1, drive selected

Equipment check, and not ready

Functions FORMAT A TRACK • This function formats an entire track. The ID Field for each sector is supplied by the programmer during the execution phase. **OUTPUT:** 0 MF 0 0 0 1 1 1 0 HDUS1 US0 0 0 0 0 Number of bytes/sector Sector/track Gap Length Filler Byte EXECUTION: Sector ID Field transfer Status Register 0 INPUT: Status Register 1 Status Register 2 Cvlinder Head Sector Number of bytes/sector POSSIBLE

ERRORS:

9.51

READ DATA • This function reads data from the diskette.

OUTPUT:

MT	MF	SK	0	0	1	1	0
0	0	0	0	0	HD	US1	US0

Cylinder Head Sector Number of bytes/sector End of Track Gap Length Data Length **EXECUTION:** Data Transfer Status Register 0 Status Register 1 **Status Register 2** Cylinder Head Sector Number of bytes/sector

INPUT:

POSSIBLE ERRORS:

No data, data error, data error in data field, and control mark • READ DELETED DATA This function reads deleted data.

OUTPUT:

MT	MF	SK	0	1	1	0	0
0	0	0	0	0	HD	US1	US0

EXECUTION: INPUT:	Cylinder Head Sector Number of bytes/sector End of Track Gap Length Data Length Data Transfer Status Register 0 Status Register 1 Status Register 2 Cylinder Head Sector Number of bytes/sector
----------------------	---

• READ ID

This function reads the first correct sector ID field.

OUTPUT:

0	MF	0	0	1	0	1	0
0	0	0	0	0	HD	US1	US0

EXECUTION: INPUT:

Status Register 0 Status Register 1 Status Register 2 Cylinder Head

Sector	
Number of bytes/se	ctor

POSSIBLE	-
ERRORS:	Missing address mark and
	no data

READ TRACK •

This function reads all data fields from the index hole to EOT. The FDC continues reading even if it finds a CRC error in the ID or data fields.

OUTPUT

OUTPUT:	-							
001101.	0	MF	SK	0	0	0	1	0
	0	0	0	0	0	HD	US1	US0
EXECUTION: INPUT:	Hea Sect Nur End Gar Dat Stat Stat Stat Cyl: Hea Sect	tor nber l of T o Len a Lei a tra tus R tus R tus R inder id	of by rack gth ngth nsfe egist egist	r ter (ter 2	0 1 2			
POSSIBLE ERRORS:					ror	and	missi	ng
	add	ress	marl	X				

• RECALIBRATE This function positions the head to head 0, cylinder or track 0.

•										
OUTPUT:										
	0	0	0	0	0		1	1		1
	0	0	0	0	0	($\mathbf{S1}$	U	$\mathbf{S0}$
EXECUTION:			Hea	ad r	epo	siti	onec	ł		
POSSIBLE ERRORS:	Equipment check									
• SCAN EQUAL This function scans for an equal data compare.										
OUTPUT:	MT	Μ	IF S	SK	1	0	0	0)	1
	0	()	0	0	0	HD	US	51	US0
EXECUTION: INPUT:	Cyli Hea Sect Nun End Gap Con Data Stat Stat Stat Stat Cyli Head Sect Nun	d or off Len tigu a tra us I us I us I nde d	r of trac ngtl ious ans: Regi Regi r	k h fer ister ister ister	alte c 0 c 1 c 2	rna	ite s	ecto	ors	1

• SCAN LOW OR EQUAL This function scans for a low or equal data compare.

OUTPUT:

MT	MF	SK	1	1	0	0	1
0	0	0	0	0	HD	US1	US0

	Cylinder
	Head
	Sector
	Number of bytes/sector
	End of track
	Gap Length
	Contiguous or alternate sectors
EXECUTION:	Data transfer
INPUT:	Status Register 0
	Status Register 1
	Status Register 2
	Cylinder
	Head
	Sector
	Number of bytes/sector

• SCAN HIGH OR EQUAL This function scans for a high or equal data compare.

OUTP	UT:
------	-----

MT	MF	SK	1	1	1	0	1
0	0	0	0	0	HD	US1	US0

EXECUTION: INPUT:	Cylinder Head Sector Number of bytes/sector End of track Gap Length Contiguous or alternate sectors Data transfer Status Register 0 Status Register 1 Status Register 1 Status Register 2 Cylinder Head Sector Number of bytes/sector
----------------------	--

• SEEK

This function positions the head at the requested cylinder.

OUTPUT:

0	0	0	0	1	1	1	1
0	0	0	0	0	HD	US1	US0

New cylinder number EXECUTION: Heads repositioned

• SENSE DRIVE STATUS This function obtains the current drive status.

OUTPUT:

.0	0	0	0	0	1	0	0
0	0	0	0	0	HD	US1	US0

INPUT:

Status Register 0

• SPECIFY

This function defines the drive parameters.

OUTPUT:

0	0	0	0	0	0	1	1
	S	SRT			HU'	Г	
HLT							ND

• WRITE DATA This function writes data.

OUTPUT:

MT	MF	0	0	0	1	0	1
0	0	0	0	0	HD	US1	US0

	Cylinder
	Head
	Sector
	Number of bytes/sector
	End of Track
	Gap Length
	Data Length
EXECUTION:	Data Transfer
INPUT:	Status Register 0
	Status Register 1
	Status Register 2
	Cylinder
	Head
	Sector
	Number of bytes/sector

• WRITE DELETE DATA This function writes deleted data.

OUTPUT:

МТ	MF	0	0	1	0	0	1
0	0	0	0	0	HD	US1	US0

EXECUTION: INPUT:	Cylinder Head Sector Number of bytes/sector End of Track Gap Length Data Length Data Transfer Status Register 0 Status Register 1 Status Register 2 Cylinder Head Sector Number of bytes/sector
----------------------	---

Sequencing and Timing There are three phases to each function:

- command The programmer writes the required information to the FDC.
- execution The FDC performs the operation.
- result The programmer reads the FDC's status.

Before any data can be read or written to the FDC the Main Status Register (MSR) must be read to determine the status of Bit 6 and Bit 7. In the command phase, Bit 6 must be 0 and Bit 7 must be 1. In the result phase both bits must be 1. You must wait 12 usec after a data read or write before reading the MSR.

In the command phases, all output must be written. The same is true in the result stage. All status information must be read.

During the execution phase, the FDC operates in DMA mode or non-DMA mode. In DMA mode, there is one interrupt at the end of the phase. In non-DMA mode, there is an interrupt after the transfer of each byte. In the format command, the ID field information for all the sectors in a track is sent to the FDC (cylinder, head, sector and bytes/sector). In DMA mode, 4 DMA requests per sector are issued. In non-DMA mode, there are 4 interrupts per sector. If interrupts cannot be handled every 13 ms in MFM mode or every 27 ms in FM then the FDC is polled. When polling, Bit 7 in the MSR functions just like the interrupt.

When it is not executing a command, the FDC polls the drives looking for a change in drive ready. If there is a change, the FDC interrupts. You can determine the cause of the unexpected interrupt with the Sense Drive Status function.

The drive motors should be off when the drives are not in use. However, they must be on prior to a drive select.

During the execution phase of read and write commands, the following occurs:

- The heads are loaded if unloaded.
- The FDC waits for the head settle time to elapse.
- The FDC begins reading the ID address marks and ID field.
- When the requested sector number compares with the one on the diskette, the transfer begins.
- After completion of the transfer, the FDC waits the head unload time before unloading the heads.

The amount of data that can be transferred in	n
one instruction depends on MT, MF, and N.	

Multi-Track	MFM/FM	Bytes/Sector	Maximum Transfer
MT	MF	N	(Bytes/Sector)(Number of Sectors)
0	0	00	128*26 = 3,328 $256*26 = 6,656$
0	1	01	
1	0	00	128*52 = 6,656 $256*52 = 13,312$
1	1	01	
0	0	01	256*15 = 3,840
0	1	02	512*15 = 7,680
1	0	01	256*30 = 7,680
1	1	02	512*30 = 15,360
0	0	02	512*8 = 4,096
0	1	03	1024*8 = 8,192
1	0	02	512*16 = 8,192
1	1	03	1024*16 = 16,384

If a read or write terminates on error, then the values for cylinder, head, sector, and number of bytes per cylinder depends on the state of MT and EOT.

МТ	HD	LAST SECTOR TRANSFERRED EOT	ID INF C	ORMATIC H	ON IN RE S	SULTS N
0	0	Less than EOT	NC	NC	S+1	NC
0	0	Equal to EOT	C+1	NC	S=1	NC
0	1	Less than EOT	NC	NC	S+1	NC
0	1	Equal to EOT	C+1	NC	S=1	NC
1	0	Less than EOT	NC	\mathbf{NC}	S+1	NC
1	0	Equal to EOT	NC	LSB	S=1	NC
1	1	Less than EOT	NC	NC	S+1	NC
1	1	Equal to EOT	C+1	LSB	S= 1	NC

NC = No Change

LSB = Least Significant Bit

The Write Deleted Data is the same as Write Data except that the FDC writes a Deleted Data Address mark at the beginning of the Data Field instead of the normal Data Address Mark. When reading deleted data, the FDC sets the CM error in Status Register 2 and reads the data. A Read Data would not read the data. If SK = 1, then the FDC skips the sector with the Deleted Data Address mark and reads the next one.

The Gap Length is different for read, write, and format commands. This table suggests appropriate values.

FORMAT	SECTOR SIZE	N	SC .	GPL(1)	GPL(2)
FM	128	00	12	07	09
FM	128	00	10	10	19
\mathbf{FM}	256	01	08	18	30
FM	512	02	04	46	87
\mathbf{FM}	1024	03	02	C8	\mathbf{FF}
\mathbf{FM}	2048	04	01	C8	\mathbf{FF}
MFM	256	01	12	$0\mathbf{A}$	0C
MFM	256	01	10	20	32
MFM	512	02	08	2A	50
MFM	1024	03	04	80	F0
MFM	2048	04	02	C8	\mathbf{FF}
MFM	4096	05	01	C8	\mathbf{FF}

GPL(1) - Suggested GPL in read and write commands GPL(2) - Suggested GPL in format commands

> The scan commands terminate when a scan condition is met, last sector on the track is reached, or a terminal count is received. The DMA issues the terminal count when it has no more data to send. This chart determines the result of the scan.

COMMAND	STATUS			COMMEN	Г
·	BIT	2 BIT 3			
SCAN EQUAL	0	1	DISKETTE	DATA = PROCH	ESSOR DATA
SCAN EQUAL	1	0	DISKETTE	DATA >< PRO	CESSOR DATA
SCAN LOW OR EQU		1	DISKETTE	DATA = PROCH	ESSOR DATA
SCAN LOW OR EQU		0	DISKETTE	DATA < PROCE	ESSOR DATA
SCAN LOW OR EQU		0	DISKETTE	DATA > PROCH	ESSOR DATA
SCAN HIGH OR EQ		1	DISKETTE	DATA = PROCE	ESSOR DATA
SCAN HIGH OR EQ		0	DISKETTE	DATA > PROCH	ESSOR DATA
SCAN HIGH OR EQ	UAL 1	0	DISKETTE	DATA < PROCH	ESSOR DATA

Scans allow the compare to be on contiguous sectors (STP = 1) or alternate sectors (STP = 2). However, for normal termination of the command the last sector on the track must be compared.

When a seek is requested, the FDC checks its current position and decides in which direction to move. Then step pulses are issued to move the heads. The speed of the pulse is controlled by the Step Rate Time in the Specify function. While the drive is seeking, the seek bit in the MSR is set. It must be cleared by Sense Interrupt Status at the completion interrupt. While a drive is seeking, the FDC is not busy. Another seek command to the other drive can be requested.

Interrupts occur as the result of:

- Entering Result Phase of: Read Data Read Track Read Deleted Data Write Data Write Deleted Data Format Track Scans
- 2) The execution phase in non-DMA mode
- 3) The Drive Ready line changing state
- 4) The end of Seek or Recalibrate

When the latter two occur, a Sense Drive Status determines the cause of the interrupt. It is mandatory to follow Seek and Recalibrate functions with a Sense Drive Status. This chart shows how to interpret the results of a Sense Drive Status.

STATUS REGIST BIT 5 BIT 6	ER 0 BIT 7	CAUSE
0 1	1	Ready line changed state
1 0	0	Normal termination of Seek or
1 1	0	Recalibrate Abnormal termination of Seek or Recalibrate

	The Specify command de Head Unload Time (HUT from 32ms to 480ms in in Therefore 1 = 32ms, 2 = 6 The Step Rate Time is pro to 32ms in increments of 2ms, E = 4ms, and 1 = 32 Time is programmable fr increments of 4ms. In thi 8ms, 7F = 508ms.	 is programmable crements of 32ms. 4ms, and F = 480ms. ogrammable from 2ms 2ms. In this case, F = ms. The Head Load om 4ms to 508ms in
Sample Program	; GET_RESULTS ; This subroutine obtains ; of status information in ; INPUT: ES:DI points to the ; the status bytes	the result phase.
	; NEC_STATUS EQU 3F	4
	GET_RESULTS: MOV CX,7 GET1: MOV DX, NEC_STATUS IN AL,DX TEST AL,080H JZ GET1 TEST AL,40H JZ GET2 INC DX IN AL,DX STOSB DEC CX JNZ GET1	;max. bytes in status ;port address of MSR ;get MSR ;Data register ready to ;send or receive ;jump if not ready yet ;direction bit ;jump if wrong ;direction ;port addr of data ;register ;get one byte of status ;move it to status area ;maximum number ;jump if not max yet
	GET2:RET	

Hard Disk Controller

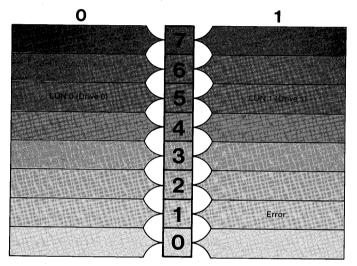
Functional Description	The DTC-5150BX hard disk controller reads and writes to a maximum of two standard $5 \ 1/4$ " Winchester disk drives. A sector size of 256, 512, or 1024 bytes is selectable. The sectors can be interleaved in 16 different ways.
	The hard disk controller operates in DMA or non-DMA mode. Interrupts can be enabled on INT5.
	Extensive diagnostics are implemented. If a cor- rectable data error is discovered, the error is automatically corrected using ECC.

Registers

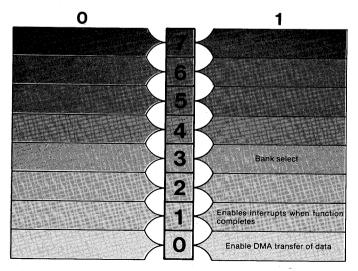
PORT #	* NAME	READ/ WRITE	DESCRIPTION
320	COMPLETION STATUS REGISTER	R	See layout
320	DATA	R/W	Transfers data, function bytes, and controller sense bytes. See layout.
321	RESET CONTROLLER	W	Initialize Controller
321	STATUS	R	See layout
322	SELECT CONTROLLER	W	Select Controller
322	DRIVE TYPE	\mathbf{R}	See layout
323	CONTROL REGISTER	W	See layout

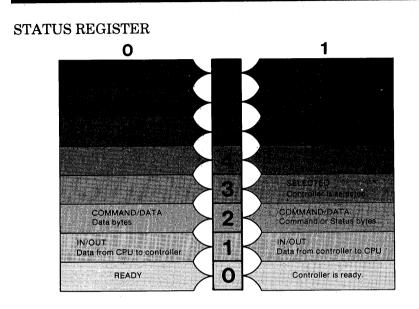
Layout

COMPLETION STATUS REGISTER

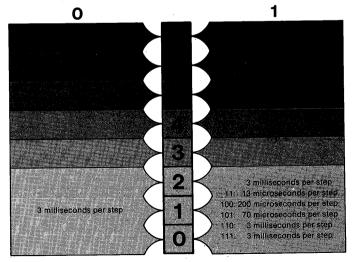


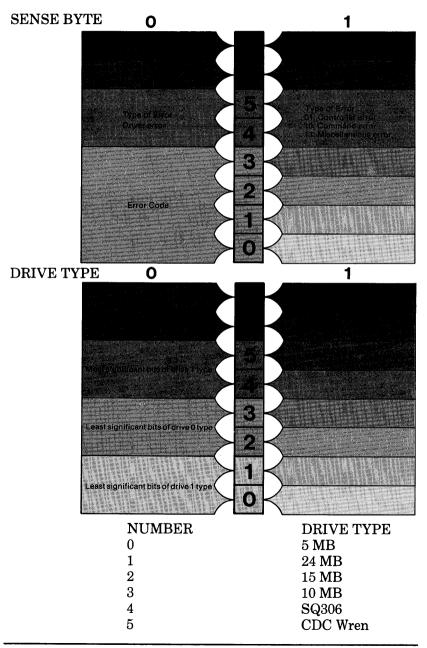
CONTROL REGISTER





CONTROL COMMAND





Error Codes

TYPE	CODE	DESCRIPTION
0	0	No error status
0	1	No index signal
0	2	No seek complete within 1.0 seconds
0	3	Write fault
0	4	Drive not ready
0	6	No track 0
0	8	Seek in progress
1	0	ID read error. ECC error in the ID field.
1	1	Uncorrectable data error during a read
1	2	Address Mark not found
1	4	Record not found. Found correct cylinder and
		head.
1	5	Seek error. Read/Write head positioned on
		wrong cylinder and/or wrong head selected.
1	8	Correctable data field error
1	9	Bad sector found
1	Α	Format error. An unexpected format
		discovered during the Check Track function.
1	С	Unable to read the alternate track address
1	${f E}$	Attempted to directly access and alternate
		track
2	0	Invalid function
2	1	Illegal disk address. Address is beyond
_		maximum.
3	0	RAM error. Data error detected during RAM
		diagnostic
3	1	Program Memory Checksum error
3	2	ECC Polynominal error

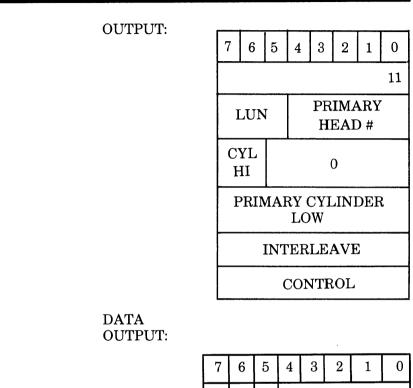
Function Parameters

NAME	DESCRIPTION
CONTROL COMMAND	Tells controller how to react to an error condition and defines step mode. See
CYLINDER LOW	layout. Eight least significant bits of the cylinder number
CYLINDER HIGH	Two most significant bits of the
ECC0,ECC1,ECC2	cylinder number ECC bytes of sector. ECC0 is least sig-
HEAD #	nificant byte. Head number
LUN #	Logical Unit Number. Winchester Drive $1 = Lun 0$, Winchester Drive $2 = Lun 1$.
SECTOR #	Sector number $2 - Lun 1$.
SENSE BYTE	Gives detailed error information. See
TYPE	layout. 0 = good track, 1 = alternate track, 2 = bad track, 3 = alternate bad track

Functions • ASSIGN ALTERNATE TRACK

This function formats the primary track specified in the function block with the alternated and bad track flags set in the ID fields and with the track address of the alternate track written in the data fields. The data field is written with the data in the sector buffer.

Future read/write accesses to the primary track cause the drive to seek to the alternate track and to perform the operation there. This is transparent to the software. Alternate tracks can be assigned once. An alternate track cannot point to another alternate track.

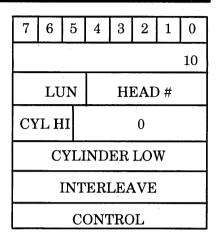


7	6	5	4	3	2	1	0	
0	0	0	SECONDARY HEAD #					
CY	CYL HI 0							
SECONDARY CYLINDER LOW								
0								

• CHECK TRACK

This function checks the track format on the specified track for the correctness of the ID fields and the interleave of the sectors. It does not read the data.

OUTPUT:



• CONTROLLER INTERNAL DIAGNOSTICS This function performs the controller internal diagnostics. The controller checks the internal processor, data buffer, ECC circuit and the checksum.

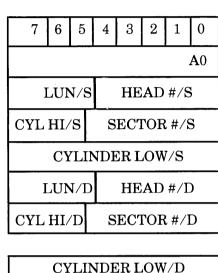
OUTPUT:

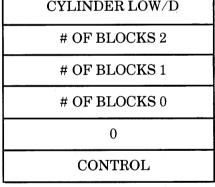
7	6	5	4	3	2	1	0
		•					E4
			()			
			()	,		
	0						
			()			· ·
			()			

• COPY

This function transfers the data blocks from the source unit to the destination unit. The number of sectors to copy is specified in the number of blocks field. If the field is zero, 15,777,216 sectors are copied.

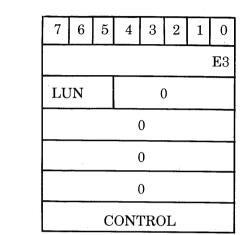
OUTPUT:





S = Source D = Destination

• DRIVE DIAGNOSTIC This function performs a diagnostic on the specified unit. It reads sector 0 on sequential tracks and then reads sector 0 on 256 random tracks.

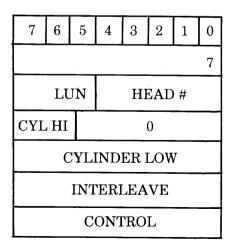


OUTPUT:

• FORMAT BAD TRACK

This function formats the track with the bad block flag set in all ID fields. It fills the data field with the data pattern in the sector buffer. The interleave must be the same for the entire drive.

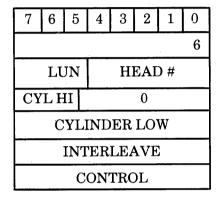
OUTPUT:



• FORMAT TRACK

This function formats the specified track with no flags set in the ID fields. It fills the data field with the data pattern in the sector buffer. The interleave must be the same for the entire drive.

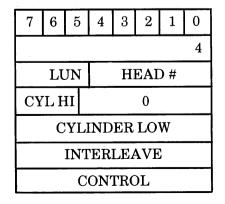
OUTPUT:



• FORMAT DRIVE

This function formats all of the tracks starting with the one specified in the function block to the end of the drive. The selected track format is used. The sectors are placed on the tracks according to the interleave code. The data fields are filled with the data pattern from the sector buffer.

OUTPUT:



• INITIALIZE DRIVE CHARACTERISTICS This function sets up the drive with different capacities and characteristics.

OUTPUT:	7 6 5 4 3 2 1 0						
	C						
	LUN 0						
	0 0						
	0						
	0						
DATA OUTPUT:	MAX # OF CYLINDERS HIGH						
	MAX # OF CYLINDERS LOW						
	MAX # OF HEADS						
	REDUCED WR. CUR. CYLINDER HIGH						
	REDUCED WR. CUR. CYLINDER LOW						
	WRITE PRECOMP. CYLINDER HIGH						
	WRITE PRECOMP. CYLINDER LOW						
	MAX ECC DATA BURST LENGTH						

• RAM DIAGNOSTIC This function performs a data pattern test on the controller RAM.

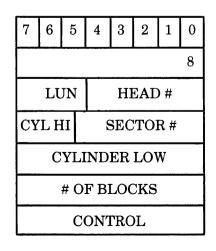
OUTPUT:

7	6	5	4	3	2	1	0	
							E0	
	0							
	0							
			C)				
			C)				
			C)				

• READ

This function reads the specified number of blocks. The function specifies the initial sector address. The data is transferred to the CPU.

OUTPUT:



• READ ECC BURST ERROR LENGTH This function transfers one byte of data to the CPU. This byte contains the ECC burst length that the controller detected for the correctable ECC data error during the last read function.

OUTPUT:

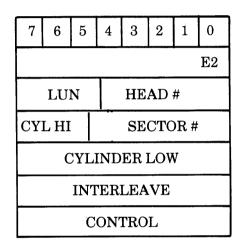
7	6	5	4	3	2	1	0	
D								
0								
0								
0								
0								
			Ċ)				

DATA INPUT:

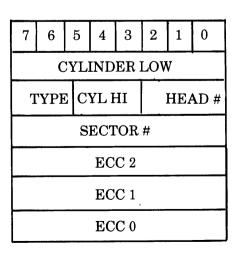
ECC BURST LENGTH

• READ ID This function reads three bytes and three ECC bytes from the specified sector address given in the function block and transfers them to the CPU.

OUTPUT:



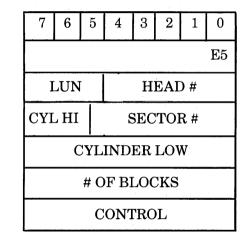
DATA INPUT:



• READ LONG

This function reads sectors of data and ECC bytes from the disk and transfers them to the CPU. If an ECC error occurs during the read, the controller does not attempt to correct the data.

OUTPUT:



DATA INPUT:

256/512/1024 BYTES OF DATA	E C 2	E C 1	E C 0	0 0	
-------------------------------	-------------	-------------	-------------	--------	--

• READ SECTOR BUFFER This function reads one sector from the controller sector buffer. No data transfer occurs between the controller and the drives.

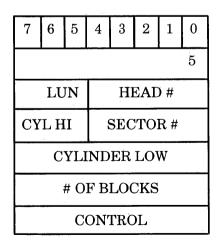
0.1	ten to	TTO
())	μhb	11/124
		U 1.

7	6	5	4	3	2	1	0		
							Ε		
	0								
	0								
			. ()					
	0								
	0								

• READ VERIFY

This function reads the specified number of blocks but does not transfer the data to the CPU. The function specifies the sector number where verification begins.

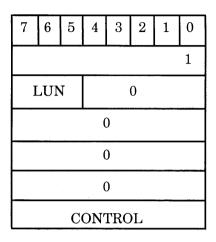
OUTPUT:



• RECALIBRATE

This function positions the read/write arm at track 0 and clears errors in the drive.

OUTPUT:



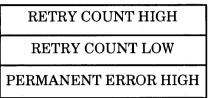
• REQUEST LOGOUT

This function retrieves the four bytes of error log for the specified unit. Each device has its own error log which is incremented every time certain errors occur and is cleared after this function is executed.

OUTPUT:

7	6	5	4	3	2	1	0
					-		E7
LUN					0		
							0
							0
							0
							0





PERMANENT ERROR LOW

• REQUEST SENSE This function sends the four Sense Bytes to the CPU as data.

OUTPUT:

7	6	5	4	3	2	1	0	
LU)							
							0	
							0	
							0	
							0	

DATA INPUT:

7 6	5	4	3	2	1	0			
SENSE BYTE									
LU	JN		H	EAD) #				
CYL HI SECTOR #									
C	CYLINDER LOW								

• REQUEST SYNDROME This function returns the four bytes of the ECC syndrome to the CPU as data.

OUTPUT:

7	6	5	4	3	2	1	0
							2
L	UN			0			
							0
							0
							0
							0

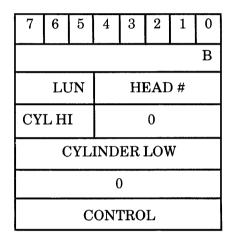
DATA INPUT:

7	6	5	4	3	2	1	0		
	MSB bit offset								
	LSB bit offset								
	0								
	0 MASK								

SEEK

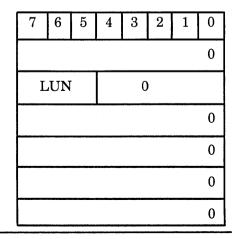
This function seeks to the cylinder of the specified block. For Winchester drives capable of overlap seeks, this function returns completion status before the seek is complete.

OUTPUT:



• TEST DRIVE READY This function selects the specified drive and verifies the drive is ready, the seek is complete, and there are no drive faults.

OUTPUT:



• WRITE

This function writes the data starting at the initial block address given in the function.

OUTPUT:

7	6	5	4	3	2	1	0			
Α										
	LU	JN	H	EAI)#					
CY	LH	[Ś	SEC	TOI	R #				
	C	YL	IND	ER	LOV	V				
# OF BLOCKS										
	CONTROL									

• WRITE LONG This function writes blocks of data and ECC bytes from the CPU to the disk without generating ECC for the data.

7	6	5	4	3	2	1	0			
E6										
	LUN HEAD #									
CY	LHI	Ι	S	SEC	TOI	R #				
	CYLINDER LOW									
# OF BLOCKS										
	CONTROL									

DATA OUTPUT:

OUTPUT:

256/512/1024 BYTES OF DATA	E C 2		E C 0	0 0
-------------------------------	-------------	--	-------------	--------

• WRITE SECTOR BUFFER

This function writes one sector's worth of data to the controller sector buffer. No data transfer occurs between the controller and the drives.

OUTPUT:

7	6	5	4	3	2	1	0
							F
							0
							0
							0
							0

Sequencing and Timing

There are three phases to each function:

- function initiation
- function execution
- function results

To initiate a function, you select the controller with the Select Controller Register. Then you wait for Ready in the Status Register to be set. The In/Out bit and the Command/Data bit should indicate function transfer to the controller. You then write six function bytes to the Data Register.

If the Ready is set after this transfer, either there was an error in the function bytes or the controller is ready to receive another group of six function bytes and/or data. Data can be transferred in DMA or non-DMA mode. If the transfer is in DMA mode, the DMA Controller is programmed in Single Transfer mode (See DMA Controller). The count word is set to:

(number of sectors to transfer)(bytes/sector) - 1

If data is transferred in non-DMA, you use Ready, In/Out, Command/Data and Interrupt Request to time the transfer during execution.

Execution begins when the last function byte is received. In data transfer functions, the controller temporarily stores the data in the sector buffer. This prevents data overruns. When the function completes and the Completion Status byte is loaded, the controller issues interrupts if requested.

You clear the Interrupt Enable and the DMA enable bits in the Control Register after reading the Completion Status. This allows the controller to clear Interrupt Request and Data Request in the Status Register. It also clears the Selected bit.

The controller does extensive error recovery. If an error is found, four retries are attempted. If a retry is successful, the error is not reported; however, the retry count is incremented.

The following errors result in a retry:

- Seek error
- Sector not found
- Uncorrectable data error

Hard Disk Controller

- Correctable data error
- No data address mark
- No ID address mark
- ECC error in ID field

On a seek error, a recalibrate and reseek is done by the controller.

The following errors are accumulated in the log:

- ECC error in ID field
- Correctable error in data field
- Uncorrectable error in data field
- No ID address mark
- No data address mark
- Seek error
- Record not found

If rereads are disabled, the controller does not reread before applying the ECC correction.

When a reset is done, the controller defaults to the following characteristics:

- Maximum number of cylinders = 306
- Maximum number of heads = 4
- Starting reduced write current cylinder = 306
- Starting write precompensation cylinder = 0
- Maximum ECC data burst length = 4 bits

The interleave factor states how many physical sectors logical sectors are apart. For example, if the Interleave Factor is 6 and there are 16 sectors in a track, then a sector looks like this:

 Physical

 Sector
 0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16

 Logical

 Sector
 0 3 6 9 12 15 1 4 7 10 13 16 2 5 8 11 14

The track layout for 256 bytes per sector, 33 sectors per track is:

ſ	13											F		е			10
	bytes	m	E	у	d	e	Ċ	0	0	bytes	m	8	bytes	с	0	0	bytes
	00's			1		с	с			00's			data	с			4E's

am, FE, cyl, hd, sec, 00, F8 = 1 byte ecc = 3 bytes

Track capacity = 10416

16 = Index Gap (4E) 10197 = 33 sectors @ 309 bytes/sector 203 = Speed Tolerance Gap (4E) 10416

309 bytes/sector including ID and overhead

The track layout for 512 bytes per sector, 17 sectors per track is:

13	a	F	с	h	s	e	0	0	13	a	F	512	е	0	0	37
bytes	m	E	у	d	е	с	0	0	bytes	m	8	bytes	c	0	0	bytes
00's			1		с	ç			00's			data	с			4E's

am, FE, cyl, hd, sec, 00, F8 = 1 byte ecc = 3 bytes Track capacity = 10416

16 =Index Gap (4E) 10064 = 17 sectors @ 592 bytes/sector 336 = Speed Tolerance Gap (4E) 10416

592 bytes/sector including ID and overhead

The track layout for 1024 bytes per sector, 9 sectors per track is:

							с			bytes	a m		bytes	e c c			58 bytes 4E's
--	--	--	--	--	--	--	---	--	--	-------	--------	--	-------	-------------	--	--	---------------------

am, FE, cyl, hd, sec, 00, F8 = 1 byte ecc = 3 bytes

Track capacity = 10416

16 = Index Gap (4E)10125 = 9 sectors @ 1125 bytes/sector $\underline{275} = \text{Speed Tolerance Gap (4E)}$ 10416

1125 bytes/sector including ID and overhead

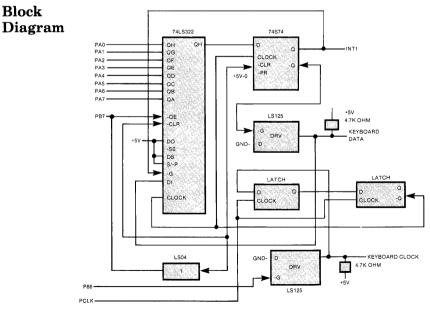
Sample	; INIT_CTLR	
Program	; This routine prepar	es the controller to
•	; receive a function.	
	; OUTPUT: Carry	v set if error
	SELECT EQU 3	
	STATUS EQU 3	21
	CONTROL EQU 32	23
	INIT-CTLR:	
	MOV DX,SELECT	Select Port Address;
	OUT DX,AL	;Output anything
	MOV DX,CONTROL	;Control Port Address
	MOV AL,3H	;Enable interrupts and
		;DMA
	OUT DX,AL	
	MOV DX,STATUS	;Status Port Address
	INIT1:	
	IN AL,DX	;Get status
	TEST AL,1H	;Is it ready?
	LOOPZ INIT1	;Loop if not ready
	CMP AL,DH	;Jump if ready for a
	JE INIT2	;function and selected
	STC	;Flag error
	RET	
	INIT2:	
	CLC	
	RET	

Keyboard Interface

The keyboard interface converts the parallel Functional data into serial data for transmission to and Description from the keyboard.

To provide maximum flexibility in defining keyboard operations, the keyboard uses scan codes rather than ASCII codes. In addition, all keys generate a make scan code when pressed and a break scan code when released. The break scan code is 80H plus the make scan code.

The keyboard is responsible for keeping track of the amount of time a key is depressed and for generating the repeat key signal. All the keys have this repeat function.

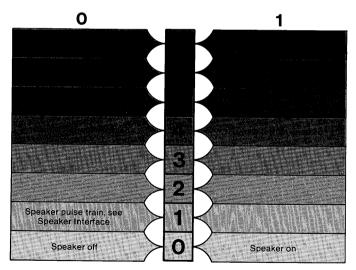


Registers

PORT	NAME	READ/ WRITE	DESCRIPTION
60	DATA	R	8 bit scan code when pressed, 8 bit scan code plus 80H when released See scan code chart.
60	DATA	W	Keyboard command codes
60	CONTROL	R/W	See layout
64	STATUS	R	See layout

Layout

CONTROL



STATUS

Functions • READ STATUS

This function allows you to determine when there is a character to read and when the keyboard is ready to receive a character. INPUT: STATUS

- READ DATA This function allows you to read the scan code of the key that was pressed or released. INPUT: DATA
- WRITE CONTROL This function allows you to issue control commands to the keyboard. OUTPUT: CONTROL

 GET KEYBOARD TYPE This function determines if the keyboard is an Olivetti M20 type keyboard. OUTPUT: DATA REGISTER 5 INPUT: DATA REGISTER 1 = Olivetti M20 keyboard

• KEYBOARD LEDS This function controls the illuminations of the CAPS LOCK and NUM LOCK LEDS. OUTPUT: DATA REGISTER

13H

Value	Operation
00h	No operation
01h	Cap lock LED OFF
02h	Num lock LED OFF
03h	Both LEDS OFF
80h	No operation
81h	Caps lock LED ON
82h	Num lock LED ON
83h	Both LEDS ON

Any other value will cause one of the above operations.

Scan Codes

KEY NO	SCAN CODE	KEY NO	SCAN CODE	KEY NO	SCAN CODE
1	01H	36	24H	71	47H
2	02H	37	25H	72	48H
3	03 H	38	26H	73	49H
4	04H	39	27H	74	4AH
5	05H	40	28H	75	4BH
6	06H	41	29H	76	4CH
7	07H	42	2AH	77	4DH
8	08H	43	2BH	78	4EH
9	09H	44	2CH	79	4FH
10	0AH	45	$2\mathrm{DH}$	80	50H
11	0BH	46	$2\mathrm{EH}$	81	$51 \mathrm{H}$
12	0CH	47	2FH	82	52H
13	$0 \mathrm{DH}$	48	30H	83	53H
14	0EH	49	31H	84	54H
15	0FH	50	32H	85	55H
16	10H	51	33H	86	56H
17	11H	52	34H	87	57H
18	12H	53	35H	88	58H
19	13H	54	36H	89	59H
20	14H	55	37H	90	5AH
21	15H	56	38H	91	5BH
22	16H	57	39H	92	5CH
23	17H	58	3AH	93	$5\mathrm{DH}$
24	18H	59	3BH	94	$5 \mathbf{EH}$
25	19H	60	3CH	95	5FH
26	1AH	61	3DH	96	60H
27	1BH	62	3EH	97	61H
28	1CH	63	3FH	98	62H
29	$1\mathrm{DH}$	64	40H	99	63H
30	$1\mathbf{EH}$	65	41H	100	64H
31	$1 \mathrm{FH}$	66	42H	101	65H
32	20H	67	43H	102	66H
33	21H	68	44H	103	67H
34	22H	69	45H	104	68H
35	23H	70	46H	-	-

Sequencing	T
and Timing	1
	b

o send a character to the keyboard, wait for Bit of the Status Register to be set and write the yte to the data register.

To receive a character, wait for Bit 0 of the Status Register to be set and read the character. The keyboard interface can be programmed to interrupt on INT1 when there is a character to read.

Sample

;This program sets the CAPS LOCK LED

Program

STATUS **EQU 64** DATA **EQU 60**

SET_LED: IN AL, STATUS TEST AL,2 JNZ SET_LED MOV AL,013H OUT DATA,AL

:read status :keyboard ready to receive ;input? Jump if ready. ;keyboard LED command

SET1:

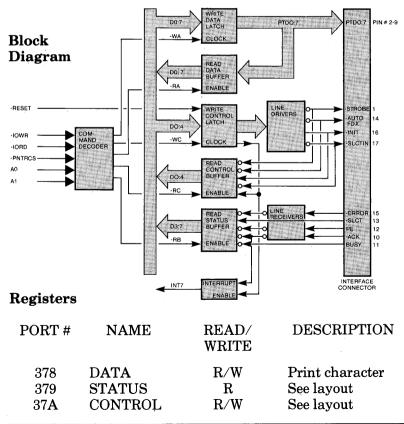
IN AL, STATUS
TEST AL,2
JNZ SET1
MOV AL,81
OUT DATA,AL
RET

:read status ;ready to receive input? ;jump if not :CAPS LOCK write out code

Parallel Printer Interface

Functional Description The parallel printer interface connects to printers with a Centronics-like parallel interface or any other device with identical interface characteristics. The input and output signals are presented to the external device through a 25-pin "D" type connector.

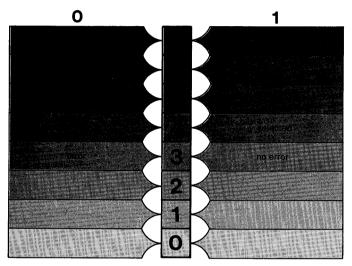
The interface has 5 buffered outputs — data, strobe, initialize printer, automatic linefeed, and select. These can be read and written. In addition, the interface has five inputs — acknowledge, busy, paper out, error and select. An interrupt can be enabled on INT7.



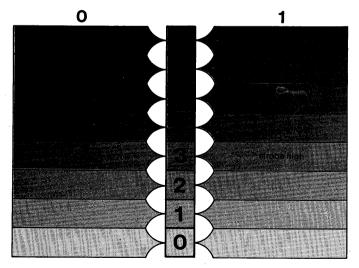
Parallel Printer Interface

Layout

STATUS



CONTROL



Functions • RESET

After a power on or a hardware reset, the data buffer is cleared and the control register is initialized to:

- bit 0: 0
- bit 1:0
- bit 2:0
- bit 3: 0
- bit 4: 0
- WRITE DATA

This instruction enables the data on the data bus to be written to the printer data bus. The actual writing occurs when the strobe line is activated.

OUTPUT: DATA

• WRITE CONTROL

This instruction inverts D0, D1, and D3 on the data bus and writes the data to the control register. If D4 is a 1 then interrupts are requested. OUTPUT: CONTROL

• READ DATA

This instruction enables the data on the printer data bus to be read onto the data bus. It normally is the last character written to the printer. INPUT: DATA

• READ CONTROL

This instruction enables the data on the printer control lines and the interrupt control bit to be placed on the data bus. INPUT: CONTROL

• READ STATUS This instruction enables the data on the printer status lines to be placed on the data bus. INPUT: STATUS

Sequencing and Timing

To send a character to the printer, the character is put on the data bus. When the printer is not busy, it is ready to accept the next character. The character must be strobed into the printer by setting the strobe bit to 1 for at least 5 μ -seconds and then resetting it.

Interrupt can be enabled on INT7 by writing D4 = 1 in the control register. An interrupt will be triggered everytime Bit 6 of the status register goes from 0 to 1 (end of the acknowledge cycle from the printer).

To initialize the printer, first select it. Then issue the initialize command setting the automatic line feed and interrupt parameters.

Parallel Printer Interface

Sample Program	; PRINT_CHAR ; Send character to printe ; INPUT AL - character to ; OUTPUT: AL - status	+
	, DATA EQU 378I	4
	PRINT_CHAR:	1
	MOV DX,DATA	;get data port
	OUT DX,AL	;put char on data ;line
	INC DX	;get status port
	IN AL,DX	;read in status
	TEST AL,080H	;is the printer busy?
	JNZ PRINT_NOT_BUSY	jump if not busy;
	•	
	PRINT_NOT_BUSY:	
	MOV AL,0DH	;strobe high
	INC DX	;get control port
	OUT DX,AL	to control register
	NOP	;wait
	NOP	;wait
	MOV AL,0CH	;strobe low
	OUT DX,AL	;to control register
	DEC DX	;get status port
	IN AL,DX	;read in status
	RET	

Programmable Interrupt Controller

Functional Description

The Intel 8259A Programmable Interrupt Controller (PIC) manages external interrupts. It receives requests from peripheral equipment, decides which request has the highest priority, and issues an interrupt to the CPU. Each PIC handles 8 maskable priority interrupts. PIC's can be cascaded allowing up to 64 priority interrupts. However, on the AT&T Personal Computer 6300 this is not done.

Each interrupt device runs to one of eight interrupt lines (INTO-INT7). If more than one device interrupts at once, the PIC decides which device to service according to one of several schemes.

The following schemes apply to a single PIC:

• Fully Nested Mode

This is the default mode. The interrupt requests have an ordered priority from 0 (highest) to 7 (lowest). The highest priority is acknowledged first and those of lower priority are inhibited.

• Special Mask Mode

This mode is similar to fully nested mode except that the interrupt mask register (IMR) determines which interrupts are disabled.

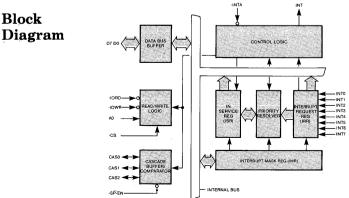
• Polled

This mode allows the CPU to poll the devices. It is selected by disabling interrupts with the CLI instruction. Periodically the CPU polls the PIC to receive the interrupt type of the highest priority device requesting service. Automatic Rotation In this mode, a device receives the lowest priority after it is serviced. All other devices have their priorities adjusted accordingly. The next highest interrupt line receives the highest priority.

Programmable Rotation In this mode, the programmer declares the lowest priority device.

The PIC keeps track of devices that are waiting for service in the interrupt request register (IRR). If not in polled mode, the PIC notifies the CPU of the pending interrupt. When it receives an interrupt acknowlege from the CPU (INTA), it sends the interrupt type of the device to the CPU. The device is then in-service. This is noted in the in-service register (ISR). The type of INTO is programmable. It must be a multiple of 8.

After the interrupt service routine services the interrupt, it notifies the PIC of end of interrupt (EOI). The device is then removed from the inservice register.



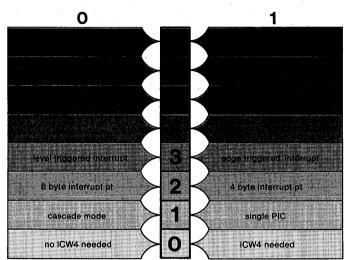
Registers

PORT #	NAME	READ/ WRITE	DESCRIPTION
20	INIT COMMAND WORD 1 (ICW1)	W	See layout
21	INIT COMMAND WORD 2 (ICW2)	W	INT0 interrupt type, multiple of 8
21	INIT COMMAND WORD 3 (ICW3)	W	Cascade mode only
21	INIT COMMAND WORD 4 (ICW4)	W	See layout
21	OPERATION COMMAND WORD 1	R/W	Interrupt Mask
			Register
	(OCW1, IMR)		See layout
20	OPERATION COMMAND WORD 2 (OCW2)	W	See layout
20	OPERATION COMMAND WORD 3 (OCW3)	W	See layout
20	IN-SERVICE REGISTER (ISR)	R	See layout
21	INTERRUPT LEVEL	R	See layout
20	INTERRUPT REQUEST REGISTER (IRR)	R	See layout

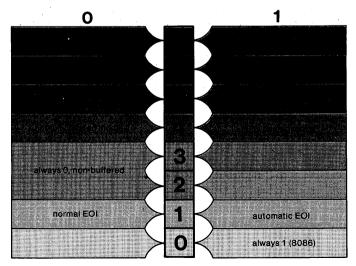
.

Layout

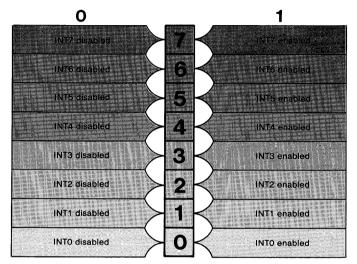
ICW1



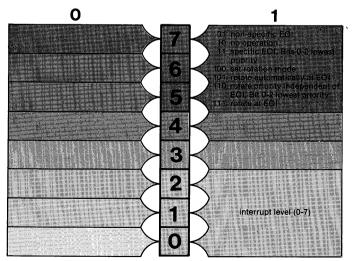
ICW4



OCW1 or INTERRUPT MASK REGISTER

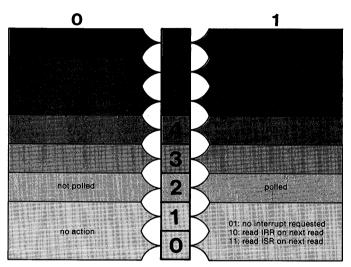


OCW2

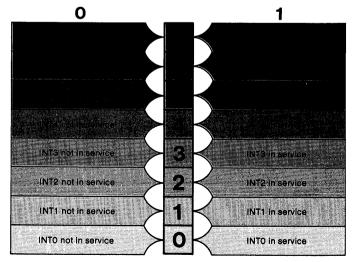


Programmable Interrupt Controller

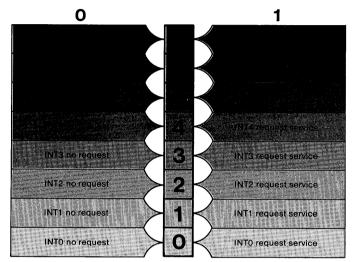
OCW3



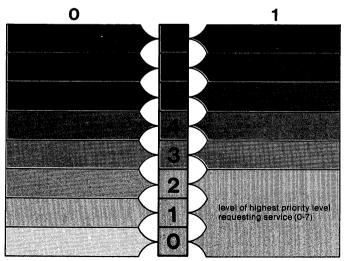
IN SERVICE REGISTER



INTERRUPT REQUEST REGISTER



INTERRUPT LEVEL



Functions • **INITIALIZATION** This function prepares the PIC to accept interrupts by setting it to an initial state. OUTPUT: ICW1 ICW2 ICW3 (Cascaded PIC's only) ICW4 SET SPECIAL MASK MODE This function sets the priority scheme to Special Mask Mode. The Interrupt Mask Register (IMR) defines enabled priorities. OUTPUT: OCW3 BITS 5-6 = 3IMR RESET SPECIAL MASK MODE This function resets the priority structure to the Fully Nested Mode. The IMR is ignored. OUTPUT: OCW3 BITS 5-6 = 1SET POLLED MODE This function sets the priority scheme to Polled Mode. The CLI instruction must be executed to disable external interrupts. The next read fetches the interrupt level. OUTPUT: OCW3 BIT 2 = 1INPUT: interrupt level AUTOMATIC ROTATION OF PRIORITIES AT EOI This function requests an automatic rotation of priorities at EOI. OUTPUT: ICW2 BITS 5-7 = 5PROGRAMMED ROTATION AT EOI This function requests a specific change in priorities at EOI. OUTPUT: ICW2 BITS 5-7 = 7ICW2 BITS 0-2 = level of lowest priority

 ROTATION OF PRIORITIES INDEPENDENT OF EOI

This function requests an immediate change in priorities.

OUTPUT: OCW2 BITS 5-7 = 6 OCW2 BITS 0-2 = level of lowest priority

• SPECIFIC END OF INTERRUPT (SEOI) This function is issued in an interrupt service routine to declare end of interrupt service for the specified level.

OUTPUT: OCW2 BITS 5-7 = 3 BITS 0-2 = interrupt level

• NON-SPECIFIC END OF INTERRUPT (EOI) When the PIC is operating in Fully Nested Mode, it can determine which interrupt is completing. This function signals completion of an interrupt service routine.

OUTPUT: OCW2 BITS 5-7 = 1

• AUTOMATIC END OF INTERRUPT This function requests the PIC to declare end of interrupt automatically after delivering the interrupt to the CPU. OUTPUT: ICW4 BIT 1 = 1

 READ IRR This function reads the devices requesting service. OUTPUT: OCW3 BITS 0-1 = 2 INPUT: IRR

READ ISR
 This function reads the in-service register.
 OUTPUT: OCW3 BITS 0-1 = 3
 INPUT: ISR

• READ IMR This function reads the interrupt mask register. INPUT: OCW1

Sequencing and Timing When the ICW1 command is issued, the initialization process begins. The following automatically occurs:

- IMR is cleared.
- INT7 is assigned the lowest priority.
- Single mode is assumed.
- Special Mask Mode is cleared.
- A status read fetches IRR.
- If Bit 0 equals zero, then ICW4 functions are set to zero.

Next ICW2 is output. ICW3 is skipped in all single PIC systems. If the ICW4 was requested by ICW1 then it is output. This completes initialization.

Once the initialization process is complete, the PIC is ready to accept interrupts. Any of the functions to change the priority scheme can be executed. In addition, the IRR, IMR, and ISR can be read.

If automatic EOI is not specified then the interrupt service routine must declare EOI. Either specific or non-specific EOI can be used depending on the priority scheme in use. When a write command is issued to the PIC, 480 nanoseconds must elapse before another command is issued. In the read case, 395 nanoseconds must elapse.

Sample

Program ; SEND_SEOI

;

Send end of INT1 service at the end of the

interrupt service routine.

, OCW2 COMMAND	•	;port address of OCW2 ;6 = SEOI, 1 = INT1
COMMIND	LQC 01	,0 0101,1 1111

SEND_SEOI:

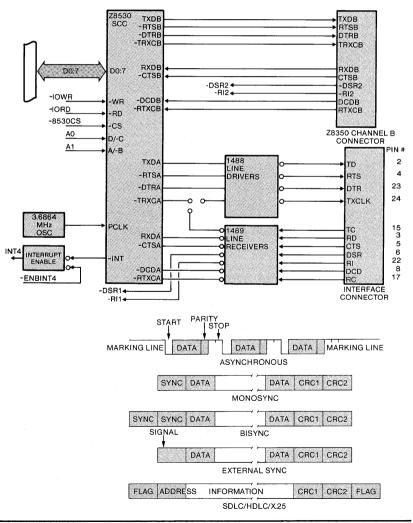
MOV AL,COMMAND;set AL = commandMOV DX,OCW2;set DX = port addressOUT DX,AL;send commandSTI;enable external interruptsRET;return to service routine

Programmable Interval Timer

	· · · · · · · · · · · · · · · · · · ·
Functional Description	The Intel 8253 Interval Timer has three identi- cal, 16-bit, settable, decrementing counters. Each counter is totally independent. The counters have either a BCD or binary value and operate in one of five modes:
•	Interrupt on Terminal Count The output remains low after the mode is set. It continues low after the counter is loaded until the counter counts down to zero. Then the output goes high. It remains high until a new mode is selected or a new count is loaded.
•	Programmable One-Shot The output goes low one count following the ris- ing edge of the gate input. The output goes high on the terminal count.
•	Rate Generator The output is low for one period of the input clock. The period from one output pulse to the next equals the number of input counts in the count register.
•	Square Wave Rate Generator The output remains low for one period of the input clock. The output remains high until one half the count has elapsed. If the count is odd, the output is high for $(n+1)/2$ and low for (n-1)/2.
•	Software Triggered Strobe After the mode is set, the output will be high.

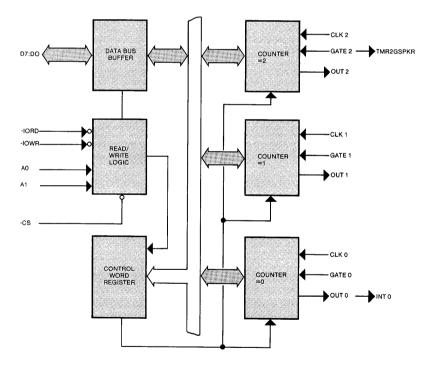
After the mode is set, the output will be high. When the count is loaded, the counter begins counting. On the terminal count,the output goes low for one clock period and then goes high. • Hardware Triggered Strobe The counter starts counting after the rising edge of the trigger input and goes low for one clock period when terminal count is reached.

These timing diagrams illustrate the different modes.



In the AT&T Personal Computer 6300 system, Counter 0 provides real time interrupts on INT0, counter 1 requests memory refreshes, and counter 2 generates a pulse train for the audio speaker.

Block Diagram

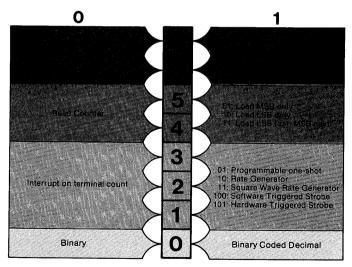


Registers

PORT #	NAME	READ/ WRITE	DESCRIPTION
40 41	COUNTER 0 COUNTER 1	R/W R/W	Provides real time interrupt INT0 Provides signals to refresh memory
42	COUNTER 2	R/W	Generate pulse train for the audio speaker
43	CONTROL	W	See Layout

Layout

CONTROL



Functions • LOAD COUNTER This function allows you to set a specific counter. OUTPUT: CONTROL REGISTER BITS 0 binary or BCD DUTO 1.0 mode

BITS 1-3 mode BITS 4-5 1,2 or 3 BITS 6-7 counter 8 or 16 bit count value

• READ COUNTER

This function allows you to read a specific counter. OUTPUT: CONTROL REGISTER

TPUT:	CONTROL REGISTER
	BITS 4-50
	BITS 6-7 counter

Sequencing and Timing

All counters must be initialized with the control register. The control register specifies the number of bytes which must be loaded.

Whenever a read or a load command is issued, the requested counter bytes must be read or written. In the read case, two reads are necessary, the first for the least significant byte (LSB) and the last for the most significant byte (MSB). In the write case, the control register specifies the byte to write.

1 microsecond recovery time is required between a read or a load and any other control signal.

Input to the timer is 1.2288MHz. Therefore, there are 18.75 interrupts per second. To generate a 1.00 KHz tone with the audio speaker, a square wave rate generator is used with a count of 614 (1.2288MHz/2*614 = 1KHz).

1,2283 X10 = 18.8

FF

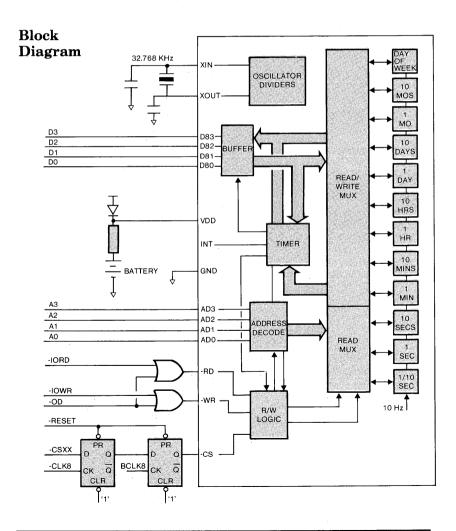
Programmable Interval Timer

Sample Program	; ; ASK_FOR_INTR ; This program re ; approximately 1 ;	0 usec (9	9765.6 nsec)
	TIMER_CONTROL	EQU 4	
	TIMER0	EQU 4)
	INT_MASK	EQU 2	1
	ASK FOR INTR		
	MOV AL,0FEH		;allow only INT0 ;interrupt
	OUT INT_MASK,	AL	;send mask
	MOV AL,00110000	В	;binary counter, ;interrupt on terminal ;count, set counter 0
	OUT TIME_CONT	ROL,AI	
	MOV AX,12		;12 * 813.8 nsec
	OUT TIMER0,AL		
	MOV AL,AH		;output counter, LSB ;then MSB
	OUT TIMER0,AL		
	RET		

Real Time Clock and Calendar

Functional Description

The real time clock and calendar keep the current data and time. All of the date and time fields can be read but the second fields cannot be written. The calendar keeps up to eight years. A rechargeable battery keeps the unit running even when the computer is turned off.



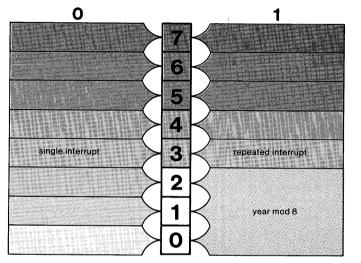
Registers

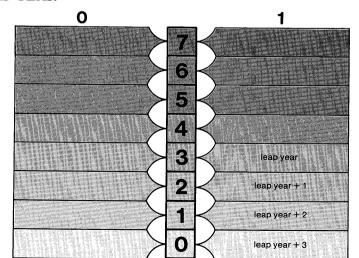
PORT #	NAME	READ/ WRITE	DESCRIPTION
70 71 72 73 74 75 76 77 78 79 7 A 7 B 7 C	TEST PORT 1/10 OF A SECOND UNIT SECONDS 10'S OF SECONDS UNIT MINUTES 10'S OF MINUTES UNIT HOURS 10'S OF HOURS UNIT DAYS 10'S OF DAYS DAY OF WEEK UNIT MONTHS 10'S OF MONTHS	WRITE W R R K/W R/W R/W R/W R/W R/W R/W R/W R/W R/W	0=not test mode, 1=test mode nybble, 0-9 nybble, 0-9 nybble, 0-5 nybble, 0-9 nybble, 0-5 nybble, 0-9 nybble, 0-1 nybble, 0-9 nybble, 0-3 nybble, 1-7 nybble, 0-9 nybble, 0-9
7D 7E 7F	LEAP YEAR STOP/START INTERRUPT/YEAR MOD 8	W W R/W	See layout 0 = stop, FF = start See layout

75

Layout

INTERRUPT/YEAR MOD 8





LEAP YEAR

10

Functions •	READ CALENDAR AND CLOCK All of the calendar and time registers are read- able. Those from port address 71 to 7D and 7F contain a nibble of data.
•	WRITE CALENDAR AND CLOCK All of the calendar and time registers except seconds are writable. The registers from port address 74 to 7D and 7F each contain a nibble of data.
Sequencing and Timing	To write data to the clock and time registers, the unit must be out of test mode and stopped. After writing to the clock, it must be restarted.
	To initialize interrupts, set Bit 4 in the Inter- rupt/Year mod 8 register. Write the register once and then read it in three times.
	If an undate occurs while reading a register the

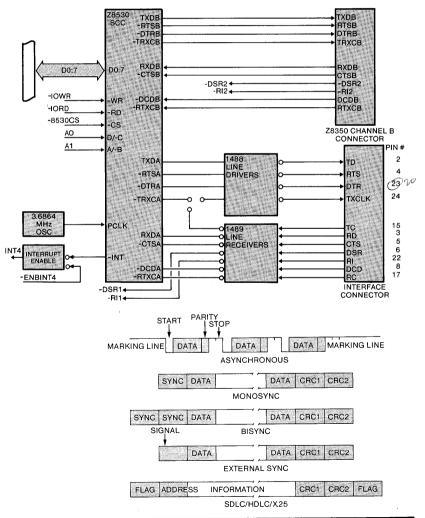
If an update occurs while reading a register, the illegal code of F is returned.

Sample Program	; SET TIME ; This routine sets the tim	ne to 12:00 noon
	; TEST_PORT EQU 7(n
	STOP_START EQU 7.	
	TENS_HOURS EQU 7'	
	WRITE_TIME:	•
	XOR AX,AX	;AX = 0
	MOV DX,TEST_PORT	;setup dx
	OUT DX,AL	;take out of ;test mode
	OUT STOP_START,AL	stop the clock
	MOV DX,TENS_HOURS	;port addr of ;10's of hours
	MOV AL,1)
	OUT DX,AL	;ten's of hours ;= 1
	DEC DX	
	MOV AL,2	
	OUT DX,AL	;unit hours = 2
	DEC DX	
	XOR AL,AL	
	OUT DX,AL	;tens of minutes ;= 0
	DEC DX OUT DX,AL	;minutes = 0
	MOV AL,0FFH OUT STOP_START,AL	;start the clock
	RET	

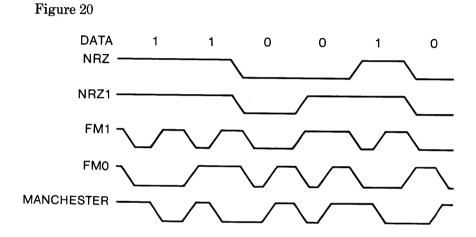
Serial Communications Controller

Functional Description

Z8530 Serial Communications Controller (SCC) performs serial-to-parallel conversion on input data characters received from a modem and parallel-to-serial conversion on output data characters received from the CPU. It supports the following common asynchronous and synchronous data communication protocols.



In addition, the SCC supports five encoding methods — NRZ, NRZI, FM1 (bi-phase mark), FM0 (bi-phase space), and Manchester (bi-phase level).



The SCC has the following capabilities:

Asynchronous

- 5, 6, 7, or 8 bits per character
- 1, 1 1/2, or 2 stop bits
- Odd or even parity
- Times 1, 16, 32, or 64 clock modes
- Break generation and detection
- Parity, overrun and framing error detection

Byte-oriented synchronous

- Internal or external character synchronization
- 1 or 2 sync characters in separate registers
- Automatic sync character insertion and deletion
- Cyclic redundancy check (CRC) generation/ detection
- 6- or 8-bit sync character

SDLC/HDLC

- Abort sequence generation and checking
- Automatic zero insertion and deletion
- Automatic flag insertion between messages
- Address field recognition
- I-field residue handling
- CRC generation/detection
- SDLC loop mode with EOP recognition/loop entry and exit

The baud rate is programmable for both channels.

Registers

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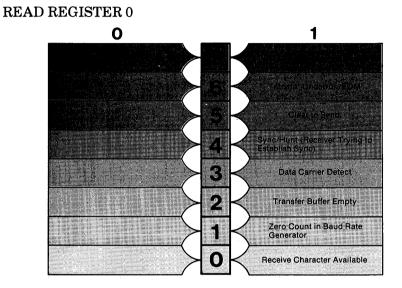
PORT # A	В	NAME	READ/ WRITE	DESCRIPTION
51 50	00	DATA SCC REGISTER POINTER		Transfer data Transfer SCC register number and SCC register data

Serial Communications Controller

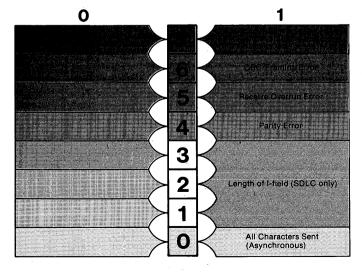
SCC Registers

READ/ WRITE	NO	NAME	DESCRIPTION
\mathbf{R}	0	Buffer and External Status	See layout
\mathbf{R}	1	Special Receive Condition Status	See layout
\mathbf{R}	2	Modified Interrupt Vector (Channel B)	
		Unmodified Interrupt Vector (Channel A)	
\mathbf{R}	-3	Interrupt Pending Bits (Channel A)	See layout
R	8	Receive Buffer	See layout
\mathbf{R}	10	Miscellaneous Status	See layout
R	12	Low Byte of Baud Rate Generator Constant	··· -
\mathbf{R}	13	High Byte of Baud Rate Generator Constant	
R	15	External/Status Interrupt Information	See layout
W	0	CRC Initialize	See layout
W	1	Transmit/Receive Interrupt and Data Transfer	
		Mode Definition	See layout
W	2	Interrupt Vector	
W	3	Receive Parameters and Control	See layout
W	4	Transmit/Receive Miscellaneous Parameters	
		and Modes	See layout
W	5	Transmit Parameters and Control	See layout
W	6	Sync Characters or SDLC Address Field	See layout
W	7	Sync Characters or SDLC Flag	See layout
W	8	Transmit Buffer	See layout
W	9	Master Interrupt Control and Reset	See layout
W	10	Miscellaneous Transmit/Receive	
		Control Bits	See layout
W	11	Clock Mode Control	See layout
W	12	Low Byte of Baud Rate Generator Constant	
W	13	High Byte of Baud Rate Generator Constant	
W	14	Miscellaneous Control Bits	See layout
W	15	External/Status Interrupt Control	See layout

Layout



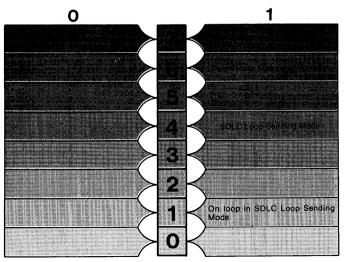
READ REGISTER 1

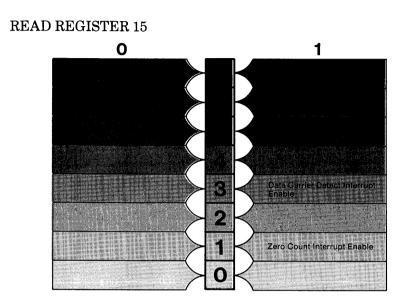


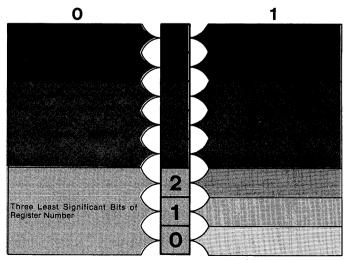
Serial Communications Controller

READ REGISTER 3

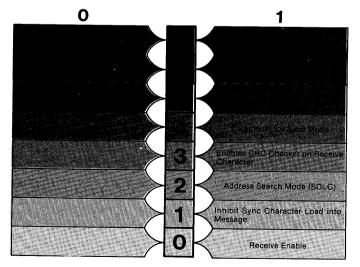
READ REGISTER 10

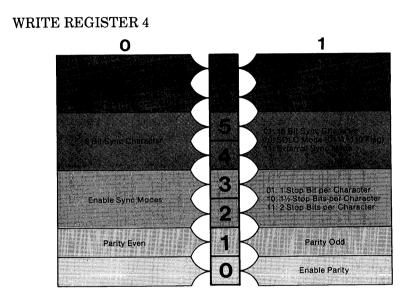


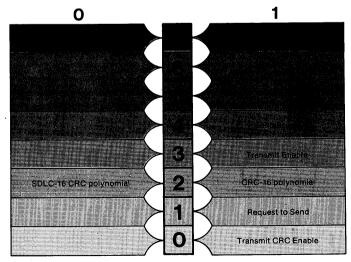




Serial Communications Controller

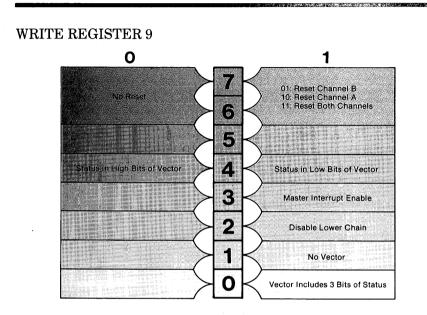


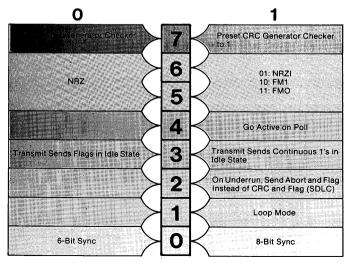


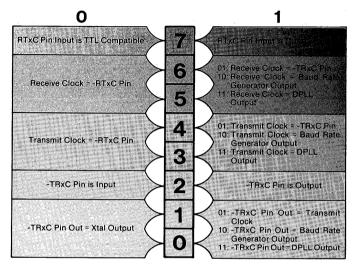


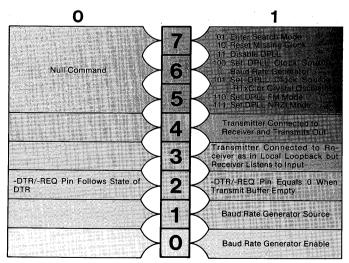
	MONO,8 BITS	MONO,16 BITS	BISYNC,16 BITS	BISYNC,12 BITS	SDLC SDLC
0	SYNC0	SYNC0	SYNC0	1	ADR0 X
1	SYNC1	SYNC1	SYNC1	1	ADR1 X
2	SYNC2	SYNC2	SYNC2	1	ADR2 X
3	SYNC3	SYNC3	SYNC3	1	ADR3 X
4	SYNC4	SYNC4	SYNC4	SYNC0	ADR4 ADR4
5	SYNC5	SYNC5	SYNC5	SYNC1	ADR5 ADR5
6	SYNC6	SYNC0	SYNC6	SYNC2	ADR6 ADR6
7	SYNC7	SYNC1	SYNC7	SYNC3	ADR7 ADR7

	MONO,8 BITS	MONO,16 BITS	BISYNC,16 BITS	BISYNC,12 BITS	SDLC
0	SYNC0	Х	SYNC8	SYNC4	.0
1	SYNC1	Х	SYNC9	SYNC5	1
2	SYNC2	SYNC0	SYNC10	SYNC6	1
3	SYNC3	SYNC1	SYNC11	SYNC7	1
4	SYNC4	SYNC2	SYNC12	SYNC8	1
5	SYNC5	SYNC3	SYNC13	SYNC9	1
6	SYNC6	SYNC4	SYNC14	SYNC10	1
7	SYNC7	SYNC5	SYNC15	SYNC11	0

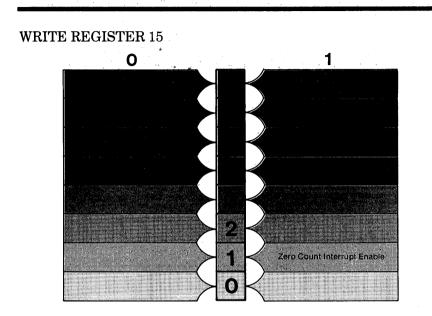








Serial Communications Controller



- **Functions** READ DATA This function reads character data. INPUT: DATA
 - READ SCC REGISTERS
 This function reads Read Register 0-15.
 OUTPUT: SCC REGISTER POINTER =
 register #

 INPUT: SCC REGISTER POINTER = data
 - WRITE DATA This function writes character data. OUTPUT: DATA
 - WRITE SCC REGISTER OUTPUT: SCC REGISTER POINTER = register # OUTPUT: SCC REGISTER POINTER = data

Sequencing and Timing	The SCC has direct addressing for the data reg- ister only. To access the other SCC registers, first write the register number to the SCC Regis- ter Pointer and then read or write the register using the SCC Register Pointer.
	The SCC can operate in three basic modes to transfer data, status and control information:
•	polling
•	interrupt
•	block
	The block mode is not used on the AT&T Per- sonal Computer 6300.
	In the polling mode, Receive Character Availa- ble and Transmit Buffer Empty in Read Register 0 are examined before receiving and sending a character. All interrupt functions must be dis- able. To do this, clear the Master Bit Enable and set the No Vector bit in Write Register 9. Then clear Write Register 1. This disables specific types of interrupts.
	For interrupt mode, the Master Interrupt Enable in Write Register 9 must be set. In addition, bits 3-4 in Write Register 1 specify interrupts on receive character conditions. Bit 1 in Write Reg- ister 1 enables interrupts on Transmit Buffer Empty. Bit 0 enables External/Status interrupt. This interrupt is caused by transmit underrun condition, a zero count in the baud rate genera-

Interrupt sources have the following priority:

Receive Channel A Transmit Channel A External/Status Channel A Receive Channel B Transmit Channel B Receive Channel B

A bit in Read Register 3 is set to indicate the highest priority device needing service. You can read the vector address of the interrupt service routine in Read Register 2 if it was programmed. If this vector is read on Channel B, it includes status bits. Vectors are initialized with Write Register 2. The interrupt service routine resets the Highest Interrupt Under Service in Write Register 0. Other interrupts are reset in Write Register 0.

To set the baud rate, first clear bits 0-1 in Write Register 14. Then load Write Register 12 and 13 with the time constant. Last set bit 0-1 in Write Register 14 to enable the baud rate generator. To use the baud rate, set the transmit and receive clocks in Write Register 11 to the baud rate generator.

To determine the time constant to use for a given baud rate, use this formula:

3,686,400 (16)(2)(Baud Rate) -2 = Time Constant

The following table states the divisors to use to obtain a given baud rate.

BAUD RATES USING 3.6864 MHZ CLOCK

BAUD RATE	TIME CONSTANT
110	1045
150	766
300	382
600	190
1200	94
2400	46
4800	22
9600	10

In Asynchronous mode, you initialize:

- Write Register 1 to disable DMA transfers and to enable or disable interrupts,
- Write Register 3 to set Receive Enable and the number of bits per receive character, to disable synchronous functions, and to enable or disable Auto Enable,
- Write Register 4 to set parity, stop bits, and data rate, and to disable synchronous mode,
- Write Register 5 to set Transmit Enable and the number of bits per transmit character, to enable or disable Request to Send, Data Terminal Ready and Send Break, and disable synchronous functions,
- Write Register 9 to force a reset and set interrupt parameters,
- Write Register 10 to choose an encoding method,
- Write Register 11 to select clock sources,
- Write Register 12 and 13 to set the baud rate time constant, and
- Write Register 15 to enable the baud rate generator.

To transmit a character, wait for Transmit Buffer Empty to be set in Read Register 1 of the SCC. Then write the character to the Data Register.

To receive a character, wait for Receive Character Ready in the Read Register 1 of the SCC. Then read the character from the Data Register.

In synchronous mode, you must transfer the data using interrupts. The External/Status interrupt is used to monitor the status of Clear to Send and Transmit Underrun/EOM latch.

In bisynchronous mode, you initialize:

- Write Register 0 to reset Transmit Underrun/EOM Latch, receive CRC checker, external/ status interrupts, and enable interrupts on next receive character,
- Write Register 3 to enable the receiver, and to program Sync Character Load Inhibit, Enter Hunt For Sync Character, and number of bits per receive character,
- Write Register 4 to set parity, enable sync modes, number of bits per sync character, and clock mode,
- Write Register 5 to enable Transmit CRC, to request 16-bit CRC polynomial, enable transmit, transmit 8 bits per character, and to set Data Terminal Ready and Request to Send,
- Write Register 6 and 7 to set the sync bytes,
- Write Register 9 first to reset the hardware and later to set interrupts and vector variables,

- Write Register 10 to set length of sync character, the encoding method, to preset the CRC generator and to set the loop mode and go active on poll if wanted,
- Write Register 11 to set the clock sources, and
- Write Register 15 to set interrupt enable conditions.

The monosync transmitter is initialized as a bisynchronous transmitter with two exceptions:

- Only one sync character is written, and
- The 6-bit or 8-bit selection in Write Register 10 must be made.

In SDLC mode, you initialize:

- Write Register 0 to reset the transmit CRC generator after transmit enable has been done and to enable interrupts,
- Write Register 1 to enable interrupts,
- Write Register 3 to select bits per receive character, to set address search mode, to enable CRC receiver and receive enable,
- Write Register 4 to set SDLC mode before anything else is initialized and later to set clock mode,
- Write Register 5 to select the SDLC-CRC polynomial, to set Request to Send, Data Terminal Ready, transmit character length, transmit enable, and transmit CRC enable
- Write Register 6 to contain the secondary address field,

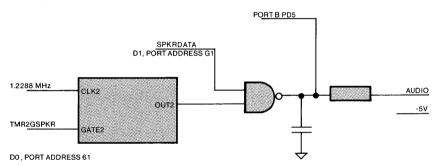
	• Write Register 7 to contain flag character 01111110,				
	• Write Register 9 to reset the hardware and to set interrupt parameters,				
	• Write Register 10 to set loop mode, Go Active on Poll, Mark/Idle Flag, Abort on Underrun, the CRC preset condition, and the encoding mode,				
	• Write Register 11 to set clock sources,				
	 Write Register 14 to set the clock source for the DPLL, and 				
	• Write Register 15 to set interrupt enable condition.				
Sample Program					
	, PTER EQU 5	0			
	DATA EQU 51				
	RECEIVE:				
	MOV DX,PTER	;Pointer Port Address			
	XOR AL,AL OUT DX,AL	;AL = 0 ;Select Read Register 0			
	REC1: IN AL,DX ;Get Read Register 0				
	TEST AL,1 ;Receive character available				
	JZ REC1 ;Jump if no character				
	MOV DX,DATA IN AL,DX	;Data Port Address ;Read character			
	RET	,			

Speaker

Functional Description

The speaker uses a permanent magnet speaker which is driven by one of two sources. Counter 2 of the Interval Timer can be programmed to automatically generate a pulse train. A bit in the Keyboard Control Register controls this pulse train. A bit in the Keyboard Control Register can also be programmed to manually generate a pulse train.

Block Diagram



Registers

PORT #	NAME	READ/ WRITE	DESCRIPTION
61	KEYBOARD CONTROL	W	Contains speaker enable and manual pulse train bits. See Keyboard documentation.
42	COUNTER 2	R/W	Counter for audio speaker tone generation. See Timer documentation.
43	TIMER CONTROL	W	Control register for Interval Timer. See Interval Timer documentation.

Functions • AUTOMATIC PULSE TRAIN This function automatically generates an audible sound. OUTPUT: INTERVAL TIMER CONTROL REGISTER BITS 1-3 = 3, square wave rate generator BITS 4-5 = 3, set counter BITS 6-7 = 2, generator INTERVAL TIME COUNTER 2 KEYBOARD CONTROL BIT 0= 1, turns on speaker
• MANUAL PULSE TRAIN

MANUAL PULSE TRAIN
 This function manually generates an audible sound.
 OUTPUT: KEYBOARD CONTROL
 BIT 1 This bit is set and cleared to generate a pulse train.

Sequencing and Timing	Input to the timer is $1.2288MHz$. To generate a 1.00 KHz tone with the audio speaker, a square wave rate generator is used with a count of 614 (1.2288MHz/2*614 = 1KHz).			
Sample Program	; BEEP : This program sounds the beep manually ; KEY_CONTROL EQU 61 TIMER_CONTROL EQU 43 BEEP: MOV DX, TIMER_CONTROL ;port address MOV AL, B8H ;of timer OUT DX, AL ;set channel 2 ;in mode 4 MOV DX, KEY_CONTROL IN AL,DX MOV AH,AL OR AH, 01H ;turn on Gate MOV BL, 80H BEEP1:	2		
	MOV AL, AH ;restore value AND AL, OFDH OUT DX, AL MOV CX, 48H LOOP \$ MOV AL, AH OR AL, 02H OUT DX, AL MOVE CX, 48H LOOP \$ DEC BL JNZ BEEP1 MOV AL,AH OUT DX,AL RET			

Video Controller

Functional Description	The AT&T Personal Computer 6300 Display Controller interfaces the CPU to either mono-
	chrome or color displays. It uses a HD6845 CRT Controller. The Display Controller operates in two basic modes — text or all points addressable
	(APR) graphics. Several resolutions are avail- able depending on the mode and display.

RESOLUTION	PC	GRAPHIC/	COLOR/
	COMPATIBLE	TEXT	MONOCHROME
80X25	YES	T	C/M
40X25	YES	T	C/M
640X400	NO	Ğ	М
640X200	YES	G	M
320X200	YES	G	C

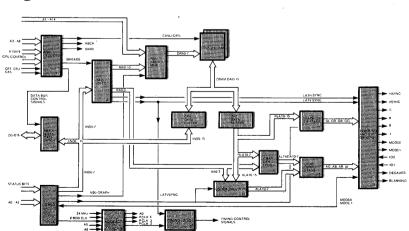
In text mode, character attributes include reverse video, blinking, highlight, hide and underline. In color mode if blinking is not requested, one of 16 colors can be chosen. Otherwise, one of 8 colors can be chosen.

In graphic mode, each pixel on a color monitor is one of four selected colors. These four colors are from a choice of 16. In a monochrome monitor, these 16 colors are shades of gray from black to white.

The Display Controller has 32K of RAM to refresh one screen page.

The Display Controller can be upgraded with an optional board. This board gives you the following features:

- Up to three additional screen pages in RAM
- Software controlled look-up table for an international character set
- High resolution characters (16 X 16 pixels instead of 8 X 16 pixels)
- Hardware smooth scroll
- The ability to mix text and graphic modes simultaneously
- Up to 16 colors can be displayed at once



Block Diagram

Registers

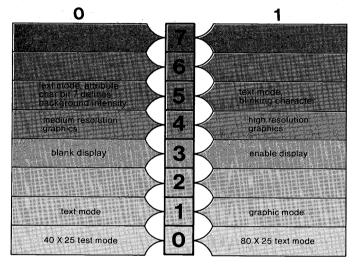
PORT #	NAME	READ/ WRITE	DESCRIPTION
3D8	MODE SELECT REGISTER 1	w	See layout
3D9	COLOR SELECT REGISTER	W	See layout
3DA	STATUS REGISTER	R	See layout
3DE	MODE SELECT REGISTER 2	W	See layout
3D4	POINTER TO HD6845 REGISTER	W	
3D5	HD6845 DATA REGISTER	R/W	

HD6845 Registers

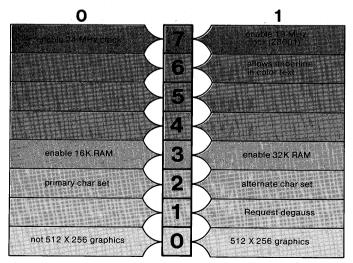
NO	NAME	READ/	INITIA	ALIZAT	ION VALUE
		WRITE	40X25	80X25	GRAPHIC
0	HORIZONTAL TOTAL	W	38	71	38
1	HORIZONTAL DISPLAYED	W	28	50	28
2	HORIZONTAL SYNC POSITION	W	2D	5 A	$2\mathrm{D}$
3	HORIZONTAL SYNC WIDTH	W	06	0C	06
4	VERTICAL TOTAL	W	$1\mathbf{F}$	1F	7F
5	VERTICAL TOTAL ADJUST	W	06	06	06
6	VERTICAL DISPLAYED	W	19	19	64
7	VERTICAL SYNC POSITION	W	1C	1C	70
8	INTERLACE MODE	W	02	02	02
9	MAX. SCAN LINE ADDRESS	W	07	07	01
Α	CURSOR START LINE (SIZE)	W	06	06	06
	CURSOR END LINE	W	07	07	07
С	ACTIVE PAGE START ADDR (H)	W	00	00	00
D	ACTIVE PAGE START ADDR (L)	W	00	00	00
\mathbf{E}	CURSOR ADDRESS (H)	R/W			
\mathbf{F}	CURSOR ADDRESS (L)	R/W			
	LIGHT PEN (H)	R			
11	LIGHT PEN (L)	R			

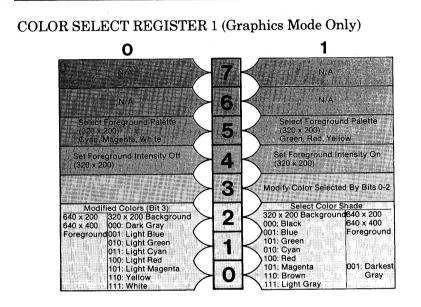
Layout

MODE SELECT REGISTER 1

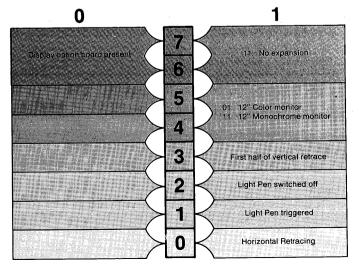


MODE SELECT REGISTER 2





STATUS REGISTER



Text Mode Every character position is defined by two bytes:

15	14	13	12	11	10	9	8	7°	6	5	4	3.	2	1	0
Ι	R	G	В	Ι	R	G	В	A	SC	II (CH	AR	CC	DD	E

Background Foreground Attribute Byte

If neither the underline or blinking capabilities are specified, the color choice for foreground and background with a color monitor is:

Black	Red
Blue	Magenta
Green	Brown
Cyan	Light Gray
Dark Gray	Light Red
Light Blue	Light Magenta
Light Green	Yellow
Light Cyan	White

With a monochrome monitor, the color choice is:

Black Darkest Gray

Lightest Gray

White

The codes for common monochrome choices follow:

normal	00001111
reverse video	11110000
non-display black	00000000
non-display white	11111111

When the blinking capability is specified in Mode Select 1, then Bit 15 of the attribute byte specifies whether the character blinks.

If the underline capability is specified in the Mode Select Register 2, then Bit 11 specifies whether the character is underlined.

The first position in the left-hand corner of the screen is defined in the first two bytes of memory starting at B0000. The next position, one column to the right, is defined in the next two bytes of memory at B0002. The first character in the next row follows immediately after the definition for the last character in the first row. For 80 column X 25 rows, memory looks like this:

B0000 B00A0 B0140	Row 1 Row 2 Row 3
	•
	•
	•
B0E60 B0F00	Row 24 Row 25

The 80 column display uses 4K of RAM and the 40 column display uses 2K of RAM. The rest of the 32K is used for multiple screen images called pages. There are either 16 or eight pages available.

Graphics Mode

In graphics mode, the display screen is a grid of pixels, the smallest displayable unit on a video monitor. In medium resolution, there are 640 across and either 200 or 400 down.

In high resolution, each pixel is defined by one bit. Bit 7 of each byte defines the first pixel and bit 0 defines the last pixel to be displayed. The background color is always black and is displayed when the pixel is off. When the pixel is on, the foreground color is one of 16 shades of gray as defined in the Color Select Register Bits 0-2 and 3.

In medium resolution, each pixel is defined by two bits:

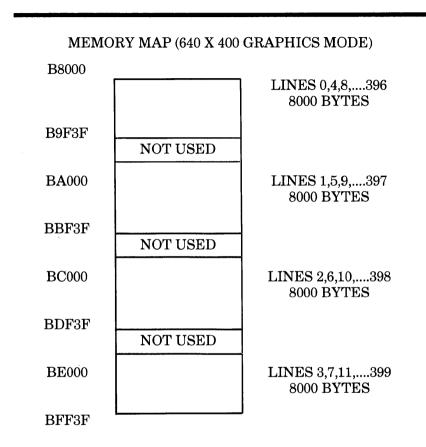
76	54	32	10	
1st	2nd	3rd	4th	PIXELS

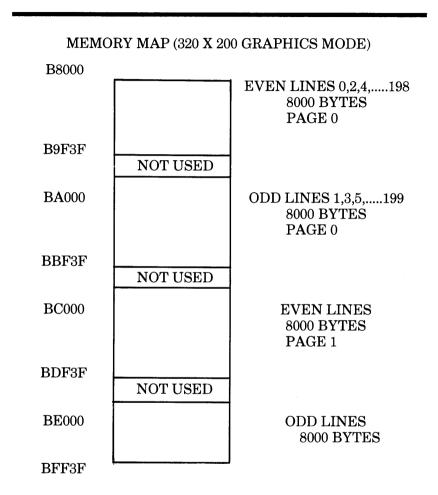
The value of two bits define one of four preselected colors.

- 3 color 3

The background color is defined by Bits 0-3 in the Color Select Register. Colors 1, 2, and 3 are cyan, magenta and white if Bit 5 of the Color Select Register is zero and are green, red, and yellow if Bit 5 is one.

Unlike the text mode, rows of pixels do not follow one after another in memory. The following memory maps illustrate the layouts.





 Functions
 INITIALIZE HD6845 This function initializes the 16 registers of the HD6845 with predetermined values. OUTPUT: POINTER TO HD6845 REGISTER Number of HD6845 register HD6845 DATA REGISTER Value of HD6845 register (Repeat 16 times for each register)

> SET MODE Set different mode characteristics such as text or graphics, type of graphics, blinking character, etc.
> OUTPUT: MODE SELECT 1 MODE SELECT 2

• SET COLOR TYPE Choose the different color or shades of gray to display. OUTPUT: COLOR SELECT REGISTER

 SET CURSOR SIZE Set starting and ending line for cursor. OUTPUT: POINTER TO HD6845 REGISTER 0AH HD6845 DATA REGISTER start line POINTER TO HD6845 REGISTER 0BH HD6845 DATA REGISTER end line

•	SET CURSOR POSITION Set cursor to location in memory.
	OUTPUT: POINTER TO HD6845 REGISTER 0EH
	HD6845 DATA REGISTER
	most significant byte of address
	POINTER TO H36845 REGISTER 0FH
	HD6845 DATA REGISTER
	least significant byte of address
•	READ CURSOR POSITION
	Read the current position of the cursor.
	INPUT: POINTER TO HD6845 REGISTER
	HD6845 DATA REGISTER
	most significant byte of address POINTER TO H36845 REGISTER
	0FH
	HD6845 DATA REGISTER
	least significant byte of address
	SET ACTIVE PAGE
	Set the address of the current page to display.
	OUTPUT: POINTER TO HD6845 REGISTER 0CH
	HD6845 DATA REGISTER
	most significant byte of address
	POINTER TO H36845 REGISTER
	0DH
	HD6845 DATA REGISTER
	least significant byte of address
Sequencing	There are two methods of communicating with
and Timing	the video display. One is with I/O commands.

There are two methods of communicating with the video display. One is with I/O commands. This method is used to set the modes of operation, the cursor position, the cursor size or the current active page.

Scrambler ROM

•														
	For programs which do not use the regular BIOS calls, the 6845 CRT controller requires some additional circuitry to translate the data sent to it by application programs into the appropriate data for the display controller. This circuitry (called the scrambler circuitry) converts the IBM6845 register values to the values which the display controller requires. A listing of these conversions follows. For additional information see the AT&T Per- sonal Computer 6300 reference manual.													
SUDOM.	7 (USED ON RI	V D1-D20)												
	ognized comma	,												
*DIS	-													
0000	39 39 39 39	39/39/39/39/39	9 39 39 39 39 39 39 39 999999999999999											
0010	39 39 39 39													
0020	39 39 39 39		9 39 39 39 39 39 39 39 9999999999999999											
0030		39 39 39 39 39												
0040		39 39 39 39 39												
0050			3 73 73 73 73 73 73 73 999999sssssssss											
0060			3 73 73 73 73 73 73 73 73 seeseeseeseese											
0070 0080	73 73 73 73 73 00 01 02 03		3 73 73 73 73 73 73 73 73 sssssssssssss											
0000	10 11 12 13													
00A0			8 19 1A 18 18 18 18 18 18 8 29 2A 2B 2C 2D 2E 2F _!″#\$%&`()*+,/											
00B0			8 39 3A 3B 3C 3D 3E 3F 0123456789:;<=>?											
0000		44 45 46 47 48												
00D0	50 51 52 53		8 59 5A 5B 5C 5D 5E 5F PQRSTUVWXYZ[\]A_											
00E0		64 65 66 67 68												
00F0	70 71 72 73	74 75 76 77 78	8 79 7A 7B 7C 7D 7E 7F pqrstuvwxyz{ }~.											
0100	00 01 02 03	04 05 06 07 - 08	8 09 0A 0B 0C 0D 0E 0F											
0110	10 11 12 13	14 15 16 17 18	8 19 1A 1B 1C 1D 1E 1F											
0120	20 21 22 23	24 25 26 27 - 28	8 29 2A 2B 2C 2D 2E 2F !″#\$%&`()*+,~./											
0130	30 31 32 33													
0140	40 41 42 43	44 45 46 47 48	-											
0150	50 51 52 53		8 59 5A 5B 5C 5D 5E 5F PQRSTUVWXYZ[\]A_											
0160			8 69 6A 6B 6C 6D 6E 6F 'abcdefghijklmno											
0170	70 71 72 73		8 79 7A 7B 7C 7D 7E 7F pqrstuvwxyz{¦}∼.											
0180	00 01 02 03		8 09 0A 08 0C 0D 0E 0F											
0190 0100	10 11 12 13		8 19 1A 1B 1C 1D 1E 1F											
01A0 01B0		24 25 26 27 28 34 35 36 37 38	8 29 2A 2B 2C 2D 2E 2F !″#\$%&`()*+,/ 8 39 3A 3B 3C 3D 3E 3F 0123456789:;<=>?											
01C0	40 41 42 43		18 49 4A 4B 4C 4D 4E 4F @ABCDEFGHIJKLMNO											
01D0	50 51 52 53													
01E0			8 69 6A 6B 6C 6D 6E 6F 'abcdefqhijklmno											
01F0			/8 79 7A 7B 7C 7D 7E 7F p.rstuvwxyz{}}~.											
v														

0200	02	03	04	05	06	07	08	09	ØĤ	ØB	0C	ØD	ØE	ØF	10	11	
0210	12	13	14	15	16	17	18	19	1A	1В	10	1D	1E	1F	20	21	
0220	22	23	24	25	26	27	28	29	28	28	20	2D	2E	2F	30	31	″#\$%&'()*+,∕01
0230	32	33	34	35	36	37	38	39	ЗA	ЗB	30	ЗD	ЗE	ЗF	40	41	23456789:;<=>?@A
0240	42	43	44	45	46	47	48	49	4 0	4B	4C	4D	4E	4F	50	51	BCDEFGHIJKLMNOPQ
0250	52	53	54	55	56	57	58	59	5A	5B	50	5D	5E	5F	60	61	RSTUVWXYZ[\]A_'a
0260	62	63	64	65	66	67	68	69	68	6B	60	6D	6E	6F	70	71	bodefahijklmnopa
0270	72	73	- 24	25	76	77	78	79	28	2B	20	7D	7E	ZF	80	81	rstuvwxyz { !}~
0280	00	01	02	03	04	05	06	07	08	09	. e	0B	00	ØD	0E	ØF	······································
0290	10	11	12	13	14	15	16	17	18	19	1A	18	10	1D	1E	1.F	
02A0	20	21	22	23	24	25	26	27	28		28	28	20	2D	2E	2F	!″#\$%&'{)*+/
02B0	30	31	32	33	34	35	36	37	38	39	3A	38	30	ЗD	ЗE	3F	0123456789:;<=>?
0200	40	41		43	44	45	46	47	48	49	48	4B	4C	4D	4E	4F	@ABCDEFGHIJKLMNO
02D0	50	51	52	53	54	55	56	52	58	.59	58	58	50	50	5E	SE	PQRSTUVWXYZ[\]A_
02E0	60	61	62	63	64	65	66	67	68	69	68	68	60	6D	6E	6F	'abcdefqhijklmno
02F0	- 20	71	72	73	74	25	76	77	- 28	79	28	7B	7Ċ	7D	7E	ZF	pgrstuvwxyz{ }~.
0300	06	06	06	06	06	06	06	06	06	06	09	06	00	ØC	00	0C	
0310	09	09	09	09	09	09	09	09 09	09	09	09	09	09	09	09	09	
0320	09	09	09	09	09	09	09	09	09	09	09	09	09	09	09	09	
0330	09	09	09	09	09	09	09	09	09	09	09	09	09	09	09	09	
0340	09	09	09	09	Ø9	09	09	09	09	09	09	09	09	09	09	09	
0350	09	09	09	09	09	09	09	09	09	09	09	09	09	09	09	09 09	
0360	09	09	09	09	09	09	09	09 09	09	09	09	09 09	09	09	09	09	
0370	09	09	09	09	09	09	09	09	09	09	09	09	09	09	09	09	
0380	09	09	09	09	09	09	09	09	09	09	09	09	09	09	09	09 09	
0390	09	09	09	09	09	09	09	09	09	09	09	09	09	09	09	09	
03A0	09	09	09	09	09	09	09	09	09	09	09	Ø9	09	09	09	09	
03B0	09	09	09	09	09	09	09	09	09	09	09	09	09	Ø9	09	Ø9	
0300	09	09	09	09	Ø9	09	09	09	09	09	09	09	09	09	09	09	
03D0	09	09	09	09	09	09	09	09	09	09	09	09	09 0	09	09	09	
03E0	09	09	09	09	09	09	09	09	09	Ø9	09	09	09	09	09	09	
03F0	09	09	09	09	09	09	09	09	09	09	Ø9	09	09	09	09	06	
0400	18	18	1A	18	1A	1A	1A	18	1A	18	10	16	18	1A	1A	18	
0410	18	18	1A	1A	1A	18	1A	18	18	1A	18	18		16	16	18	
0420	1A	1A	1A	18	1A	1A	1A	10	18	16	16			10	18	18	
0430	1A	1A	1A	18	1A	1Ĥ	18	18	18	1A	16		18		18	18	
0440	1A	68	6B	6B	68	6B	68	ĠВ	6B	6B	68	6B		68	6B	6B	Kkkkkkkkkkkkkk
0450	6B	68	6B	6B	6B	6B	68	68	68	68	6B	6B	6B	68	6B	68	RARAARKKKKKKKK
0460	6B	6B	6B	6B	6B.	68	6B	6B	6B	6B	6B	6B	6B	68	6B	6B	KKKKKKKKKKKK
0470	68	68	6B	6B	6B		6B	6B	6B	68	68	6B	6B	68	6B	6B	kkkkkkkkkk
0480	6B	6B	68	68	6B	6B	6B	6B	ĠВ	6B	6B	6B	6B	6B	6B	68	KKKKKKKKKKKKK
0490	6B	6B	6B	6B	68	6B	6B	6B	68	68	6B	6B	6B	6B	6B	68	kkkkkkkkkkkkkk
04A0	6B	6B	6B		6B	68		6B	6B	6B		6B		ĠВ	6B	6B	kkkkkkkkkkkkkkk
04B0	6B	68	6B	6B	6B	6B	6B	6B	6B	6B	6B		6B	6B	6B	6B	kkkkkkkkkkkkkkk
04C0	6B	6B	68	68	68	6B	6B	6B	6B	6B	6B			68	6B	6B	kkkkkkkkkkkkkk
04D0			6B		6B			6B	6B	6B	68			6B	6B	6B	kkkkkkkkkkkkkk
04E0					6B			6B	6B	6B	6B		6B	6B	6B	6B	kkkkkkkkkkkkk
04F0	6B	6B	68	6B	6B			6B	6B	6B	6B			6B	68	6B	KKKKKKKKKKKK
0500	00	00			00	00	,	00	00	00	00	00	00	00	00	00	
0510	00	00	00	00	00	00		00	00	00	00	00	00	00	00	00	
0520	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0530	00	00	00	00	00	00	00	00	00	00	00	00		00	00	00	
									_		-		-		-		

0540	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0550	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0560	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	• • • • • • • • • • • • • • • • • • •
0570	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	•••••
0580	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0590	00	00	00	00		` 00	00	00	00	00	00	00	00	00	00	00	
05A0	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
05B0	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0500	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
05D0	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	•••••
05E0	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00 00	
05F0	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	•••••
0600	00	Ø1	02	03	04	05	06	07	08	09	ØA	ØB	0C	ØD	ØE	ØF	•••••
0610	10	11	12	13	14	15	16	17	18	19	18	1B	10	1D	1E	1F	1//Д+00 1/1×1/
0620	20	21	22	23	24	25	26	27	28	29	2A	2B	20	2D	2E	2F	!"#\$%&'()*+,/
0630	30	31	32	33	34	35	36	37	38	39	3A	3B 4D	30	3D	3E	3F 4E	0123456789:;<=>?
0640	40	41	42	43	44	45	46	47	48	49	4A	4B	4C	4D	4E	4F	@ABCDEFGHIJKLMNO
0650	50	51	52	53	54	55	56	57	58	59	5A	5B	50	5D	SE CE	5F	PQRSTUVWXYZ[\]A_
0660	60	61	62	63	64	65	66	67	68	69 79	66	6B	60	6D	38	6F 2F	'abcdefghijklmno
0670 0670	70	71 81	72 82	73	74 84	75 85	76 86	77 87	78 88	79 89	2A 8A	78 86	7C 8C	2D 8D	7E 8E	2r 8F	pqrstuvwxyz{ }∼.
0680 0690	80	91	92	83 93	94	95	96	07 97	_	07 99	9A	9B	9C	9D	9E	or 9F	•••••
0690 0680	90 A0	91 A1	92 A2	A3	94 84	95 A5	96 A6	9/ AZ	98 A8	- 22 - A9	- PH - AA	AB	AC	AD	AE	AF	
0680	BØ	81	HZ B2	B3	нч В4	H5 B5	86	н/ В7	BB	нэ В9	BA	BB	BC	BD	BE	BF	
0600	C0	C1	62	C3	C4	C5	C6	67 CZ	C8	69	CA	CB	CC	CD	CE	CF	
06D0	DØ	D1	D2	D3	D4	DS	D6	D7	DB	D9	DA	DB	DC	DD	DE	DF	
06E0	EØ	E1	E2	E3	E4	E5	EG	E7	E8	E9	EA	EB	EC	ED	EE	EF	
06F0	FØ	F1	F2	F3	F4	F5	F6	F7	F8	F9	EA	FB	FC	FD	FE	EF	
0700	19	19	19	19	19	19	19	19	19	19	19	19	19	19	19	19	
0710	19	19	19	19	19	19	19	19	19	19	19	19	19	19	19	19	
0720	19	19	19	19	19	19	19	19	19	19	19	19	19	19	19	19	
0730	19	19	19	19	19	19	19	19	19	19	19	19	19	19	19	19	
0740	19	64	64	64	64	64	64	64	64	64	64	64	64	64	64	64	.dddddddddddddd
0750	64	64	64	64	64	64	64	64	64	64	64	64	64	64	64	64	ddddddddddddd
0760	64	64	64	64	64	64	64	64	64	64	64	64	64	64	64	64	ddddddddddddd
0770	64	64	64	64	64	64	64	64	64	64	64	64	64	64	64	64	dddddddddddddd
0780	64	64	64	64	64	64	64	64	64	64	64	64	64	64	64	64	dddddddddddddd
0790	64	64	64	64	64	64	64	64	64	64	64	64	64	64	64	64	ddddddddddddd
0780	64	64	64	64	64	64	64	64	64	64	64	64	64	64	64	64	ddddddddddddd
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0230	32	33	34	35	36	37	38	39	3		_	30	ЗD	ЗE	ЗF	40	41	23456789:;<=>?@A
0240	42	43	44	45	46	47	48	49	4		_	4C	4D	4E	4F	50	51	BCDEFGHIJKLMNOPQ
0250	52	53	54	55	56	57	58	59	5			SC	5D	SE	5F	60	61	RSTUVWXYZ[\]A_'a
0260	62	63	64	65	66	67	68	69	6			6C	6D	6E	6F	70	71	bcdefghijklmnopq
0270	. –	73	74	75	76	77	78	79	7		-	7C	7D.		7F	80	81	rstuvwxyz{¦}∼
0280	00	Ø1	02	03	04	05	Ø6	07	Ø		-	ØA	ØВ	0C	ØD	ØË	ØF	
0290	10	11	12	13	14	15	16	17	1			1A	18	10	1D	1E	1F	• • • • • • • • • • • • • • • • • • • •
02A0	20	21	22	23	24	25	26	27	2			2A	2B	2C	2D	2E	2F	!~#\$%&`()*+,/
02B0	30	31	32	33	34	35	36	37	З		-	ЗA	ЗB	3С	ЗD	ЗE	ЗF	0123456789:;<=>?
0200	40	41	42	43	44	45	46	47	4			4A	4B	4C	4D	4E	4F	@ABCDEFGHIJKLMNO
02D0	50	51	52	53	54	55	56	57	5		-	5A	5B	5C	5D	SE	SF	PQRSTUVWXYZ[\]^_
02E0	60	61	62	63	64	65	66	67	6			6A	6B	60	6D	6E	6F	'abcdefghijklmno
02F0	70	71	72	73	74	75	76	77	7	37	9	2A	7B	7C	7D	7E	7F	pqrstuvwxyz{¦}∼.
0300	ØE	ØE	ØE	ØE	0E	ØE	ØE	ØE	Ø	E Ø	E	0E	0E	ØE	ØE	0E	ØE	• • • • • • • • • • • • • • • • • • • •
0310	0E		ØE	ØE	0E	ØE	ØE	ØE	0			0E	0E	ØE	ØE	0E	ØE	• • • • • • • • • • • • • • • • • • • •
0320	0E	ØE	0E	ØE	0E	ØE	ØE	0E	0			0E	0E	ØE	0E	0E	ØE	• • • • • • • • • • • • • • • • • • • •
0330	ØE	ØE	0E	ØE	0E	ØE	ØE	ØE	0			0E	ØE	0E	0E	ØE	ØE	• • • • • • • • • • • • • • • • • • • •
0340	ØE	ØE	0E	0E	0E	ØE	0E	ØE	0			0E	ØE	0E	0E	0E	ØE	•••••
0350	ØE	ØE	ØE	ØE	ØE	ØE	0E	ØE	0	Ξ Ø	Έ	ØE	ØË	ØE	ØE	0E	ØE	• • • • • • • • • • • • • • • • • • • •
0360	ØE	ØE	ØE	0E	0E	ØE	0E	ØE	0	ΞØ	Ε	ØE	ØE	ØE	ØE	0E	ØE	
0370	ØE	ØE	ØE.	ØE	ØE	ØE	ØE	ØE	0	Ξ Ø	Έ	0E	ØE	ØE	ØE	0E	ØE	• • • • • • • • • • • • • • • • • • • •
0380	ØE	ØE	0E	ØE	ØE	ØE	ØE	ØE	0	Ξ Ø	Ε	0E	0E	0E	0E	0E	ØE	••••
0390	0E	ØE	0E	ØE	ØE	ØE	ØE	ØE	0			0E	0E	0E	0E	0E	ØE	•••••
03A0	0E	ØE	ØE	ØE	ØE	ØE	ØE	ØE	0			0E	0E	ØE	ØE	0E	ØE	•••••
0380	ØE	ØE	ØE	ØE	ØE	ØE	ØE	ØE	0	ΞØ	Ε	ØE	ØE	ØE	0E	ØE	0E	•••••
03C0	ØE	ØE	ØE	ØE	ØE	ØE	ØE	ØE	0	Ξ Ø	Έ	0E	ØE	0E	ØE	ØE	ØE	
03D0	ØE	0E	0E	ØE	ØE	0E	ØE	ØE	0	Ξ Ø	E	ØĒ	ØE	ØE	ØE	ØE	ØE	
03E0	ØE	0E	0E	ØE	ØE	ØE	ØE	ØE	0	Ξ0	Έ	0E	ØE	ØE	ØE	ØE	ØE	•••••
03F0	ØE	0E	ØE	ØE	ØE	0E	0E	ØE	0			0E	ØE	ØE	ØE	0E	.0E	•••••
0400	18	1A	1A	18	1A	1A	1A	1A	1	1	A.	1A	1A	18	1A	18	1A	•••••
0410	1A	1A	1A	18	18	1A	1A	1A	1			1A	1A	1A	18	1A	1A	
0420	18	1A	18	1A	18	1A	1A	1A	1	9 1	A.	18	18	18	18	18	1A	•••••
0430	18	1A	18	1A	18	1A	1A	1A	1	A 1	Ĥ.	18	1A	1A	18	1A	1A	
0440	1A	6B		6B		6B	6B	6B	6			6B	6B	6B	6B	6B	68	. kiddddddddddddd
0450	6B	6B	6B	6B	6B	6B	6B	6B	6	3 6	8	6B	6B	6B	6B	6B	6B	kkkkkkkkkkkk
0460	6B	6B	6B	6B	6B	6B	6B	6B	6	36	βB	6B	6B	6B	68	6B	6B	kkkkkkkkkkkk
0470	6B	6B	6B	68	6B	6B	6B	6B	6	3 6	βB	6B	68	6B	68	68	6B	kkkkkkkkkkkk
0480	00	01	02	03	04	05	06	07	Ø	30)9	ØA	0B	0C	ØD	ØE	ØF	
0490	10	11	12	13	14	15	16	17	1		.9	18	1B	1C	1D	1E	1F	·····
04A0	20	21	22	23	24	25	26	27	2	8 2	29	2A	2B	2C	2D	2E	2F	!″#\$%&'()*+,/
04B0	30	31	32	33	34	35	36	37	З		39	ЗA	ЗB	30	ЗD	ЗE	ЗF	0123456789:;<=>?
04C0	40	41				45	46	47	4	B 4	19	4A	4B	4C	4D	4E	4F	@ABCDEFGHIJKLMNO
04D0	50	51	52	53	54	55	56	57	5	8 5	59	5A	5B	50	5D	SE	SF	PQRSTUVWXYZ[\]A_
04E0	60	61			64	65	66	67	6		59	6A	6B	60	6D	6E	6F	'abcdefghijklmno
04F0	70	71	72	73	74	75	76	77	7	8 7	'9	7A	7B	20	7D	7E	7F	pqrstuvwxyz{¦}∼.

0500	00	00	00	00	00	00	00	00	aa	00	00	00	00	00	00	00	
0510	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0520	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0530	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0540	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0550	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0560	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0570	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0580	00	01	02	03	04	05	06	07	08	09	ØA	ØB	0C	ØD	ØE	ØF	
0590	10	11	12	13	14	15	16	17	18	19	18	1B	10	1D	1E	1F	
05A0	20	21	22	23	24	25	26	27	28	29	28	2B	20	2D	2E	2F	!″ # \$%&'()*+,/
0580	30	31	32	33	34	35	36	37	38	39	38	3B	30	30	ЗE	3F	0123456789:;<=>?
0500	40	41	42	43	44	45	46	47	48	49	48	4B	4C	4D	4E	4F	@ABCDEFGHIJKLMNO
05D0	50	51	52	53	54	55	56	57	58	59	5A	5B	SC	5D	SE	5F	PQRSTUVWXYZ[\]A
05E0	60	61	62	63	64	65	66	67	68	69	68	6B	60	6D	6E	6F	'abcdefghijklmno
05F0	70	71	72	73	74	25	26	77	78	79	28	7B	20	70	7E	ZF	pqrstuvwxyz{}}~.
0600	00	01	02	03	04	05	06	07	08	09	0A	ØB	00	0D	ØE	ØF	
0610	10	11	12	13	14	15	16	17	18	19	18	18	10	10	1E	1F	• • • • • • • • • • • • • • • • • • • •
0620	20	21	22	23	24	25	26	27	28	29	28	2B	20	2D	2E	2F	!″ # \$%& ` {`}*+,/
0630	30	31	32	33	34	35	36	37	38	39	38	3B	30	3D	3E	21 3F	0123456789 :: <=>?
0640	40	41	42	43	44	45	46	47	48	49	4A	4B	4C	4D	4E	ىر 4F	@ABCDEFGHIJKLMNO
0650	50	51	52	53	54	55	56	57	58	59	58	5B	50	40 50	SE	SF	PORSTUVWXYZ[\]A_
0660	60	61	62	63	64	65	66	67 -	68	69	6A	6B	60	6D	6E	6F	
0670	20	21	72	73	74	25	76	77	78	79	28	2B	20	7D	7E	2F	'abcdefghijklmno pqrstuvwxyz{¦}∼.
0680	80	81	82	83	84	85	86	87	88	89	88	88	80	8D	8E	8F	
0690	90	91	92	93	94	95	96	97	98	99	98	9B	90	9D	9E	9F	•••••
06A0	AØ	A1	A2	AG	84	A5	86	67 87	68	69	88	AB	AC.	AD	AE	P! BE	
06B0	BØ	B1	B2	83	B4	85	B6	B7	88	B9	BA	BB	BC	BD	BE	BF	
0600	CØ	C1	C2	С3	C4	65	C6	C7	CB	C9	CA	СВ	CC	CD	CE	CF	•••••
06D0	DØ	D1	D2	D3	D4	D5	DG	D7	DB	D9	DA	DB	DC	DD	DE	DF	
06E0	FØ	E1	E2	E3	E4	E5	E6	E7	EB	E9	EA			ED	EE	EF	
06F0	FØ	F1	F2	F3	F4	F5	F6	E7	F8	F9	FA				FE	FF	
0700	19	19	19	19	19	19	19	19	19	19	19	19	19	19	19	19	
0710	19	19	19	19	19	19	19	19	19	19	19	19	19	19	19	19	
0720	19	19	19	19	19	19	19	19	19	19	19	19	19	19	19	19	
0730	19	19	19	19	19	19	19	19	19	19	19	19	19	19	19	19	
0740	19	64	64	64	64	64	64	64	64	64	64	64	64	64	64	64	.ddddddddddddd
0750	64	64	64	64	64	64	64	64	64	64	64	64	64	64	64	64	dddddddddddddd
0760	64	64	64	64	64	64	64	64	-64	64	64	64	64	64	64	64	ddddddddddddd
0770	64	64	64	64	64	64	64	64	64	64	64	64	64	64	64	64	dddddddddddddd
0780	00	01	02	0З	04	05	Ø6	07	08	09	ØA	ØВ	0C	ØD	ØE	ØΕ	
0790	10	11	12	13	14	15	16	17	18	19	1A	18	1C	1D	1E	1F	
07A0	20	21	22	23	24	25	26	27	28	29	2A	28	2C	2D	2E	2F	!~#\$%&?()*+,/
0780	30	31	32	33	34	35	ЗG	37	38	39	ЗA	38	30	ЗD	3E	ЗF	0123456789:;<=>?
0700	40	41	42	43	44	45	46	47	48	49	4A	4B	4C	4D	4E	4F	@ABCDEFGHIJKLMNO
07D0	50	51	52	53	54	55	56	57	58	59	5A	5B	50	5D	5E	5F	PQRSTUVWXYZ[\]A_
07E0	60	61	62	63	64	65	66	67	68	69	6A	6B	60	6D	6E	6F	'abcdefghijklmno
07F0	70	71	72	73	74	25	76	77	78	Z9	ZA	7B	70	7D	7E	ZF	pqrstuvwxyz{¦}~.
0800	00	00	00	ØЗ	00	00	00	00	00	00	00	00	00	00	00	00	
0810	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0820	00.	00	00	00	00	00	00	00	00	00	00	00	00	00	0Ø	00	
0830	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	

0840	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0850	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0860	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0870	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0880	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0890	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
08A0	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
08B0	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0800	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
08D0	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
08E0	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
08F0	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0900	01	03	05	03	09	ØB	ØD	ØF	11	13	15	17	19	1B	1D	ØF	
0910	21	23	25	27	29	2B	2D	2F	31	33	35	37	39	ЗВ	ЗD	ЗF	!#%')+-/13579;=?
0920	41	43	45	47	49	4B	4D	4F	51	53	55	57	59	5B	5D	5F	ACEGIKMOQSUWY[]
0930	61	63	65	67	69	6B	6D	6F	71	73	75	77	79	7B	7D	7F	acegikmoqşuwy{}.
0940	81	83	85	87	89	88	8D	8F	91	93	95	97	99	98	9D	9F	
0950	A1	AЗ	A5	AZ	A9	ĤΒ	AD	ΑF	В1	B3	В5	B7	89	BB	ВD	BF	
0960	Ċ1	СЗ	C5	C7	69	СВ	CD	CF	D1	DЗ	D5	D7	D9	DB	DD	DF	
0970	E1	E3	E5	E7	E9	EΒ	ED	ΕF	F1	FЗ	F,5	FZ	۴9	FΒ	FD	FF	
0980	00	01	02	03	04	05	06	07	08	Ø9	ØA	08	0C	ØD	ØË	ØF	
0990	10	11	12	13	14	15	16	17	18	19	16	18	10	1D	1E	1F	
09A0	20	21	22	23	24	25	26	27	28	29	2A	28	20	20	2E	2F	!″#\$%&'()*+,/
0980	30	31	32	33	34	35	36	37	38	39	ЗA	ЗВ	30	30	ЗE	ЗF	0123456789:;<=>?
0900	40	41	42	43	44	45	46	47	48	49	4A	4B	4C	4D	4E	4F	@ABCDEFGHIJKLMNO
09D0	50	51	52	53	54	55	56	57	58	59	5A	5B	5C	5D	5E	5F	PORSTUVWXYZ[\]A_
09E0	60	61	62	63	64	65	66	67	68	69	68	6B	60	6D	6E	6F	'abcdefqhijklmno
09F0	70	71	72	73	74	75	76	77	78	79	2Ĥ	2B	20	7D	7E	7F	pgrstuvwxyz{!}~.
0A00	00	02	04	Ø6	08	0A	0C	0E	10	10	10	10	10	10	10	10	
0A10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	
0A20	20	22	24	26	28	2A	20	2E	30	30	30	30	30	30	30	30	~\$&(*,.00000000
0A30	30	30	30	30	30	30	30	30	30	30	30	30	30	30	30	30	000000000000000000
0A40	40	42	44	46	48	40	4C	4E	50	50	50	50	50	50	50	50	@BDFHJLNPPPPPP
0A50	50	50	50	50	50	50	50	50	50	50	50	50	50	50	50	50	PPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPP
0A60	60	62	64	66	68	6A	6C	6E	70	70	20	70	20	70	70	70	'bdfhjlnppppppp
0A70	70	20	70	Ż0	70	20	70	70	70	-70	70	70	70	70	20	20	qqqqqqqqqqqqqqqqq
0A80	00	01	02	03	04	05	Ø6	07	08	Ø9	ØĤ	ØВ	ØC	ØD	ØE	ØF	
0A90	10	11	12	13	14	15	16	17	18	19	1A	18	10	1D	1E	1F	
ØAAØ	20	21	22	23	24	25	26	27	28	29	2Ŕ	2B	20	2D	2E	2F	!″#\$%&`()*+,/
ØABØ	30	31	32	33	34	35	36	37	38	39	ЗA	38	30	ЗD	ЗE	ЗF	0123456789:;<=>?
ØACØ	40	41	42	43	44	45	46	47	48	49	4Ĥ	4B	4C	4D	4E	4F	@ABCDEFGHIJKLMNO
ØADØ	50	51	52	53	54	55	56	57	58	59	5A	SB	50	5D	5E	SF	PQRSTUVWXYZ[\]^_
ØAEØ	60	61	62 62	63	64	65	66	67	68	69	6A	6B	60	6D	6E	6F	'abcdefghijklmno
ØAFØ	70	71	72	73	74	75	76	77	78	79	7A	7B	20	7D	7E	7F	pgrstuvuxyz{!}~.
Ø800	00	02	04	06	08	0A	ØC	ØE	10	12	14	16	18	1A	10	1E	
ØB10	20	22	24	26	28	2A	2C	2E	30	32	34	36	38	ЗA	30	ЗE	″\$&(*,.02468 : <>
ØB20	40	42	44	46	48	4A	4C	4E	50	52	54	56	58	5A	50	5E	@BDFHJLNPRTVXZ\
ØB30	60	62	64	66	68	68	60	6E	70	72	74	76	78	28	7B	7E	'bdfhjlnprtvxz ∼
0B40	80	82	84	86	88	BA	80	8E	90	92		96	98	9A	90	9E	
0B50	AØ	A2	A4	-A6		AA	AC	AE	вØ	82		86	B8		BC	BE	
0B60	CØ	C2	C4	06	C8	CA	CC	CE	DØ	D2	D4	DG	DB	DA	DC	DE	
0B70	ΕØ	E2		E6			EC		FØ			F6					
													-		_	-	

0800 <																		
06808 20 21 22 24 25 26 27 28 29 20 22 27 24 25 26 27 28 29 20 22 27 27 28 29 20 22 27	0880	00	01		ØЗ	04	05	06	07	08	09	ØA	0B	ØC	ØD	ØE	ØF	•••••
06B0 30 31 32 33 43 36 37 38 39 34 35 36 30 32 33 44 45 46 47 48 49 44 <		-																
08C0 40 41 42 34 45 64 48 49 44 46 40 46 47 PORSTUNKLY2(1) 08C0 66 66 66 66 66 66 66 67 76 PORSTUNKLY2(1) 08C0 60 61 62 66 66 66 66 66 67 76 PORSTUNKLY2(1) 02C0 00 01 02 03 40 56 67 78 79 74 75 77 78 70 70 77 77 77 78 77 78 77 78 77 78 77 78 77 78 77 78 <	ØBAØ	20	21	22	23	24	25			28	29	2A	2B	2C	2D	2E	2F	
08D0 50 51 52 53 54 55 56 <	0BB0	30	31	32	33	34		36	37	38		ЗA	3B		ЗD			,
08E0 60 61 62 63 64 65 66 67 78 79 78 79 78 79 78 70 72 77 79 78 79 78 79 78 70 72 77 79 78 79 78 79 78 70 70 77 77 79 78 79 78 79 78 79 78 79 78 79 78 79 78 79 77 70 <	ØBCØ	40	41	42	43	44	45	46	47	48	49	4A	4B	4C	4D	4E	4F	@ABCDEFGHIJKLMNO
08F0 20 71 72 73 74 75 76 72 78 79 74 78 72 78 79 74 78 72 78 79 74 78 70 72 77 78 79 74 78 70 72 77 78 79 74 78 70 78 70 78 70 78 71 72 71 72 <	ØBDØ	50	51	52	53	54	55	56	57	58	59	5A	5B	SC	5D	5E	5F	PQRSTUVWXYZ[\]^_
0000 00 01 02 03 04 05 06 07 08 09 0A 08 00 06 06 06 07 08 09 0A 08 00 06 06 06 07 08 09 0A 08 00 06 06 06 02 24 25 66 <	0BE0	60	61	62	63	64	65	66	67	68	69	6A	6B	60	6D	6E	6F	'abcdefghijklmno
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The Display Enhancement Board

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DEB Capabilities

- Introduction
- The DEB Driver
- 16-Color Graphics
- Look-Up Table (LUT)
- Overlay Modes

The Display Enhancement Board (DEB) option adds improved color and graphics functionality to your AT&T PC 6300. When you use the DEB with the PC 6300 color monitor, you can display graphics in up to 16 color combinations simultaneously or treat the screen as two screens in one and overlay one screen treatment on top of the other. When you use the DEB with the PC 6300 monochrome monitor, you have the same capabilities you have with the color monitor, except that colors are displayed as "shades of green."

The DEB is compatible with existing software, so all the programs you have already can be used now as if the DEB were not installed. Of course, these programs may not have access to any of the new capabilities.

This supplement describes the functionality of the DEB device driver. Although it is not necessary to use the driver in order to use the DEB, the driver is designed to work with MS-DOS, GWBASIC, and other AT&T software products. If you wish to program the DEB hardware directly, you must consult the *AT&T Technical Reference Manual*. Such programming is considered a circumvention of the AT&T operating system and we advise against it.

This supplement assumes that you are familiar with video programming through the Interrupt 10H interface and with INTEL® 8086 assembler programming. Information on the Interrupt 10H interface can be found in the *System Programmer's Guide*, in the section on the ROM BIOS Service Routines. Before you begin writing programs for the DEB, follow the procedures in the DEB Installation Manual for installing the DEB hardware and device driver software.

The DEB is an optional hardware component for the AT&T PC 6300 that works in conjunction with the PC 6300's built-in Video Display Controller (VDC) to provide improved color and graphics functionality.

The built-in VDC contains circuitry and memory that support either 4 color medium resolution $(320 \times 200 \text{ pixels})$ graphics, 1 color high resolution $(640 \times 200 \text{ pixels})$ graphics, or 1 color super resolution $(640 \times 400 \text{ pixels})$ graphics.

The DEB contains additional circuitry and memory that can be combined with the capabilities of the built-in VDC to produce up to 16 color combinations in either high or super resolution. You can also program the VDC and DEB separately, treating them as two separate images that are combined on one screen to produce an overlaying effect. The overlay modes let you use up to 8 colors on the DEB screen and up to 16 colors on the VDC screen. You load the DEB device driver by entering a "DEVICE" statement in the CONFIG.SYS file (see **Chapter 2, Programming Tips**). The driver installs an Interrupt 10H "filter" during the loading process.

When you are using the DEB and are running some programs that use the DEB and some that do not, the "filter" provides video support for both kinds of programs. For programs that do not use the DEB, the filter passes control to the standard Interrupt 10H ROM BIOS routine.

The DEB driver installs a filter for Interrupt 9H. This filter resets the DEB to transparent mode whenever you warmstart the system through **CTRL/ALT/DEL**. The filter controls scrolling when you press **CTRL/NUMLOCK**. This feature lets you display 16 color combinations in either high resolution (640×200) or super resolution (640×400). Not only can you use the standard 16 colors, you can also combine colors to form new colors and cause pixels to blink from one color to another.

The DEB provides 5 palettes for you to use when programming in color. At any point in your program, you select one of the palettes as the "active" palette. The color combinations contained in that palette determine what colors and effects show on the screen.

Each of the first 4 palettes contains a default set of 16 color combinations, but to suit the needs of your program you can change the contents of the palette to any one of the following:

• any of the 16 standard colors with which you are already familiar from the standard applications. The standard colors are:

0 = black	8 = gray
1 = blue	9 = light blue
2 = green	10 = light green
3 = cyan	11 = light cyan
4 = red	12 = light red
5 = magenta	13 = light magenta
6 = brown	14 = yellow
7 = white	15 = high intensity white

- a mixture, or "dithering," of any 2 of the 16 standard colors
- an alternation, or blinking, between any 2 of the standard 16 colors

The last palette contains no default combinations. You program the fifth palette by loading color values into a 256-byte array. The DEB device driver uses this special palette to program the DEB's color Look-Up Table (LUT). By using the LUT you can add the capability of dithering or blinking between any four colors.

Look-Up Table (LUT)

The LUT resides in RAM on the DEB board, and is accessed through write-only hardware registers. The device driver keeps a copy of the register values in the LUT. The register values are accessible to software applications through the device driver. The LUT contains 256 values that determine the colors, blinking, and dithering that appear on the screen. Whether you need to learn about the use and layout of the LUT depends on the application you are writing.

If you use the standard palettes, you need not be concerned with the LUT. The DEB device driver automatically programs the LUT to correspond to the way you set up the palettes. If you program a custom LUT, you greatly increase the color combinations and blinking effects available to you. The overlay modes let you use the screen to display two images at once, independently. For example, you can display a high resolution color graphics image with its own foreground and background. Then, on "top" of that image, you can display a box of text and scroll the text without affecting the graphics image.

The overlay modes use the DEB to control one image and use the standard controller board to control the other image. You can select from many combinations of graphics, text, color, and high or super resolution in designing the two images. The overlay modes offer 5 palettes. Each of the first 4 palettes has 8 positions. These four palettes have default colors that you can change to suit your needs. You can choose 8 color combinations from any of the 16 standard colors, or blink between 2 of the standard colors. The dithering combinations of the 16-color graphics modes are not available. You can also use the last palette to custom program the LUT. •

2 Programming Tips

- Presence of Hardware/Software
- Hardware/Software Compatibility
- Setup

Whenever you plan an application, it is important to use the DEB device driver to test for the presence of both the DEB and the associated driver. Test for the presence of the hardware by checking for DEB video memory. This is accomplished by writing and reading back data patterns into memory, in the range A000H:0H to B800H:0H. Test for the software device driver by issuing a function call to open the device called "DEBDRIVE," then immediately issuing a call to close "DEBDRIVE." If the open fails (carry set on return from Interrupt 21H) then the driver is not present. No functions are implemented in the driver, which is used only to detect the presence of the software.

Hardware/Software Compatibility

The driver software has been designed to fit into the structure of MS-DOS programs. The DEB hardware uses the same range of addresses as the standard video ports on any compatible machine. If your application uses a light pen, consult the DEB supplement in the AT&T Personal Computer Technical Reference Guide.

The DEB driver makes minor modifications to the ROM BIOS video interrupt. Mode setting and color selection offer additional functionality. Be careful when you use the following functions.

- SET MODE uses an additional register BL
- SCROLLING uses an additional register BH
- STATUS returns an additional register pair ES:DI. No application should count on ES:DI not changing.

Install the DEB driver just as you would install any device driver. Be sure the CONFIG.SYS file is in the root directory. Put the line DEVICE = DEDRIVER.DEV in CONFIG.SYS. This line puts the DEB driver in the device driver chain. The driver makes patches in INT 10H and INT 9H to add the new functionality. The driver has two features:

- the INIT function, which deallocates itself after it runs
- chaining, which allows you to test for the driver's presence by issuing an open function call

3 How to Program the DEB

- Overview
- Mode Setting
- Setting Colors and Effects
- Displaying Graphics Images

There are three steps for video programming that apply whether or not you are using the DEB capability:

- 1 Set the hardware's mode. You also must set the active page if you are in an overlay mode and want to select the DEB screen.
- $\label{eq:select} 2 \quad \text{Select the color combinations and effects you want} \\ \text{to use.}$
- ${f 3}$ Construct the graphics images you want to display.

This chapter describes each of these steps in detail. This chapter does **not** describe how to program the LUT directly (see **Chapter 5**, "**Programming the LUT**").

	The DEB is controlled by invoking one of the DEB video modes through the Set Mode function (INT 10H, function 0H). The Set Mode function estab- lishes the mode for both the DEB and the VDC. These modes fall into four categories: 16-color graphics, overlay, transparent, and disabled.
16-Color Graphics Modes	There are two DEB modes that provide 16-color graphics: high resolution and super resolution. Both these modes let you use 5 palettes and dis- play up to 16 color combinations simultaneously.
Overlay Modes	When overlaying the VDC on the DEB output, you specify one of the modes for the VDC and one mode for the DEB. The VDC modes are a subset of the modes for non-DEB graphics: 80×25 text mode, high and super resolution modes. The DEB modes are both graphics modes: high and super resolution.
	If you are using one of the four standard palettes, the VDC's output takes precedence over the output of the DEB, so that if each board writes a pixel to the same screen location, the pixel sent by the VDC is displayed. This precedence is programmed into the LUT. If you want to have the DEB take precedence over the VDC, you must change the values in the LUT. (For more information, see Chapter 5, "Programming the LUT.")

How to Program the DEB

Transparent Mode	The non-DEB modes, modes 0-40H and mode 48H, work exactly as they work without the DEB device driver installed.
Disabled Mode	In the disabled mode, you can cause the output of the VDC, the DEB, or both to be blacked out. This allows you to draw a graphics image or to fill a screen with text and not have them displayed while you are building them. You can then have the image "pop up" by taking VDC or DEB out of the disabled mode. You can also achieve this result by using the programmable palettes and the LUT.

Setting Colors and Effects

Colors and effects are controlled by the Set Color Palette command, (INT 10H function 0BH). Use this function to set color values in one of the four palettes, to switch between palettes, or to reset palettes to their default values. You also use Set Color Palette to program the LUT directly. There are two methods for displaying graphics images using the DEB: writing dots at screen locations or directly programming the VDC and DEB memory.

To write dots (pixels) to the screen, use the Write Dot function (INT 10H, function 0CH). Write Dot requires that you specify the display page, the row and column where you want the dot to appear, and the color or pattern for the dot.

If you want to program the VDC and DEB graphics memory directly , you need to learn the details of how the LUT is structured and how LUT addresses are formed (see the section on "Programming the Bit Planes" in Chapter 5).

- Introduction
- Functions

The following section describes the DEB device driver software functions. This interface is an extension of the INT 10H software function to the PC6300 ROM BIOS that controls the VDC. The ROM BIOS screen driver has 16 functions:

- 0H set the display mode
- 2H set the cursor position
- 3H read the cursor position
- 5H select the active display page
- 6H scroll the active page up
- 7H scroll the active page down
- 8H read character/attribute at the current cursor position
- 9H write character/attribute at cursor position
- AH write only the character at current cursor position
- BH change the color palette
- CH write a point on the screen

- DH read a point on the screen
- EH write in teletype style to the active page
- FH return information about the active video state

Not all these functions are applicable to the DEB. The filter receives the Interrupt 10H function call, filters the functions that are applicable to the DEB and performs them. The functions that are not applicable to the DEB are passed on to the ROM BIOS INT 10H routine or to a previously installed filter or driver routine. The following section describes the functions which are processed by the DEB Interrupt 10H filter.

Set Mode	The function establishes the mode for both the DEB and the VDC. If you select a non-DEB related mode, control is passed to the ROM resident Set Mode function. Set Mode initializes palette 0 as the active palette.
Input	 (AH) = 0H function number for Set Mode (AL) = new mode (BL) = optional overlay mode
	Setting AL bit $7 = 0$ puts you in either the DEB transparent mode or 16-color graphics mode:
	$ (AL) = 0H 40 \times 25 \text{ monochrome, text} \\ (AL) = 1H 40 \times 25 \text{ color, text} \\ (AL) = 2H 80 \times 25 \text{ monochrome, text} \\ (AL) = 2H 80 \times 25 \text{ color, text} \\ (AL) = 3H 80 \times 25 \text{ color, text} \\ (AL) = 4H 320 \times 200 \text{ color} \\ (AL) = 5H 320 \times 200 \text{ monochrome} \\ (AL) = 6H 640 \times 200 \text{ color} \\ (AL) = 40H 640 \times 400 \text{ with } 2\text{-position programmable palette, defaulting to black and white} \\ (AL) = 41H 640 \times 200 \text{ 16-color graphics with four palettes} \\ (AL) = 42H 640 \times 400 \text{ 16-color graphics with four palettes} \\ (AL) = 44H Disable mode (disables both DEB \\ $

	Setting AL bit $7 = 1$ puts you in overlay mode. The following values are only used in overlay mode. AL contains the setting for the VDC; BL contains the mode setting for the DEB. In overlay modes, the active page defaults to zero.		
VDC Settings			
DEB settings		0 imes 200 graphics with four	
		position palettes. $400 \text{ graphics with four}$	
		340×400 graphics with four B-position palettes.	
	(BL) = 44H I	Disable mode. Disables only the DEB.	
Output	Contents of all	registers are preserved.	
Example	MOV AL,41H	; Select Set Mode ; Select 16 color graphics ; Change the mode	

Set Cursor Position	This function sets the cursor position for either the DEB, the VDC, or both.
Input	 (AH) = 2H Function number for Set Cursor Position (DH,DL) = row, column of new position (BH) = page number Valid page numbers for DEB modes are 0 for the VDC and 80H for the DEB in overlay mode. Row values are 0 thru 23, column values are 0 thru 79, in DEB modes.
Output	Contents of all registers are preserved.
Example	MOV AH,2 ; SCP function MOV DH,ROW MOV DL,COL MOV BH,PAGE INT 10H ; Moves cursor to position defined in above variables.

Read Cursor Position	This function returns the position of the cursor for the DEB, VDC, or both.		
Input	 (AH) = 3H Function number for Read Cursor Position (BH) = page number Valid page numbers for DEB modes are 0 for VDC and 80H for the DEB in over- lay mode. Row values are 0 thru 23, col- umn values are 0 thru 79, in DEB modes. 		
Output	(DH,DL) = row, column of current position. Contents of all other registers are preserved.		
Example	MOV AH,3 MOV BH,PAGE INT 10H MOV ROW,DH MOV COL,DL		

Select Active Display	This command allows selection of the DEB display in overlay mode.		
Input	 (AH) = 5H Function number for Select Action Display (AL) = active page Values for the active page in DEB modes are, 0 for the VDC and 80H for the DEB. 		
Output	Contents of all registers are preserved.		
Example	MOV AH,5 MOV AL,PAGE INT 10H		

Scroll Active Page Up	This function defines a pattern that is to be dis- played on the blank lines as the screen scrolls. The pattern consists of ones and zeros. Zeros are inter- preted as the background color (palette position zero). Ones are interpreted as the foreground color, which is defined in BL. Care should be taken when scrolling in DEB modes, to insure that all applica- tions set the additional argument in BH correctly.
Input	 (AH) = 6H function number for Scroll Active Page Up (AL) = number of lines to scroll (CH,CL) = row, column of upper left corner to scroll (DH,DL) = row, column of lower right corner to scroll (BH) = pattern to be used on blank lines (BL) = foreground color The range of lines to be scrolled is 0 thru 23 (where 0 specifies clear screen). Row values are 0 thru 23, column values are 0 thru 79, in DEB modes. Valid foreground colors are specified by palette position 0-FH for 16-color graphics, and 0-7H for 8-color graphics.
Output	Contents of all registers are preserved.
Example	MOV AH,6 ;Scroll Active Page Up MOV AL,LINES MOV CH,UPROW MOV CL,UPCOL MOV DH,LOWROW MOV DL,LOWCOL MOV BH,0 MOV BL,FGCOLOR INT 10H

Scroll Active Page Down	This function permits you to define a pattern that is to be displayed on the blank lines as the screen scrolls downward. The pattern consists of ones and zeros. Zeros are interpreted as the background color (palette position zero). Ones are interpreted as the foreground color, which is defined in BL. Care should be taken when scrolling in DEB modes, to insure that all applications set the addi- tional argument in BH correctly.	
Input	 (AH) = 7H function number for Scroll Active Page Down (AL) = number of lines to scroll (CH,CL) = row, column of upper left corner to scroll (DH,DL) = row, column of lower right corner to scroll (BH) = pattern to be used on blank lines (BL) = foreground color The range of lines to be scrolled is 0 thru 23 (where 0 specifies clear screen). Row values are 0 thru 23, column values are 0 thru 79, in DEB modes. Valid foreground colors are specified by palette position 0-FH for 16-color graphics, and 0-7H for 8-color graphics. 	
Output	Contents of all registers are preserved.	
Example	MOV AH,7 ; Scroll Active Page Down MOV AL,LINES MOV CH,UPROW MOV CL,UPCOL MOV DH,LOWROW MOV DL,LOWCOL MOV BH,0 MOV BL,FGCOLOR INT 10H	

Read Character and Attribute at Current Cursor Position	This function returns the value of the character at the current cursor position. The value of the char- acter's foreground color is returned in AH.		
Input	 (AH) = 8 Function number for Read Character and Attribute at Current Cursor Position. (BH) = Valid page numbers for DEB modes are 0 for the VDC and 80H for the DEB in overlay mode. 		
Output	 (AL) = ASCII character code (AH) = foreground palette position or VDC attribute Contents of all other registers are preserved. 		
Example	MOV AH,8 ;Read CHR function MOV BH,PAGE INT 10H MOV CHAR,AL ;Save CHAR/COLOR MOV CURCOLOR,AH		

Write Character and Attribute at Current Cursor Position	This function displays the character whose ASCII code is in register AL. The character is displayed according to the color values in BL.		
Input	 (AH) = 9H Write Character function (AL) = ASCII character code (BL) = foreground color (BH) = page (CX) = count of characters to write If bit 7 of BL = 1, the color value is XOR'd with the current dots in that location. Valid page numbers for DEB modes are 0 for the VDC and 80H for the DEB in overlay mode. Valid foreground colors are specified by palette position 0-FH for 16-color graphics, and 0-7H for 8-color graphics.		
Output	Contents of all registers are preserved.		
Example	MOV AH,9 MOV AL,CHAR MOV BL,CURCOLOR MOV BH,PAGE MOV CX,1 INT 10H		

Write Character Only at Current Cursor Position In DEB modes, this function is the same as "Write Character and Attribute."

Set Color Palette

This function is used to set color values in one of the four palettes, to switch between palettes, or to reset palettes to their default values.

In the overlay modes, the Set Color Palette function works on the active page. If the active page is set to display to the VDC board, this function works the same as the standard ROM BIOS INT 10H (function 0BH).

If you specify a palette position greater than the value allowed for the mode in which you are working, the value you specify will be put in that palette's highest position. For example, if you attempted to set palette position 13 to red when working in overlay mode, which has 8-position palettes, the 8th palette position would be set to red.

Note:

The following discussion covers the use of the simple palette programming functions. You can also use "Set Color Palette" to program the LUT. (For more information, see **Chapter 5**, "**Programming the LUT**").

Input	(AH) (AL) (BH) (BL) For sir followi	 positional pointer color value nple palette programming functions, use the 	
	(AL) (BH)	= 0 = palette color ID BH = FFH switches to the palette specified in BL, without changing to the default palettes unless there is a change in palette type (e.g., change from a 16- position palette to an 8- position palette).	
		BH = 80H switches to the palette specified in BL and resets the palette to its default.	
		BH = 0.16 sets this palette position to the color or attribute in BL.	
	(BL)	= actual color value or code for blinking and dithering	

Input	The special settings for using a customized LUT in Set Color Palette are as follows: (AL) = non-zero (a zero here selects a standard palette)	
	AL bit $0 = 1$	means use ES:SI to program the palette and registers BH and BL to indicate an offset and length into the LUT. ES:SI points to the LUT table (in the above example, LUT-STRING).
		In this case, $BH = offset into LUT$ and $BL = length of portion of LUT$ to be changed. If you are loading an entire new table, set BH and BL to 0.
	AL bit $1 = 1$	means use BH and BL to program the LUT one location at a time.
		In this case, $BH = position$ in LUT and $BL =$ the value to put in that position.
	AL bit $2 = 1$	means use the short LUT address- ing mode. (Only uses the first 16 LUT entries).

The DEB driver lets you automatically load your customized LUT and use it in place of one of the standard palettes.

The steps for loading and using the customized LUT are:

- $1 \quad {\rm Define \ the \ table \ with \ DB \ (Define \ Byte)} \\ {\rm statements.}$
- **3** Use the Read Dot and Write Dot commands to access the LUT (see Chapter 4, "Interrupt 10H Functions").

The code for defining the table would be similar to this:

LUT-STRING	
------------	--

DB	4 ! Signifies active palette 4
DB	1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15,
DB	1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15,
DB	1,2,3,4,5,6,7,8,9,10,11,12,13,14,15,
DB	1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15,
•	
•	
•	
DB	1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15,

> To load a new table of values into the LUT, where the table in your program is named LUT-STRING, you can use these statements:

PUSH DS! save the data segment addressPOP ESMOVS1,LUT-STRINGMOVAL, 1MOVAH, 11XORBH,BX! Sets BH = BL = 0INT

The defaults for each of the four palettes are:

Default Palettes	Palette Number 0 Position Color	
	0	0 = black
	1	2 = green
	2	4 = red
	3	6=brown
	4	1 = blue
	5	3 = cyan
	6	5 = magenta
	7	7 = white
	8	8 = gray
	9	9 = light blue
	10	10 = light green
	11	11 = light cyan
	12	12 = light red
	13	13 = light magenta
	14	14 = yellow
	15	15 = high-intensity white

Palette Number 1

Position Color

0	0 = black
1	3 = cyan
2	5 = magenta
3	7 = white
4	1 = blue
5	2 = green
6	4 = red
7	6=brown
8	$8 = \operatorname{gray}$
9	9 = light blue
10	10 = light green
11	11 = light cyan
12	12 = light red
13	13 = light magenta
14	14 = yellow
15	15 = high-intensity white

Palettes 2 and 3 are the same, and they contain the standard colors in numerical order.

Palette Number 2 and Palette Number 3 Position Color

	00101
0	0 = black
1	1 = blue
2	2 = green
3	3 = cyan
4	4 = red
5	5 = magenta
6	6 = brown
7	7 = white
8	$8 = \operatorname{gray}$
9	9 = light blue
10	$10 {=} { m lightgreen}$
11	11 = light cyan
12	12 = light red
13	13 = light magenta
14	14 = yellow
15	15 = high-intensity white

DEB PALETTES 0-3

Color combinations 136-255 have been pre-assigned to allow you easy access to dithering effects while using the standard palettes. The following table describes the available combinations.

ght magents tight green ر ight cyan iight blue magenta ght red rown ellow white olue green zyan red olack gray A 1 black blue 136 137 138 green 139 140 141 cyan 142 143 144 145 red 146 147 148 149 150 magenta brown 151 152 153 154 155 156 157 158 159 160 161 162 163 white 164 165 166 167 168 169 170 171 gray light blue 172 173 174 175 176 177 178 179 180 light green 181 182 183 184 185 186 187 188 189 190 191 192 193 194 195 196 197 198 199 200 201 light cyan 202 203 204 205 206 207 208 209 210 211 212 213 light red light magenta 214 215 216 217 218 219 220 221 222 223 224 225 226 vellow 227 228 229 230 231 232 233 234 235 236 237 238 239 240 high-intensity 241 242 243 244 245 246 247 248 249 250 251 252 253 254 255 white

NOTE: To select a value that combines colors A and B to create a new color, find the number at the intersection of row A and column B.

white

BLINKING COLOR EFFECTS FOR DEB PALETTES 0-3

Color combinations 16-135 have been pre-assigned to allow you easy access to blinking effects while using the standard palettes. The following table describes the available combinations.

	В 🗕	blue	green	cyan	red	magenta	brown	white	gray	light blue	light green	light evan	light red	light magenta	yellow	high-intensity
A ↓	black	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30
v	blue		31	32	33	34	35	36	37	38	39	40	41	42	43	44
	green			45	46	47	48	49	50	51	52	53	54	55	56	57
	cyan				58	59	60	61	62	63	64	65	66	67	68	69
	\mathbf{red}					70	71	72	73	74	75	76	77	78	79	80
m	agenta						81	82	83	84	85	86	87	88	89	90
	brown							91	92	93	94	95	96	97	98	99
	white								100	101	102	103	104	105	106	107
	gray									108	109	110	111	112	113	114
lig	ht blue										115	116	117	118	119	120
ligh	t green											121	122	123	124	125
lig	ht cyan												126	127	128	129
li	ght red													130	131	132
light m	agenta														133	134
	yellow															135

NOTE: To select a value that will cause blinking between colors A and B, find the number at the intersection of row A and column B.

Write Dot	The Write function writes a pixel to the location on the screen that you specify. If the screen is in the DEB mode, Write Dot may also write a pattern.		
Input	 (AH) = 0CH, Function number for Write Dot (AL) = Palette position to be written. (BH) = display page designator (bit 7 = 1 selects the DEB) (CX) = column number (DX) = row number 		
Output	Contents of all registers are preserved.		
Example	MOV AH,0CH MOV AL,PALPOS MOV BH,PAGE MOV CX,COL MOV DX,ROW INT ;Write the Dot		

-

Read Dot	This function reads a dot from the screen. If the screen is in the DEB mode this function returns the value in the LUT that corresponds to this dot. (For more information, see Chapter 5 , "Pro- gramming the LUT.")		
Input	 (AH) = 0DH Function number for Read Dot (BH) = display page designator (bit 7 = 1 selects the DEB) (CX) = column number (DX) = row number 		
Output	(AH) = VDC value or DEB palette position Contents of all other registers are preserved.		
Example	MOV AH,0DH MOV BH,PAGE MOV CX,COL MOV DX,ROW INT MOV DOTCOL,AH ;Save the Dot		

Input	 (AH) = 0EH, Function number for Write Teletype (AL) = character to write (BL) = foreground color (in graphics modes) If bit 7 = 1, color is XOR'd to current contents.
Output	Contents of all registers are preserved.
Example	MOV AH,0EH MOV AL,CHAR MOV BL,FGCOL INT 10H

Read Current Video State	indicates	ction returns the current video state. It whether the DEB or VDC is active in the node and returns the number of the active
Input	(AH)	= 0FH Function number for Read Cur- rent Video State
Output	(BH) (AL) (ES:DI)	 = display page designator = mode currently set = pointer to a copy of the current LUT
Example	MOV AH,(INT 10H	

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5 Programming the LUT

- Overview
- 16-Color Graphics LUT Programming
- Overlay Modes LUT Programming
- Programming the Bit Planes

This chapter describes programming the DEB Look-Up Table (LUT). By programming the LUT yourself, you can create color patterns that are not available when you use standard palettes. You need not read this chapter if you do not want to use this extended functionality.

The hardware uses the LUT to translate the contents of video memory patterns into graphics effects. In the standard palettes, INT 10H filter programs the LUT for you and thereby provides the preassigned color combinations and effects as described in previous chapters.

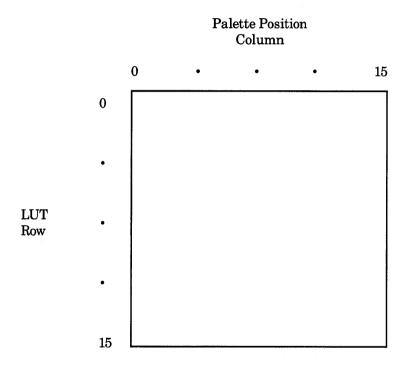
To program the LUT directly, you select Palette 4 in Set Color Palette function. Palette 4, also called the "LUT palette," has a minimum of 256 positions. Each palette position contains a value between 0 and 15. These values map into the LUT locations on the DEB. The 256 locations on the DEB collectively determine the color and special effects displayed when you specify a particular palette position. The color and special effect for each pixel on the screen are determined by:

- the palette position you specify
- the values in the LUT
- the active mode

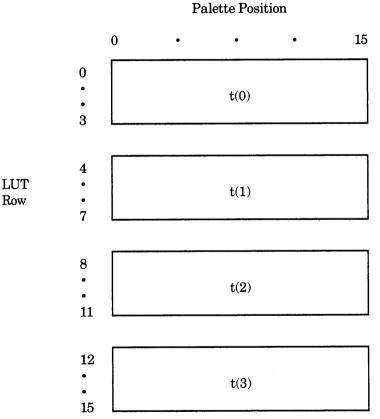
There are some differences in the way the LUT is structured for 16-color graphics modes and overlay modes. This chapter describes LUT operation for 16-color graphics modes and overlay modes separately.

16-Color Graphics Lut Programming

In these modes, the LUT can be viewed as a twodimensional array (16 \times 16). Each location contains one of the standard 16 colors.



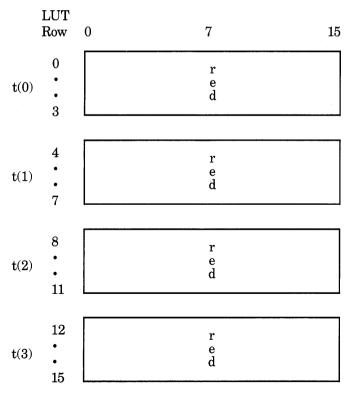
The locations in the LUT are numbered consecutively from left to right and top to bottom. Thus, location 17 corresponds to Row 1, palette position 1. In the 16-color graphics mode, the LUT is divided into four "time states." At any one time, only one quarter of the LUT determines the display on the screen.



The hardware cycles through the LUT every second, so each quarter of the LUT is active for $\frac{1}{4}$ of each second. The cycling mechanism produces blinking. The following examples show the details of how you can produce several different blinking effects by setting different values in the LUT.

LUT

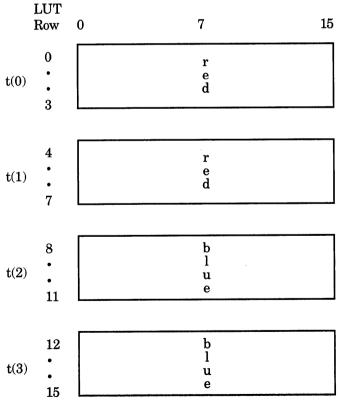
In this example, the Write Dot or Write Character functions specify palette position 7 and the LUT is set up as shown. Pixels are displayed as a solid red color. In the first $\frac{1}{4}$ second, the DEB displays the color in the first quarter of the LUT, which in this case is red. In the second, third, and fourth $\frac{1}{4}$ seconds, the DEB displays the color in the second, third, and fourth quarters of the LUT, respectively. In this example, the DEB keeps finding the color value for red, so what you see on the screen is a solid (non-blinking) red color.



Palette Position

Non-Blinking Color

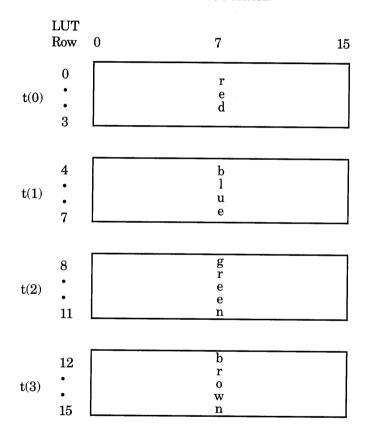
In this example, any item displayed on the screen with palette position 7 blinks between red and blue. For the first two $\frac{1}{4}$ seconds, the DEB picks up the color value for red from the first and second quarters of the LUT. For the second two $\frac{1}{4}$ seconds, the DEB obtains the color value of blue from the LUT. The net effect is a slow blink between red and blue.



Palette Position

Slow Blink

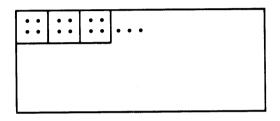
In this example, any item displayed using palette position 7 blinks rapidly between red, blue, green, and brown.



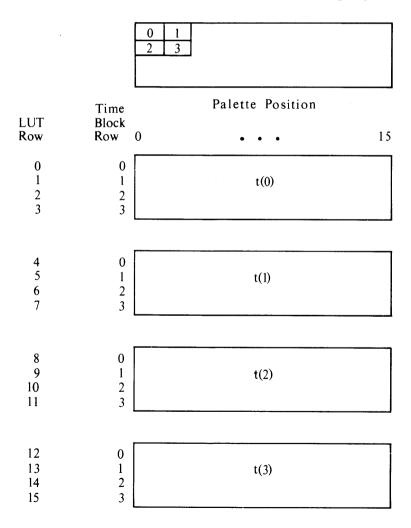
Palette Position

4-Color Fast Blink

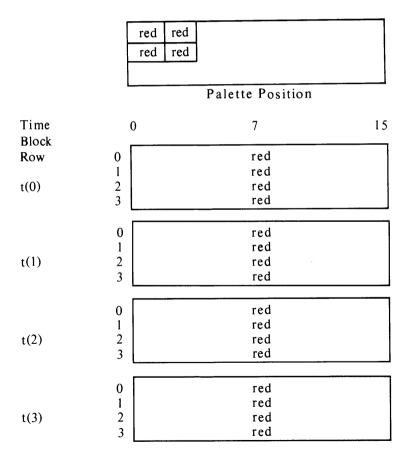
For dithering colors, the DEB uses a scheme similar to the blinking scheme. Dithering is accomplished by manipulating groups of 4 adjacent pixels. The screen is divided into blocks of 4 pixels.



Each of the 4 time states is divided into four dither states that determine the dithering effect. The rows of the time state blocks correspond to the 4pixel blocks on the screen in the following way:

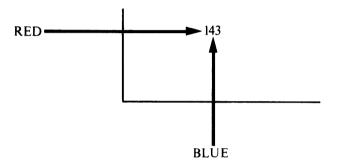


The pixels in the pixel blocks are so close together that our eyes cannot perceive them as separate. If each of the pixels in a pixel block is a different color, our eyes perceive the pixel block as one color — a combination of the color of the individual pixels. If the adjacent pixels are the same color, our eyes see just that one color.



"Solid" Dither showing correspondence between pixel positions in a pixel block and time state rows

Remember the table of "pre-assigned" dithered colors. To combine colors, you check the table for the color number for a particular dither effect. For example, you would choose this number to produce a dither between red and blue.

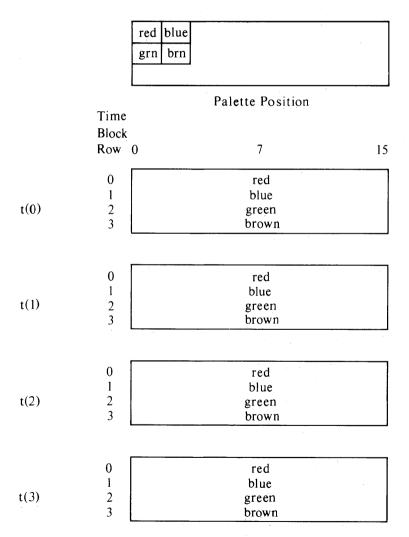


If you want to program the LUT directly to dither red and blue together, the LUT would look like this:

	blue red blue red	
	blue red blue red	
	Time Palette Position	
	Block	1.5
	Row 0 7	15
	0 blue	
t(0)	1 red 2 blue	1
ι(0)	2 blue 3 red	
	L	
	0 blue	
t(1)	1 red 2 blue 3 red	
	0 blue	
	1 red	
t(2)	1 red 2 blue 3 red	
	0 blue	
(•)	1 red	
t(3)	0 blue 1 red 2 blue 3 red	
	J ICU	

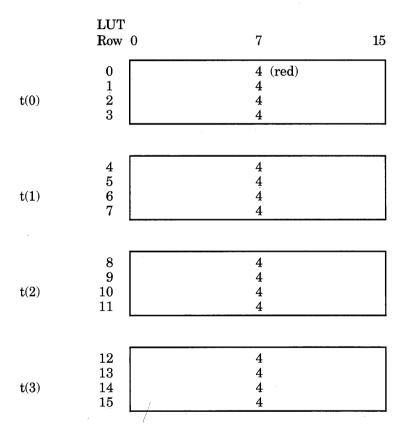
2-Color Dither

You can set up the LUT to dither two, three, or four colors together.



4-Color Dither

The following examples show the actual LUT values for each of the previous cases of blinking and dithering.



Palette Position

Palette Position 7 programmed for Non-Blinking Red

	LUT Row 0	7	15
t(0)	0 1 2 3	4 (red) 4 4 4	
t(1)	4 5 6 7	4 4 4 4	
t(2)	8 9 10 11	1 (blue) 1 1 1	
t(3)	12 13 14 15	1 1 1 1	

Palette Position

Palette Position 7 programmed to blink slowly between red and blue.

	LUT Row 0	7 15
t(0)	$ \begin{array}{c} 0\\ 1\\ 2\\ 3 \end{array} $	4 (red) 4 4 4
t(1)	4 5 6 7	1 (blue) 1 1 1
t(2)	8 9 10 11	2 (green) 2 2 2
t(3)	12 13 14 15	6 (brown) 6 6 6 6

Palette Position

4-Color Fast Blink

		Palette Position	
	LUT Row 0	7	15
t(0)	0 1 2 3	4 (red) 4 4 4	
t(1)	4 5 6 7	4 4 4 4	
t(2)	8 9 10 11	4 4 4 4	
t(3)	$ \begin{array}{c c} 12 \\ 13 \\ 14 \\ 15 \end{array} $	4 4 4 4	

Solid Red Dither

	LUT	Palette Position	
	Row 0	7	15
t(0)	$\begin{smallmatrix} 0\\1\\2\\3\end{smallmatrix}$	1 (blue) 4 (red) 1 (blue) 4 (red)	
t(1)	4 5 6 7	1 4 1 4	
t(2)	8 9 10 11	1 4 1 4	
t(3)	12 13 14 15	1 4 1 4	

2-Color Dither: Red and Blue

	LUT Row	0 7	15
t(0)	$egin{array}{c} 0 \ 1 \ 2 \ 3 \end{array}$	4 (red) 2 (green) 1 (blue) 6 (brown)	
t(1)	4 5 6 7	4 2 1 6	
t(2)	8 9 10 11	4 2 1 6	
t(3)	$12 \\ 13 \\ 14 \\ 15$	4 2 1 6	

Palette Position

4-Color Dither Between Red, Green, Blue, and Brown

The following is an example that combines blinking and dithering:

LUT Row 0 7 150 1 (blue) 1 4 (red) $\frac{1}{2}$ **t**(0) 1 4 1 4 5 6 7 4 t(1) 1 4 8 $\mathbf{2}$ (green) 9 6 (brown) t(2) 10 $\mathbf{2}$ 11 6 12 $\mathbf{2}$ $\overline{6}$ 13 $\mathbf{2}$ t(3) 14 6 15

Palette Position

The following table of values can be used to program the LUT for normal 16-color graphics.

Palette Position

	LUT Row	$0\ 1\ 2\ 3\ 4\ 5\ 6\ 7\ 8\ 9\ 10\ 11\ 12\ 13\ 14\ 15$
t(o)	0 1 2 3	$\begin{matrix} 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, \\ 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, \\ 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, \\ 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, \\ 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, \end{matrix}$
t(1)	4 5 6 7	$\begin{matrix} 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, \\ 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, \\ 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, \\ 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, \end{matrix}$
t(2)	8 9 10 11	$\begin{matrix} 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, \\ 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, \\ 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, \\ 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, \end{matrix}$
t(3)	$12 \\ 13 \\ 14 \\ 15$	$\begin{matrix} 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, \\ 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, \\ 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, \\ 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, \end{matrix}$

Non-Blinking Standard Colors

Note that palette position 7 in the first two time states has been programmed to show white and in the second two time states to show red.

Palette Position

	LUT Row	0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
t(o)	0 1 2 3	$\begin{matrix} 0, 1, 2, 3, 4, 5, 6, \textbf{7}, 8, 9, 10, 11, 12, 13, 14, 15, \\ 0, 1, 2, 3, 4, 5, 6, \textbf{7}, 8, 9, 10, 11, 12, 13, 14, 15, \\ 0, 1, 2, 3, 4, 5, 6, \textbf{7}, 8, 9, 10, 11, 12, 13, 14, 15, \\ 0, 1, 2, 3, 4, 5, 6, \textbf{7}, 8, 9, 10, 11, 12, 13, 14, 15, \\ 0, 1, 2, 3, 4, 5, 6, \textbf{7}, 8, 9, 10, 11, 12, 13, 14, 15, \end{matrix}$
t(1)	4 5 6 7	0, 1, 2, 3, 4, 5, 6, 7 , 8, 9, 10, 11, 12, 13, 14, 15, 0, 1, 2, 3, 4, 5, 6, 7 , 8, 9, 10, 11, 12, 13, 14, 15, 0, 1, 2, 3, 4, 5, 6, 7 , 8, 9, 10, 11, 12, 13, 14, 15, 0, 1, 2, 3, 4, 5, 6, 7 , 8, 9, 10, 11, 12, 13, 14, 15,
t(2)	8 9 10 11	$\begin{matrix} 0, 1, 2, 3, 4, 5, 6, 4, 8, 9, 10, 11, 12, 13, 14, 15, \\ 0, 1, 2, 3, 4, 5, 6, 4, 8, 9, 10, 11, 12, 13, 14, 15, \\ 0, 1, 2, 3, 4, 5, 6, 4, 8, 9, 10, 11, 12, 13, 14, 15, \\ 0, 1, 2, 3, 4, 5, 6, 4, 8, 9, 10, 11, 12, 13, 14, 15, \\ 0, 1, 2, 3, 4, 5, 6, 4, 8, 9, 10, 11, 12, 13, 14, 15, \end{matrix}$
t(3)	$12 \\ 13 \\ 14 \\ 15$	0, 1, 2, 3, 4, 5, 6, 4, 8, 9, 10, 11, 12, 13, 14, 15, 0, 1, 2, 3, 4, 5, 6, 4, 8, 9, 10, 11, 12, 13, 14, 15, 0, 1, 2, 3, 4, 5, 6, 4, 8, 9, 10, 11, 12, 13, 14, 15, 0, 1, 2, 3, 4, 5, 6, 4, 8, 9, 10, 11, 12, 13, 14, 15, 0, 1, 2, 3, 4, 5, 6, 4, 8, 9, 10, 11, 12, 13, 14, 15,

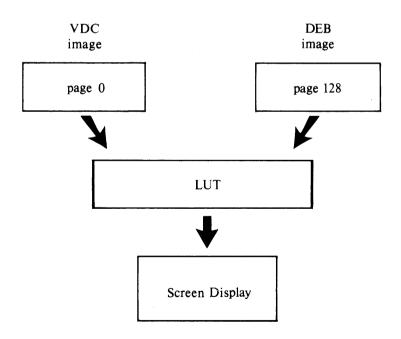
LUT for Blinking Between White and Red in Palette Position 7

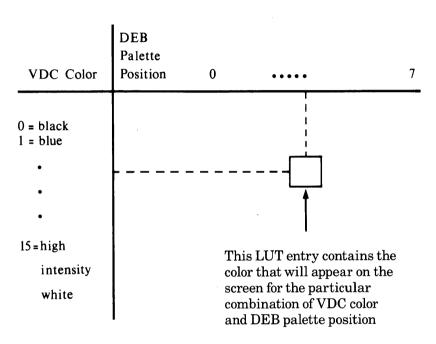
Overlay Modes LUT Programming

Overlay Modes LUT Programming

When the LUT is used in the overlay modes it can be viewed as a two-dimensional array with 8 columns and 32 rows. The column values are DEB palette positions. The row values are VDC color values.

In overlay modes, there are 2 separately controlled images: the VDC image and the DEB image. The 2 images are combined on the display screen. Each pixel on the screen has 2 values associated with it: the VDC color and the DEB palette position. The LUT is used to resolve contention between the 2 values associated with each pixel.



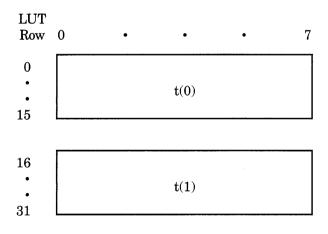


The LUT for overlay modes looks like this:

As in the 16-color graphics modes, the locations in the LUT are numbered consecutively from left to right and top to bottom. For example, location 17 corresponds to Row 2, Palette Position 0. In the overlay modes, as in the 16-color graphics mode, the LUT is divided into time states that control blinking effects. However, in the overlay modes, the LUT is only divided into two time states. Half of the LUT determines what is being displayed at any time. The top half is used for the first $\frac{1}{2}$ of each second and the bottom half is used for the second $\frac{1}{2}$ of each second.

Using the overlay modes, you create blinking by making the values in the top half of the table different from the corresponding values in the bottom half of the table.





The following example shows the LUT values for standard Palette 2 of an overlay mode. The LUT is programmed so that the DEB image is displayed only if the VDC color is 0 (black). If the VDC requests any other color, then that color is displayed no matter what the DEB requests. This has the effect of overlaying the VDC image "on top" of the DEB image.

DEB Palette Position

VDC

Color

Values	0	1	2	3	4	5	6	7
0	0,	1,	2,	3,	4,	5,	6,	7,
1	1,	1,	1,	1,	1,	1,	1,	1,
2	2,	2,	2,	2,	2,	2,	2,	2,
3	3,	3,	3,	3,	3,	3,	3,	3,
4	4,	4,	4,	4,	4,	4,	4,	4,
5	5,	5,	5,	5,	5,	5,	5,	5,
6	6,	6,	6,	6,	6,	6,	6,	6,
7	7,	7,	7,	7,	7,	7,	7,	7,
8	8,	8,	8,	8,	8,	8,	8,	8,
9	9,	9,	9,	9,	9,	9,	9,	9,
10	10,	10,	10,	10,	10,	10,	10,	10,
11	11,	11,	11,	11,	11,	11,	11,	11,
12	12,	12,	12,	12,	12,	12,	12,	12,
13	13,	13,	13,	13,	13,	13,	13,	13,
14	14,	14,	14,	14,	14,	14,	14,	14,
15	15,	15,	15,	15,	15,	15,	15,	15,

t(0)

	VDC	DE	BF	Pale	tte]	Posi	tior	ı	
	Color								
	Values	0	1	2	3	4	5	6	7
		~		-			~	2	-
	0	0,	1,	2,	3,		5,	6,	7,
	1	1,	1,	1,	1,	1,	1,	1,	1,
	2	2,	2,	2,	2,	2,	2,	2,	2,
	3	3,	3,	3,	3,	3,	3,	3,	3,
t(1)	4	4,	4,	4,	4,	4,	4,	4,	4,
	5	5,	5,	5,	5,	5,	5,	5,	5,
	6	6,	6,	6,	6,	6,	6,	6,	6,
	7	7,	7,	7,	7,	7,	7,	7,	7,
	8	8,	8,	8,	8,	8,	8,	8,	8,
	9	9,	9,	9,	9,	9,	9,	9,	9,
	10	10,	10,	10,	10,	10,	10,	10,	10,
	11	11,	11,	11,	11,	11,	11,	11,	11,
	12	12,	12,	12,	12,	12,	12,	12,	12,
	13	13,	13,	13,	13,	13,	13,	13,	13,
	14	14,	14,	14,	14,	14,	14,	14,	14,
	15	15,	15,	15,	15,	15,	15,	15,	15,

In this example, the standard Palette 2 is modified so that position 2 is a blinking between blue (color 1) and red (color 4). .

.

		DE	CB F	Pale	tte]	Posi	tion	ı	
	VDC								
	Color								
	Values	0	1	2	3	4	5	6	7
	0	0,	1,	1,	3,	4,	5,	6,	7,
	1	1,	1,	1,	1,	1,	1,	1,	1,
	2	2,	2,	2,	2,	2,	2,	2,	2,
	3	3,	3,	3,	3,	3,	3,	3,	3,
t(0)	4	4,	4,	4,	4,	4,	4,	4,	4,
	5	5,	5,	5,	5,	5,	5,	5,	5,
	6	6,	6,	6,	6,	6,	6,	6,	6,
	7	7,	7,	7,	7,	7,	7,	7,	7,
	8	8,	8,	8,	8,	8,	8,	8,	8,
	9	9,	9,	9,	9,	9,	9,	9,	9,
	10	10,	10,	10,	10,	10,	10,	10,	10,
	11	11,	11,	11,	11,	11,	11,	11,	11,
	12	12,	12,	12,	12,	12,	12,	12,	12,
	13		13,						
	14	14,	14,	14,	14,	14,	14,	14,	14,
	15		15,						
	10	10,	10,	10,	10,	10,	10,	10,	10,

		DE	CB F	Pale	tte I	Posi	itio	n	
	VDC								
	Color								
	Values	0	1	2	3	4	5	6	7
						ł			
	0	0,	1,	4,	3,	4,	5,	6,	7,
	1	1,	1,	1,	1,	1,	1,	1,	1,
	2	2,	2,	2,	2,	2,	2,	2,	2,
	3	3,	3,	3,	3,	3,	3,	3,	3,
1)	4	4,	4,	4,	4,	4,	4,	4,	4,
	5	5,	5,	5,	5,	5,	5,	5,	5,
	6	6,	6,	6,	6,	6,	6,	6,	6,
	7	7,	7,	7,	7,	7,	7,	7,	7,
	8	8,	8,		8,	8,	8,	8,	8,
	9	9,	9,	9,	9,	9,	9,	9,	9,
	10	10,	10,	10,	10,	10,	10,	10,	10,
	11	11,	11,	11,	11,	11,	11,	11,	11,
	12	12,	12,	12,	12,	12,	12,	12,	12,
	13	13,	13,	13,	13,	13,	13,	13,	13,
	14	14,	14,	14,	14,	14,	14,	14,	14,
	15	15,	15,	15,	15,	15,	15,	15,	15,

t(1

In this example, values in the LUT cause the DEB's output to take precedence over the VDC's output. The VDC's output is only displayed when you specify DEB palette position 0 in a graphics statement.

DEB Palette Positions

$\rm VDC$	
Color	
Values	$0\ 1\ 2\ 3\ 4\ 5\ 6\ 7$
	· · · · · · · · · · · · · · · · · · ·
0	0, 1, 2, 3, 4, 5, 6, 7,
1	1, 1, 2, 3, 4, 5, 6, 7,
2	2 , 1, 2, 3, 4, 5, 6, 7,
3	3 , 1, 2, 3, 4, 5, 6, 7,
4	4, 1, 2, 3, 4, 5, 6, 7,
5	5 , 1, 2, 3, 4, 5, 6, 7,
6	6, 1, 2, 3, 4, 5, 6, 7,
7	7 , 1, 2, 3, 4, 5, 6, 7,
8	8, 1, 2, 3, 4, 5, 6, 7,
9	9 , 1, 2, 3, 4, 5, 6, 7,
10	10, 1, 2, 3, 4, 5, 6, 7,
11	11, 1, 2, 3, 4, 5, 6, 7,
12	12, 1, 2, 3, 4, 5, 6, 7,
13	13, 1, 2, 3, 4, 5, 6, 7,
14	14, 1, 2, 3, 4, 5, 6, 7,
15	15, 1, 2, 3, 4, 5, 6, 7,
I	

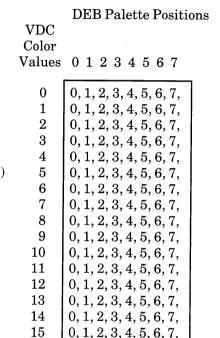
t(0)

VDC	DEB Palette Positions
Color	
Values	$0\ 1\ 2\ 3\ 4\ 5\ 6\ 7$
1	01004505
1	0 , 1, 2, 3, 4, 5, 6, 7,
1	0, 1, 2, 3, 4, 5, 6, 7,
2	2 , 1, 2, 3, 4, 5, 6, 7,
3	3 , 1, 2, 3, 4, 5, 6, 7,
4	4, 1, 2, 3, 4, 5, 6, 7,
5	5 , 1, 2, 3, 4, 5, 6, 7,
6	6 , 1, 2, 3, 4, 5, 6, 7,
7	7, 1, 2, 3, 4, 5, 6, 7,
8	8, 1, 2, 3, 4, 5, 6, 7,
9	9 , 1, 2, 3, 4, 5, 6, 7,
10	10 , 1, 2, 3, 4, 5, 6, 7,
11	11, 1, 2, 3, 4, 5, 6, 7,
12	12, 1, 2, 3, 4, 5, 6, 7,
13	13, 1, 2, 3, 4, 5, 6, 7,
14	14, 1, 2, 3, 4, 5, 6, 7,
15	15, 1, 2, 3, 4, 5, 6, 7,

t(1)

The following LUT entirely blocks out VDC output:

		DEB Palette Positions
	VDC	
	Color	
	Values	$0\ 1\ 2\ 3\ 4\ 5\ 6\ 7$
	0	0, 1, 2, 3, 4, 5, 6, 7,
	1	0, 1, 2, 3, 4, 5, 6, 7,
	$\frac{1}{2}$	0, 1, 2, 3, 4, 5, 6, 7,
	3	0, 1, 2, 3, 4, 5, 6, 7,
	4	0, 1, 2, 3, 4, 5, 6, 7,
t(0)	5	0, 1, 2, 3, 4, 5, 6, 7,
L(U)	5 6	0, 1, 2, 3, 4, 5, 6, 7, 0, 1, 2, 3, 4, 5, 6, 7, 0, 1, 2, 3, 4, 5, 6, 7, 0, 1, 2, 3, 4, 5, 6, 7, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0,
	•	
	7	0, 1, 2, 3, 4, 5, 6, 7,
	8	0, 1, 2, 3, 4, 5, 6, 7,
	9	[0, 1, 2, 3, 4, 5, 6, 7,]
	10	0, 1, 2, 3, 4, 5, 6, 7,
	11	0, 1, 2, 3, 4, 5, 6, 7,
	12	0, 1, 2, 3, 4, 5, 6, 7,
	13	0, 1, 2, 3, 4, 5, 6, 7,
	14	0, 1, 2, 3, 4, 5, 6, 7,
	15	0, 1, 2, 3, 4, 5, 6, 7,



t(1)

Introduction Once you have learned to program the LUT directly using the Set Color Palette command, you can make further use of the LUT's capabilities by programming the VDC and DEB video memory directly.

By directly programming the video memory of the VDC and DEB boards, you can increase the graphics display speed. The values you load into the video memory planes determine how the LUT is accessed. This section assumes that you have read and understood how to program the LUT directly.

In the 16-color graphics modes, the device driver combines the 3 bit planes of the DEB with one bit plane from the VDC to create the four bit planes necessary for 16-color graphics.

In the overlay modes, the device driver uses the 3 DEB bit planes for 8-color graphics output and uses the VDC board separately for either text or graphics output.

A0000:0	DEB Bitplane 0
A8000:0	DEB Bitplane 1
B000:0	DEB Bitplane 2
B8000:0	VDC Bitplane

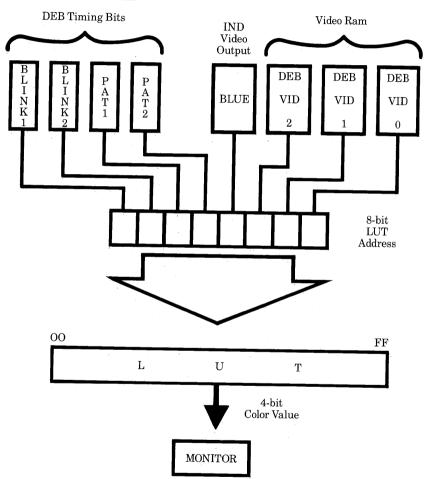
Memory Map

LUT Addressing	A LUT address is an 8-bit value that points to one of the 256 locations within the LUT. The method of address formation depends on the current video mode.
	For transparent and disabled modes, LUT address- ing is irrelevant. In the transparent mode, VDC color values bypass the LUT processing and go directly to the monitor output. In the disabled mode, all output from the LUT is forced to the value of zero.
	For the 16-color graphics and overlay modes, the LUT address is composed of bits from the DEB video bit planes, the VDC's video output, and DEB timing bits.
Timing Bits	The timing bits are called BLINK1, BLINK2, PAT1, and PAT2. BLINK1 and BLINK2 effect blinking; PAT1 and PAT2 effect patterning (dithering).
	All of the timing bits are applicable in the 16-color graphics mode; only BLINK1 is part of the address formation in the overlay mode. Therefore, you have fewer options for blinking and no ability to dither in the overlay mode.
	The operation of the timing bits is very fundamen- tal to creation of special effects. The bits always cycle on and off, each at a different rate. BLINK1 cycles on and off each 1/4 second. BLINK2 cycles on and off each 1/8 second.

PAT1 and PAT2 cycle on and off so fast that the eye cannot perceive a blink (PAT1 is the fastest). A dithered color is really 2-4 separate colors that are changing so rapidly that the eye perceives them as one solid color.

PAT1 changes value at the same rate that the monitor's cathode ray moves from one pixel to the next. PAT1's effect on LUT addressing is that it switches the address by 16 LUT entries — in the previous table, between pairs of rows. PAT2 changes value at the same rate that the cathode ray changes scanlines — in the previous table, between one pair of rows and the next pair of rows.

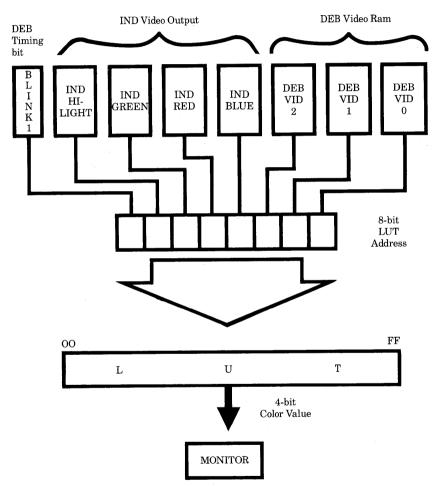
PAT2	PAT1	Portion of LUT
0	0	1st 16 entries of each quarter
0	1	2nd 16 entries of each quarter
1	0	3rd 16 entries of each quarter
1	1	4th 16 entries of each quarter



To output a color to the monitor, the DEB concatenates the DEB timing bits BLINK1, BLINK2, PAT1, PAT2, the BLUE output bit from the VDC, and a bit from corresponding locations on each of the three DEB bit planes.

1. 16-color Graphics Mode

2. Overlay Mode

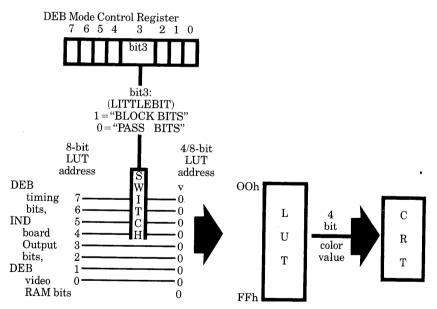


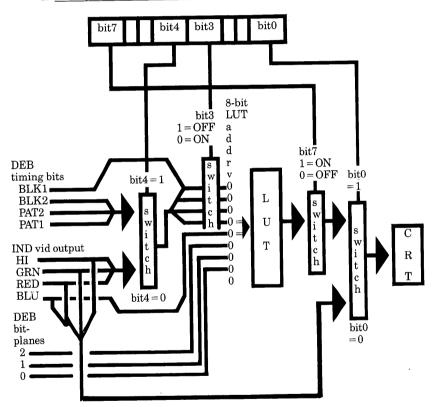
To output a color to the monitor, the DEB concatenates the following bits: BLINK1, the HILIGHT, GREEN, RED, and BLUE output bits from the VDC, and a bit from corresponding locations on each of the three DEB bit planes.

Short LUT Addresses

The DEB supports a method for you to access only the first sixteen LUT locations. This lets you use normal 16-color graphics without needing to manage all of the 256 LUT locations. You invoke this short addressing mode by a setting bit 2 in AL in the "Set Color Palette" command.

3. Short LUT Addresses





4. Modes, Address Formation, & DEB Mode Control Register